

X-point radiation and detachment control at ASDEX Upgrade

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See author lists of ⁶B. Labit et al 2019 Nucl. Fusion 59 086020 and ⁷H. Meyer et al 2019 Nucl. Fusion 59 112014

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 **EUROfusion**



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1. The X-point radiation regime

2. Real-time control of the radiator position

- An ELM-mitigated scenario

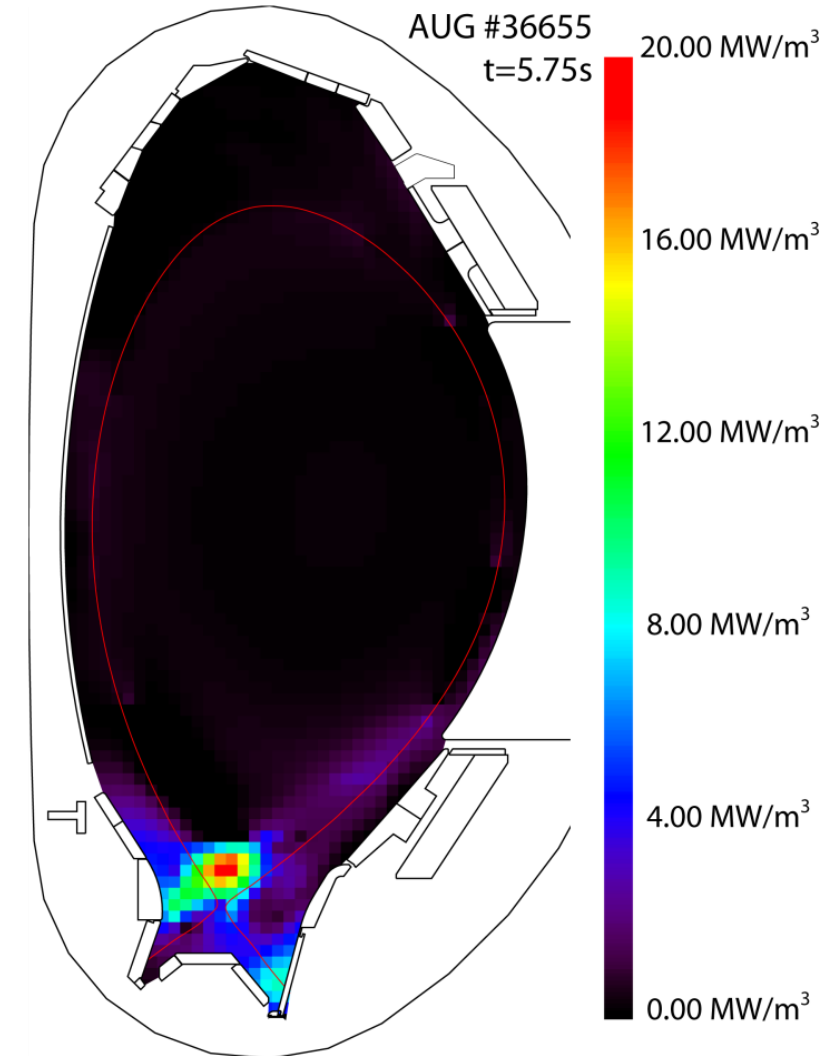
3. Other Control at AUG, TCV & DIII-D

4. Feasibility for future reactors?

5. Summary

The X-point radiation regime

- Detachment in metal machines achieved with seeding
- With the pronounced detachment of the outer divertor, an intense, localized radiator evolves close to the X-point.
- Most likely radiation condensation (MARFE-like)
- Radiated power fraction close to 100%

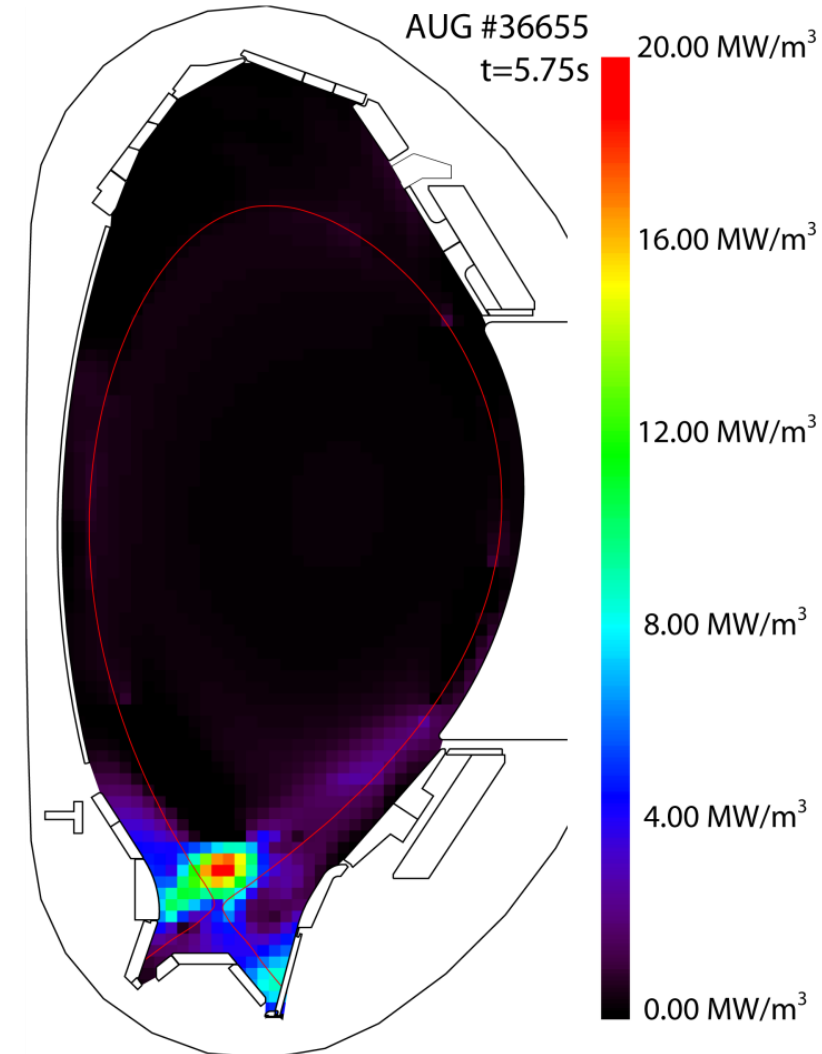


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-
- X-point radiation is:
 - ➔ Stable scenario
 - ➔ Existing with N or Ar seeding
 - ➔ Radiates up to 1/3 of the heating power
 - ➔ Existing in a wide range of heating power:

$$P_{\text{heat}} [\text{MW}] = 2.5 - 20$$

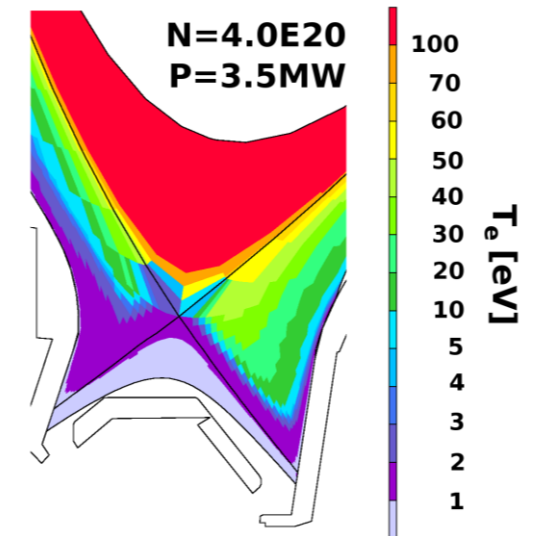
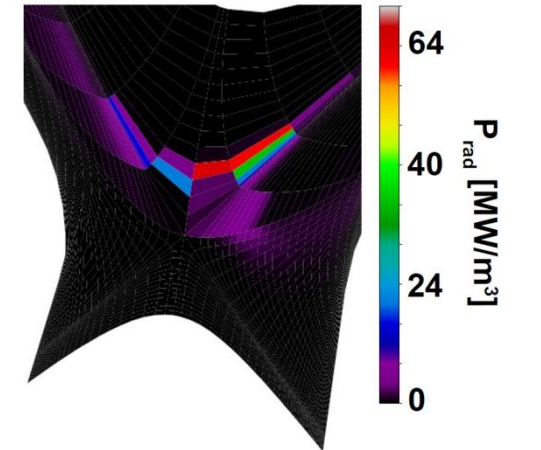
$$P_{\text{heat}}/P_{\text{LH}} = 1 - 5$$



The X-point radiation regime

- Radiator reproduced by SOLPS [Reimold, NF 2015]
- Temperature reduction within confined region
 - $T_e < 5\text{eV}$
 - D line radiation observed
 - Parallel temperature gradients inside confined region!

[F.Reimold, PSI 2014]



The X-point radiation regime

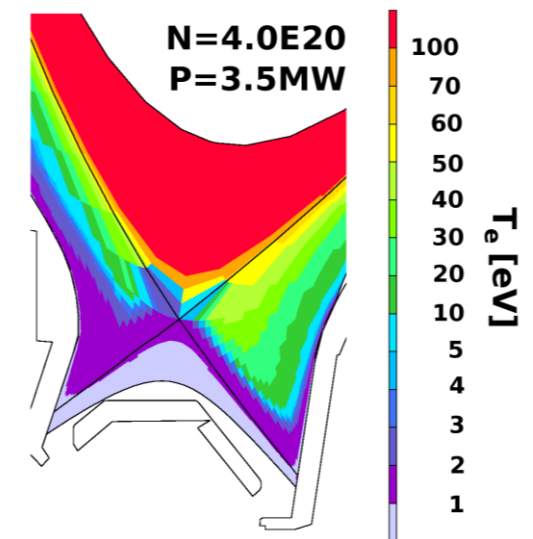
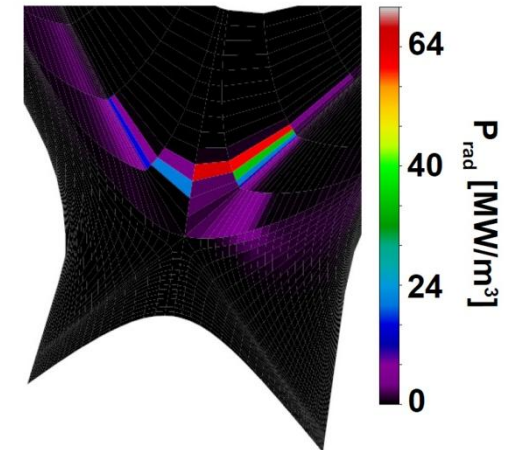
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Why is it stable here?

- Highest flux expansion \leftrightarrow longest connection length to midplane
 - Low, sustainable parallel temperature gradients
 - Power flux driven parallel to magn. field
 - Radiator acts as heat sink

Moves inside confined region with higher impurity concentration

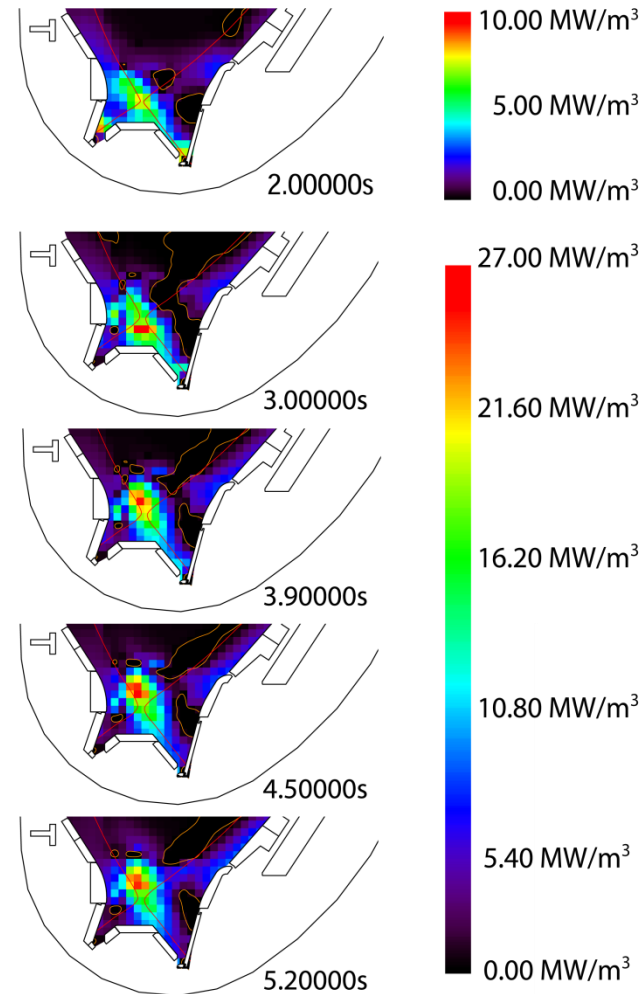
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Movement of the X-Point radiation peak

Tomographic reconstruction of X-point radiation movement (#30506, N seeding)

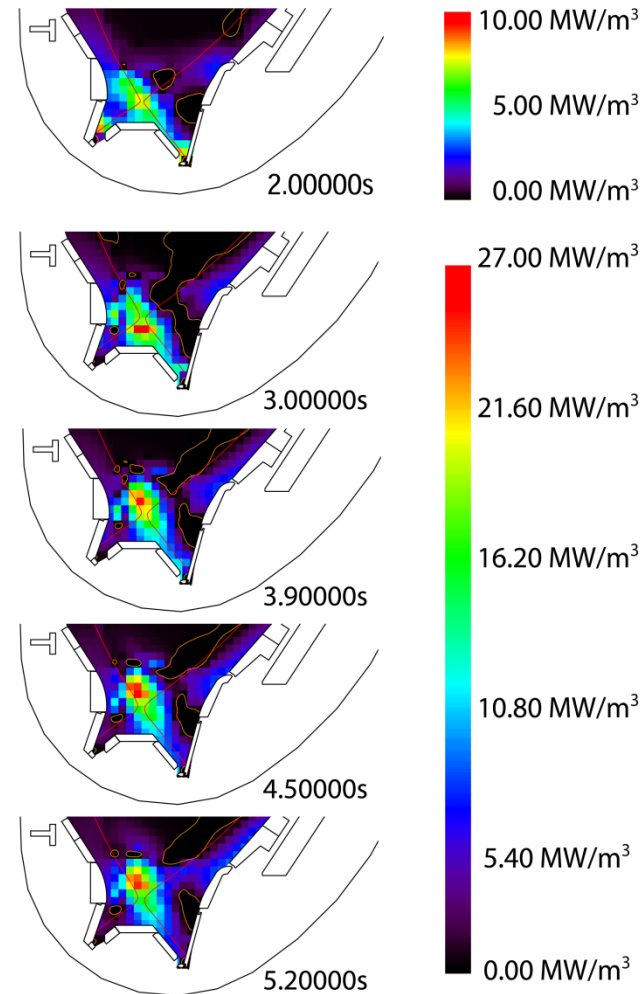
- Radiator forms close to X-point
- Moves further inside
- Up to 15cm inside confined region ($q_{pol} \approx 0.99$) observed



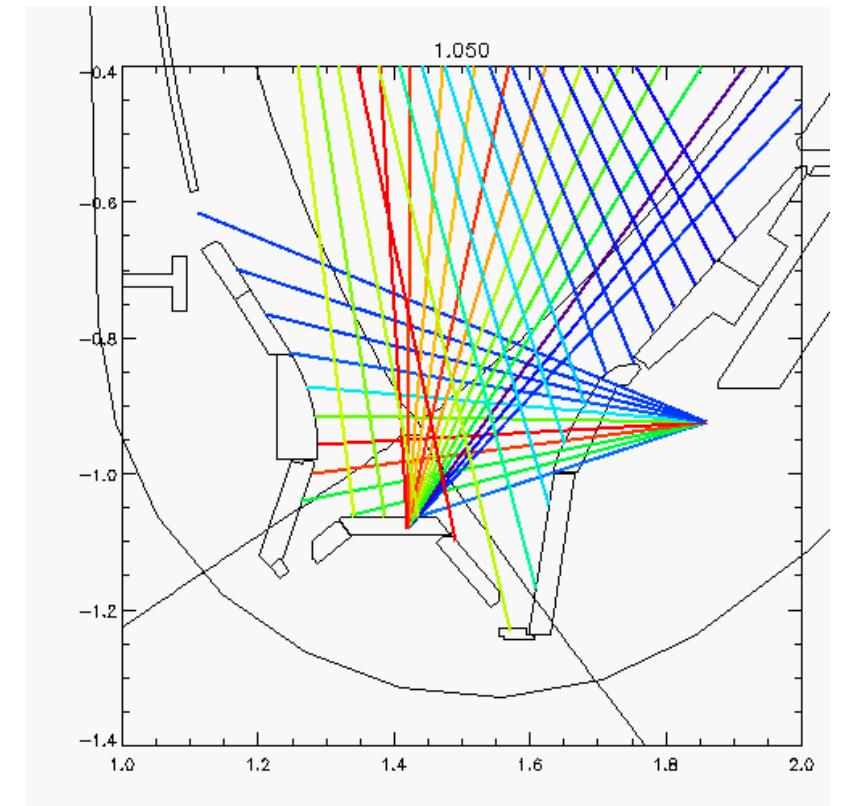
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Tracking using AXUV diodes (#32273, N seeding)



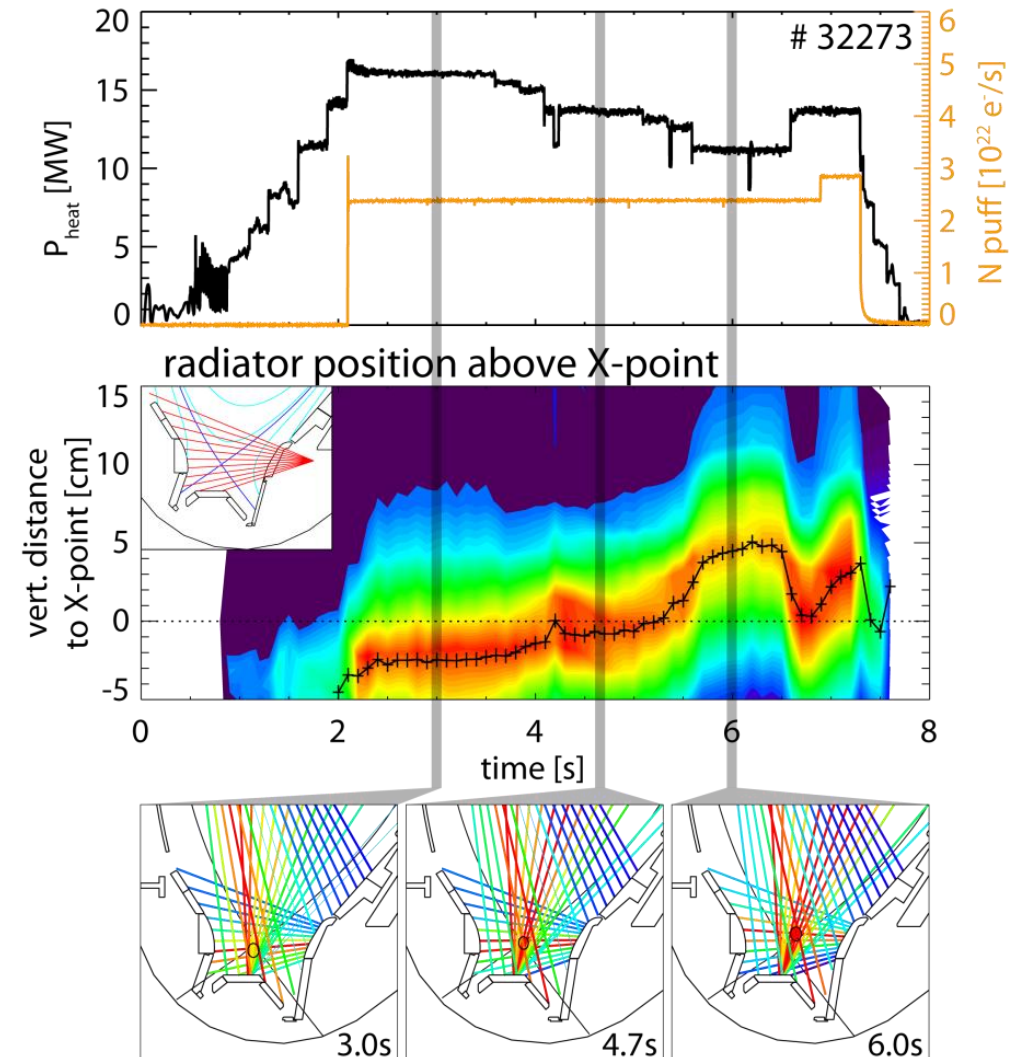
Actively influencing the location

- Location can be influenced by heating power or nitrogen seeding level →

Implemented real time control

Sensor: AXUV diodes

- SIO2 real time data acquisition
- 20ms median filtered data → ELM filter



Actively influencing the location

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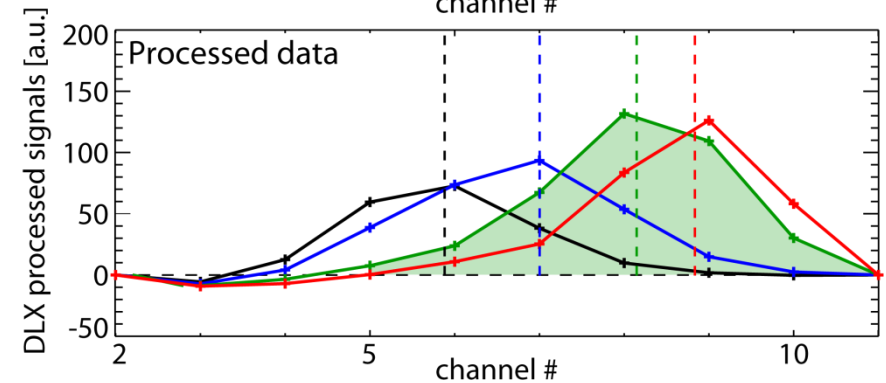
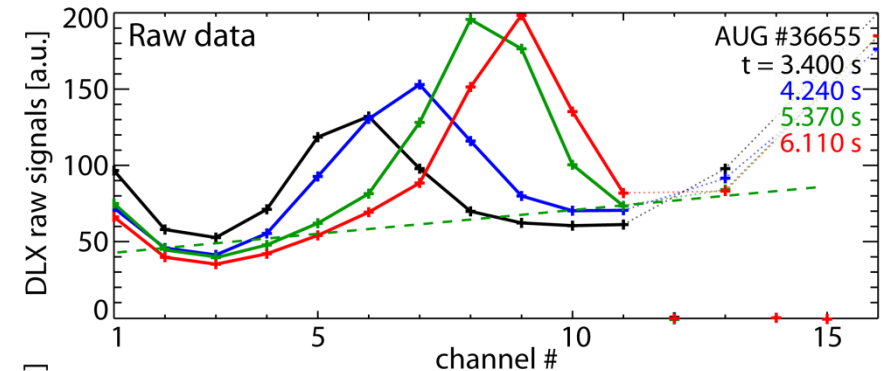
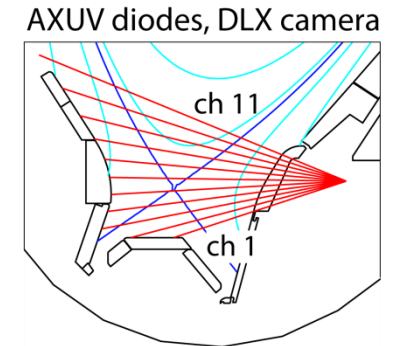
Implemented real time control

Sensor: AXUV diodes

- SIO2 real time data acquisition
- 20ms median filtered data → ELM filter
- Peak detection by calculation of 1st moment →

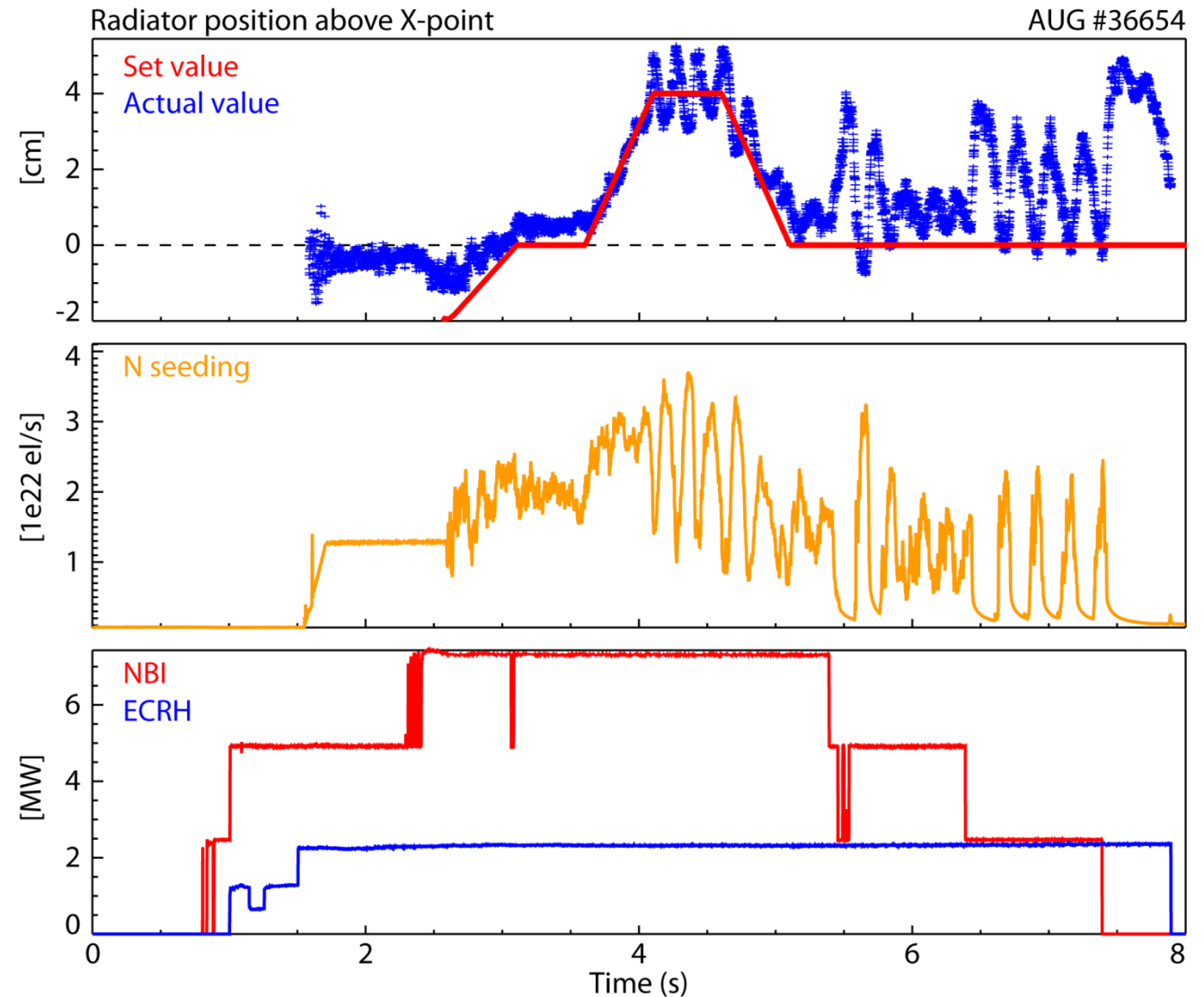
Actuator: N seeding

- PI controller
- Further possibilities: Ar seeding, Heating power



First application: Location & heating variation

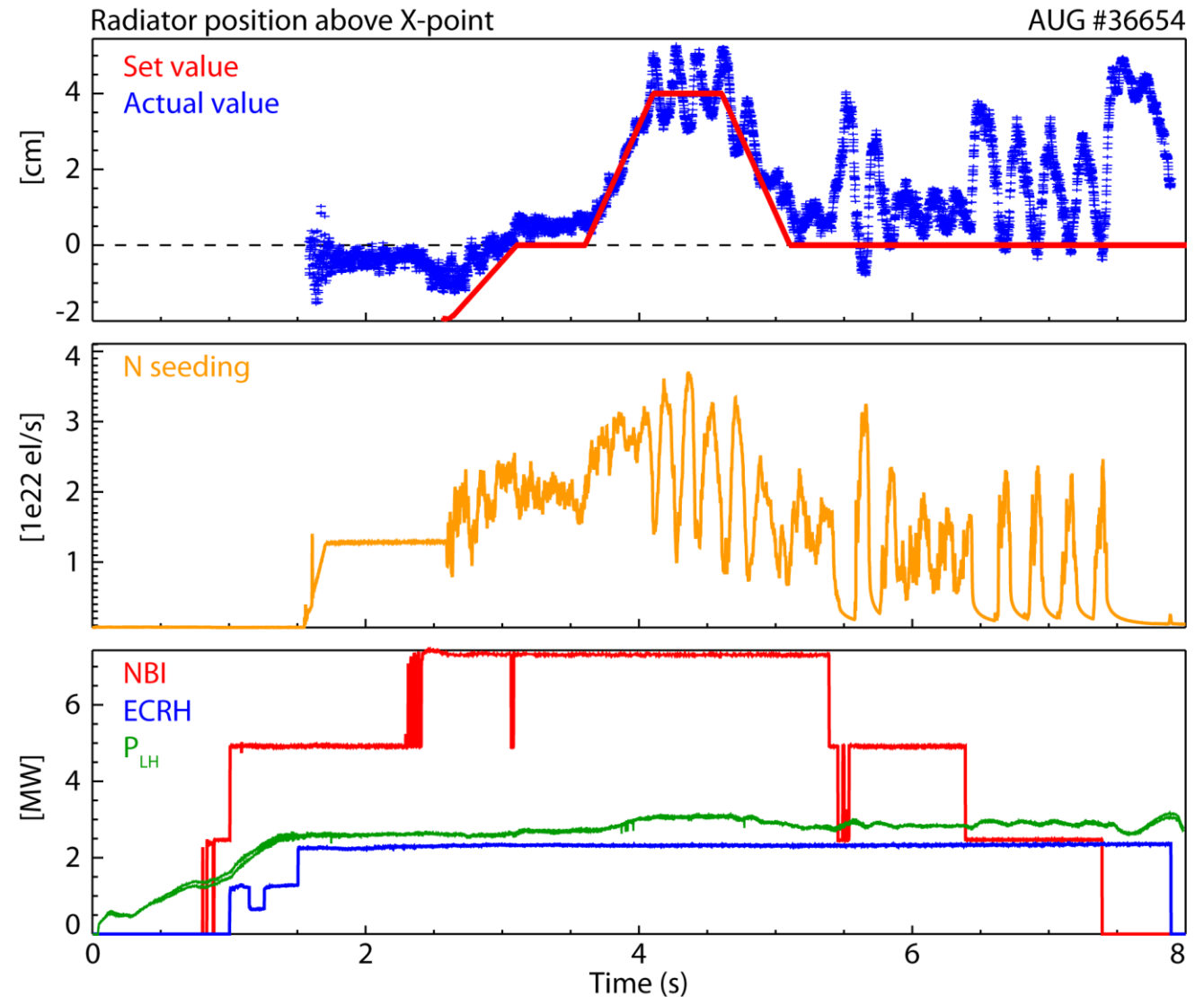
- Detection within 5mm
- Power steps well compensated
- Controller unstable at:
 - Location around 4cm
 - Low heating power
 - Optimisation necessary
- Oscillation period (150-250ms) in time scale of seeding reaction time (~50ms)



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- Detection within 5mm
- Power steps well compensated
- Controller unstable at:
 - Location around 4cm
 - Low heating power→ Optimisation necessary
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**Scenario (in ELMy H-mode)
stable for $P_{\text{heat}} = 2.5\text{MW} \approx P_{\text{LH}}$**

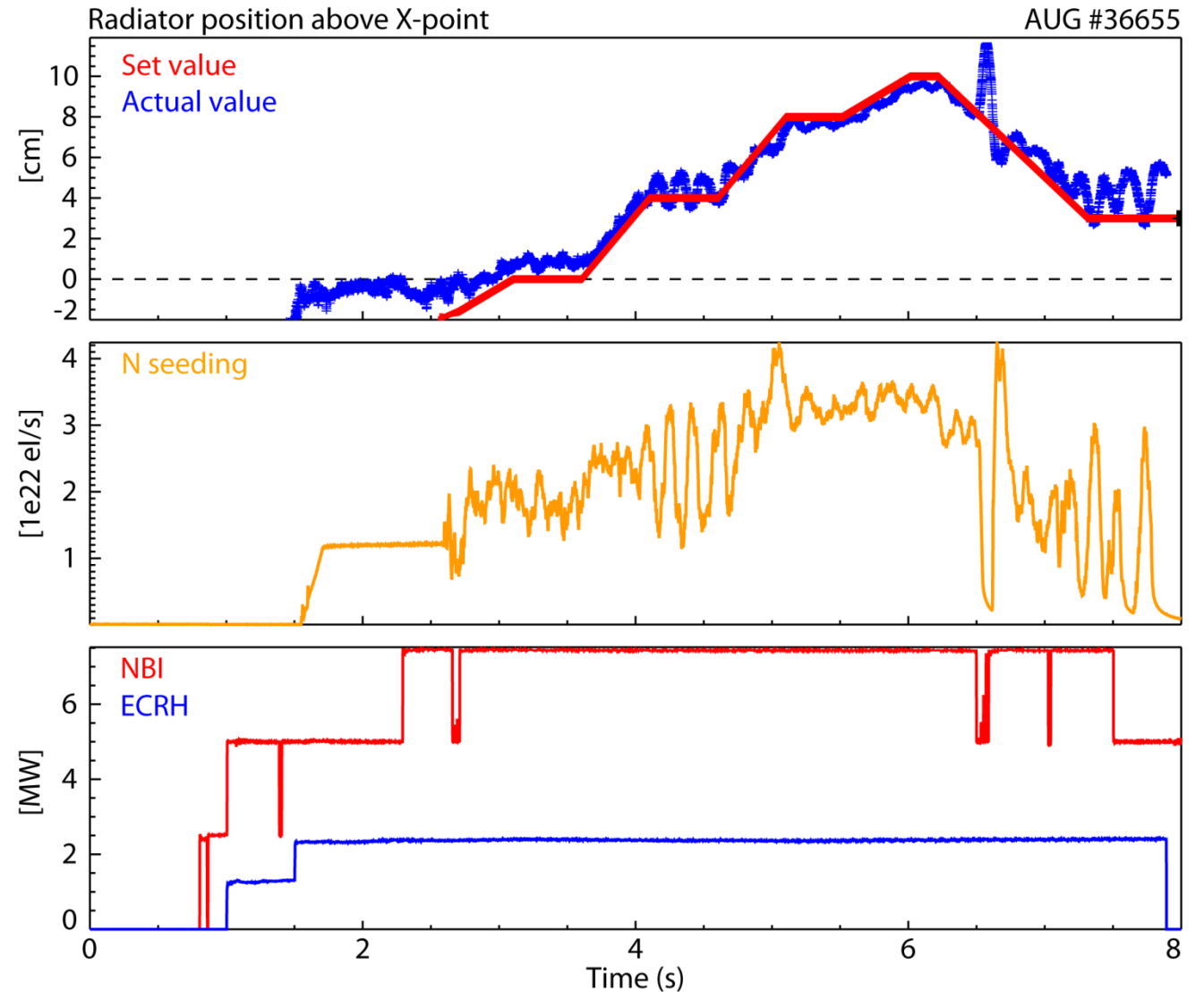


First application: Deep penetration

- Control up to 10cm above X-point (and higher)
- Power trips also far inside well compensated

→ stable!

- Oscillations only around 4-6cm

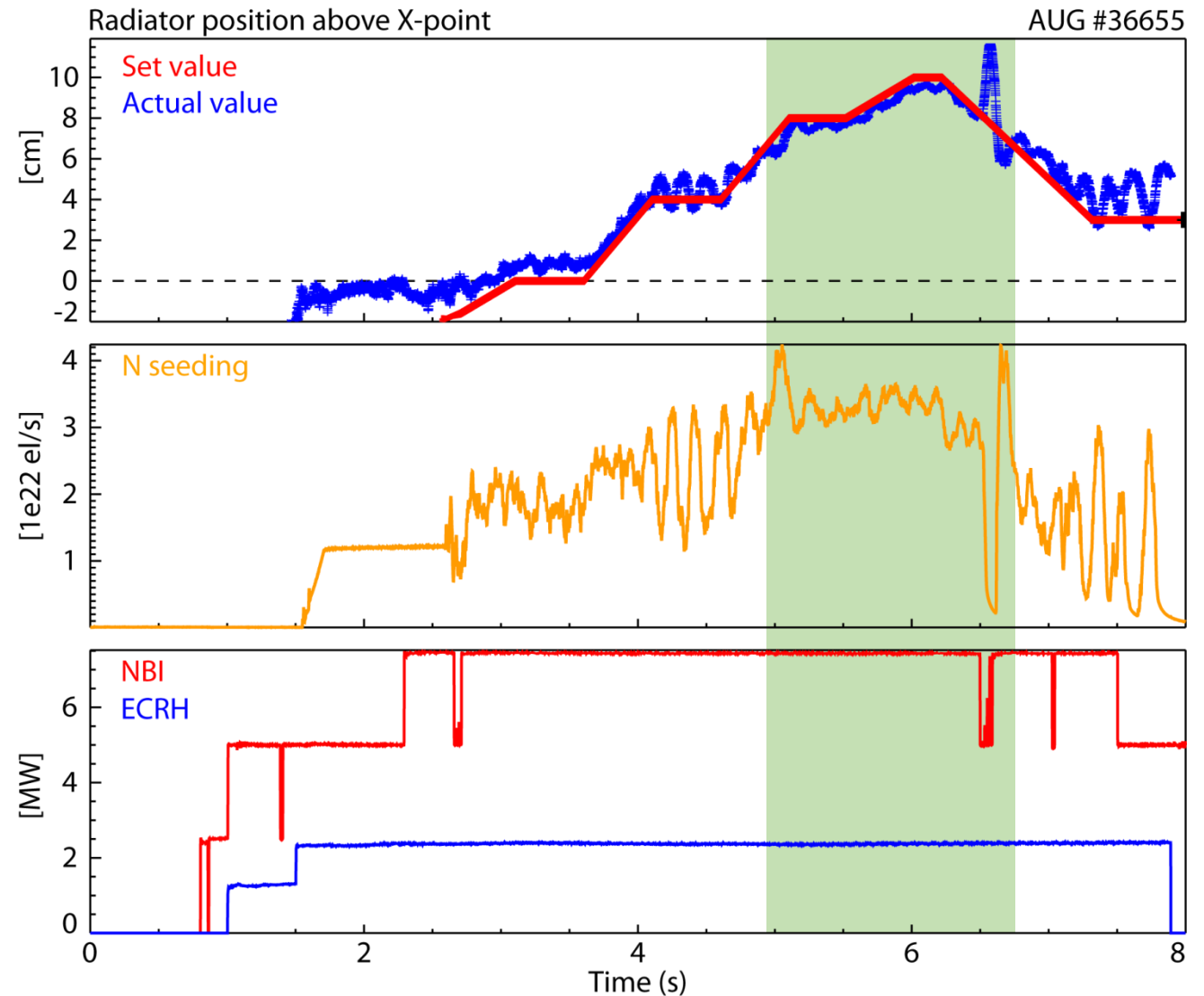


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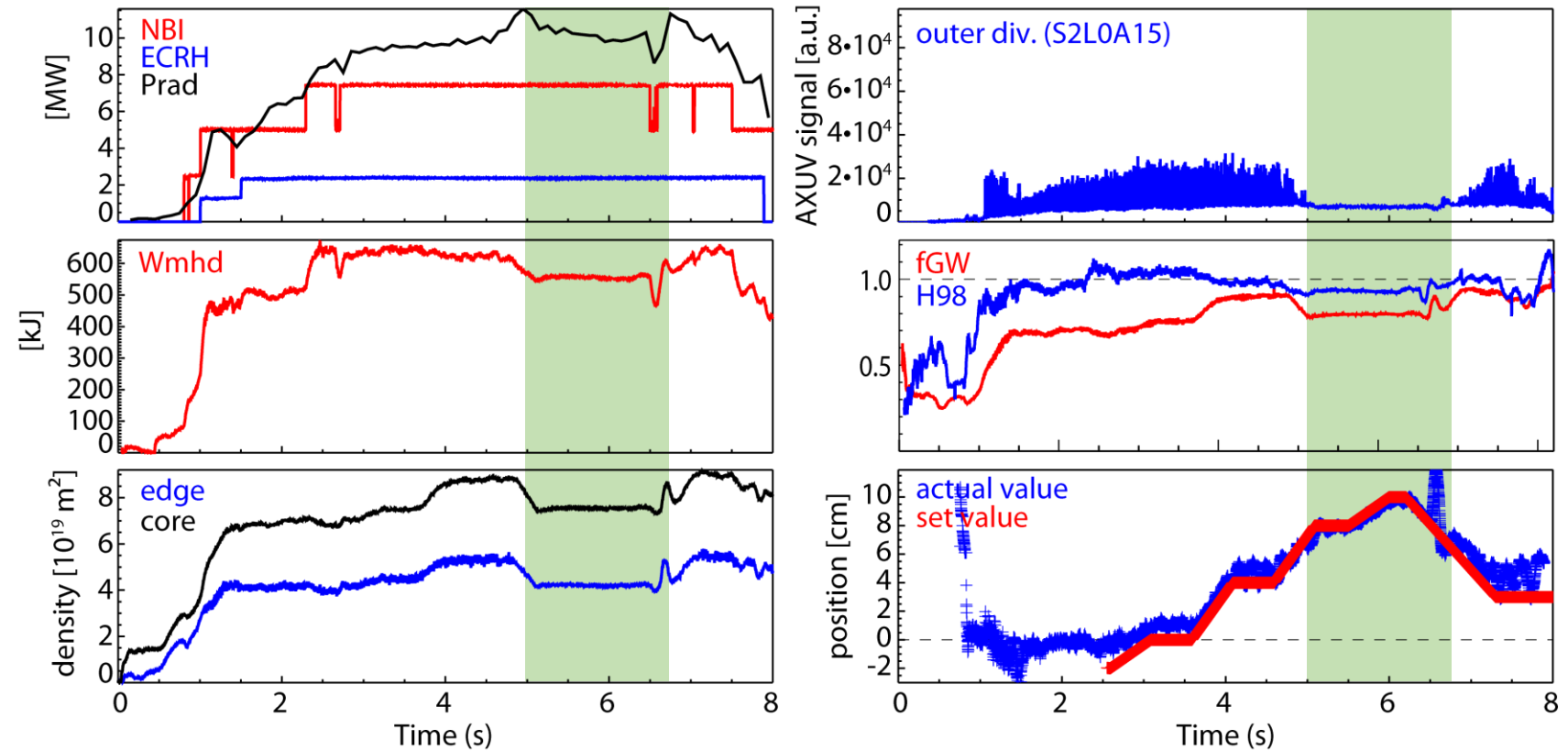
→ stable!

- Oscillations only around 4-6cm
- ELMs disappear for location higher than 7cm
 - reappear for lower locations



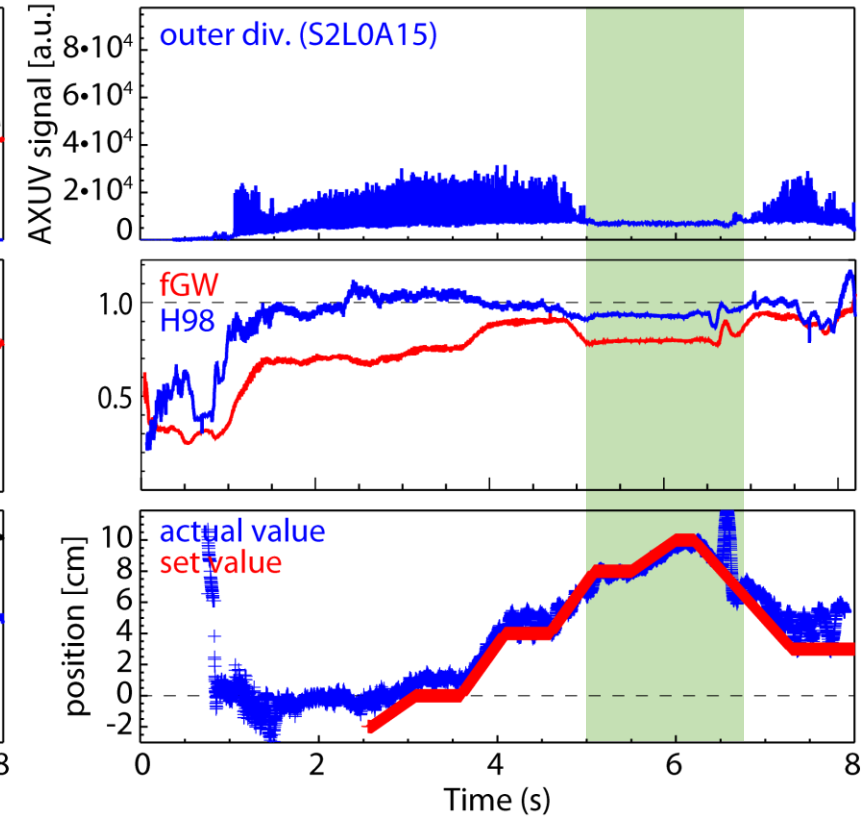
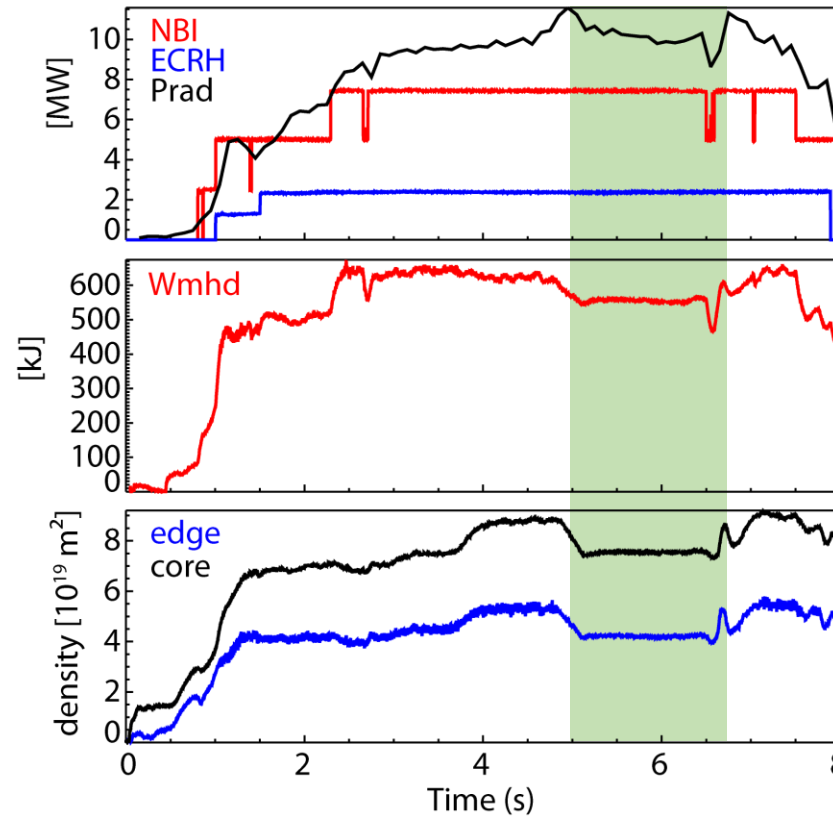
An ELM-free regime?

- Reproducible in other shots
e.g. [Reimold, NF 2015]
- Though without control
less stable



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- Sudden change of characteristics:
 - No clear ELM signature
→ ELM mitigated
 - Density reduced by 15%
 - W_{MHD} reduced by ~10%

- Characteristics between L- & H-mode (E_r well, filament characteristics)
- Increased divertor compression
- Reduced W content

How is the pedestal affected?

Attached → partially detached:

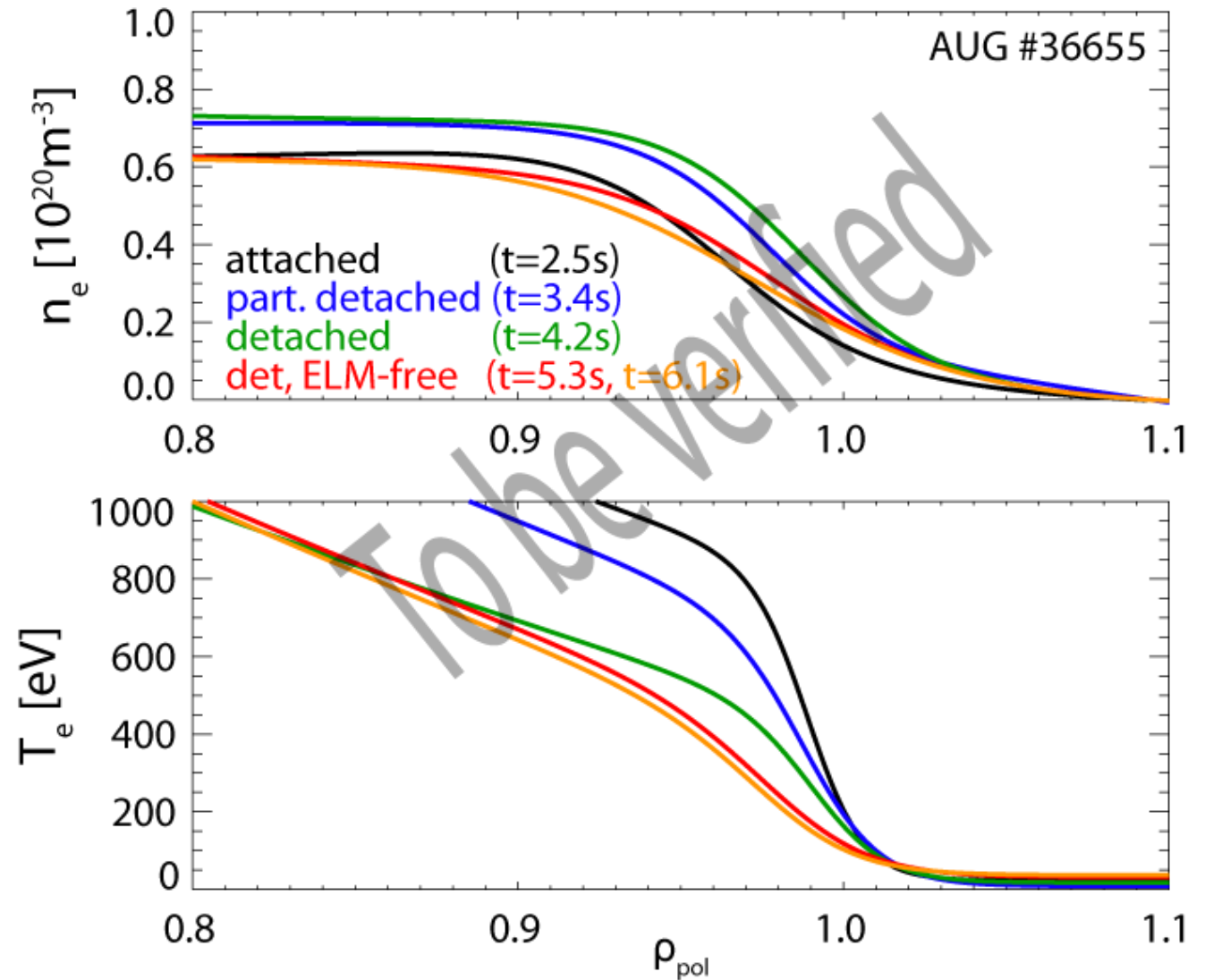
- Temperature ↓
- Density ↑

Partially detached → detached:

- Temperature ↓
- Density ↑

Detached → ELM-free:

- Density ↓
- Temperature gradient ↓
→ Temperature recovered further inwards



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Partially detached → detached:

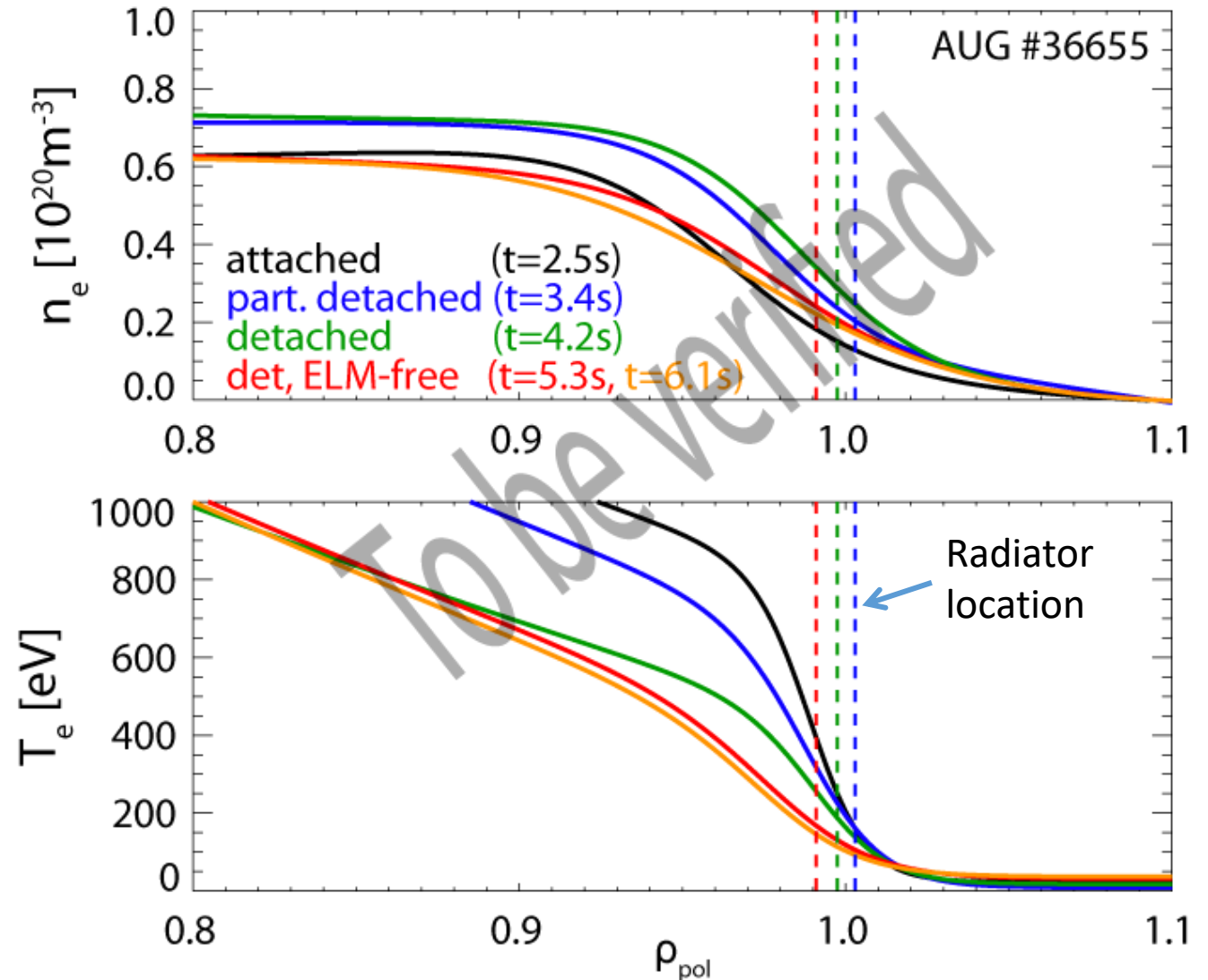
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- Temperature gradient ↓
→ Temperature recovered further inwards

All changed further inside than radiator

→ Pedestal stability is affected



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- Density ↑

Parti

- $H_{98} \approx 0.95$
- $f_{GW} \approx 0.8$

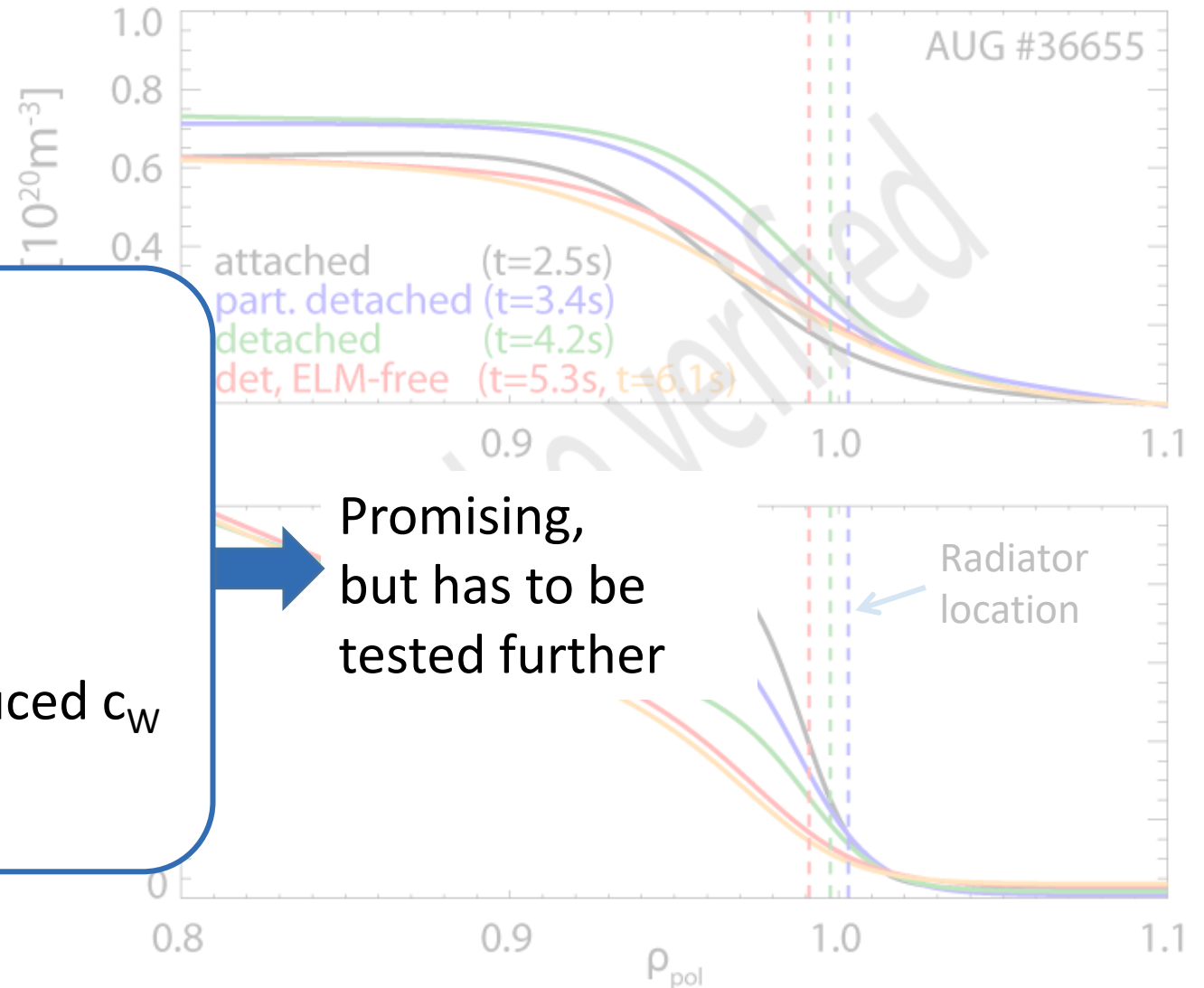
Det

- Full detachment
- ELM mitigated
- Increased compression & reduced c_w
- $c_{N,core} \approx 2-2.5\%$

All ch

radiator

→ Pedestal stability is affected



Comparison to existing detachment control



Detachment control...

... exists at:

- AUG
- DIII-D
- TCV
- JET
- EAST
- C-Mod

... sensors are:

- Divertor Thomson Scattering
- Shunt currents
- Bolometry
- Langmuir probes
- Thermocouples
- Filt. Cameras

... controls with:

- N seeding
- Ar seeding
- D fuelling

... controlled state:

- L-mode
- H-mode
- **onset of detachment**
- **partial detachment**

Where does the new control set in?

Detachment control...

... exists at:

- **AUG**
- DIII-D
- TCV
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X-point radiator control allows for:

- Control of full detachment
- Buffer between re-attachment and radiative collapse

- X-Point radiating regime promising candidate for heat exhaust
 - Stable & controllable
 - Large buffer
 - Good performance
 - ELM mitigated

 - Different paths of detachment control exist
 - X-Point radiator control first to control full detachment
 - Offers operational buffer between re-attachment and radiative collapse
- Applicable for detachment control in reactors