



Assembly Technologies of the Superconducting Tokamak on JT-60SA

FIP/4-1Ra

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JT-60SA TF Coil Manufacture, Test and Preassembly by CEA

FIP/4-1Rb

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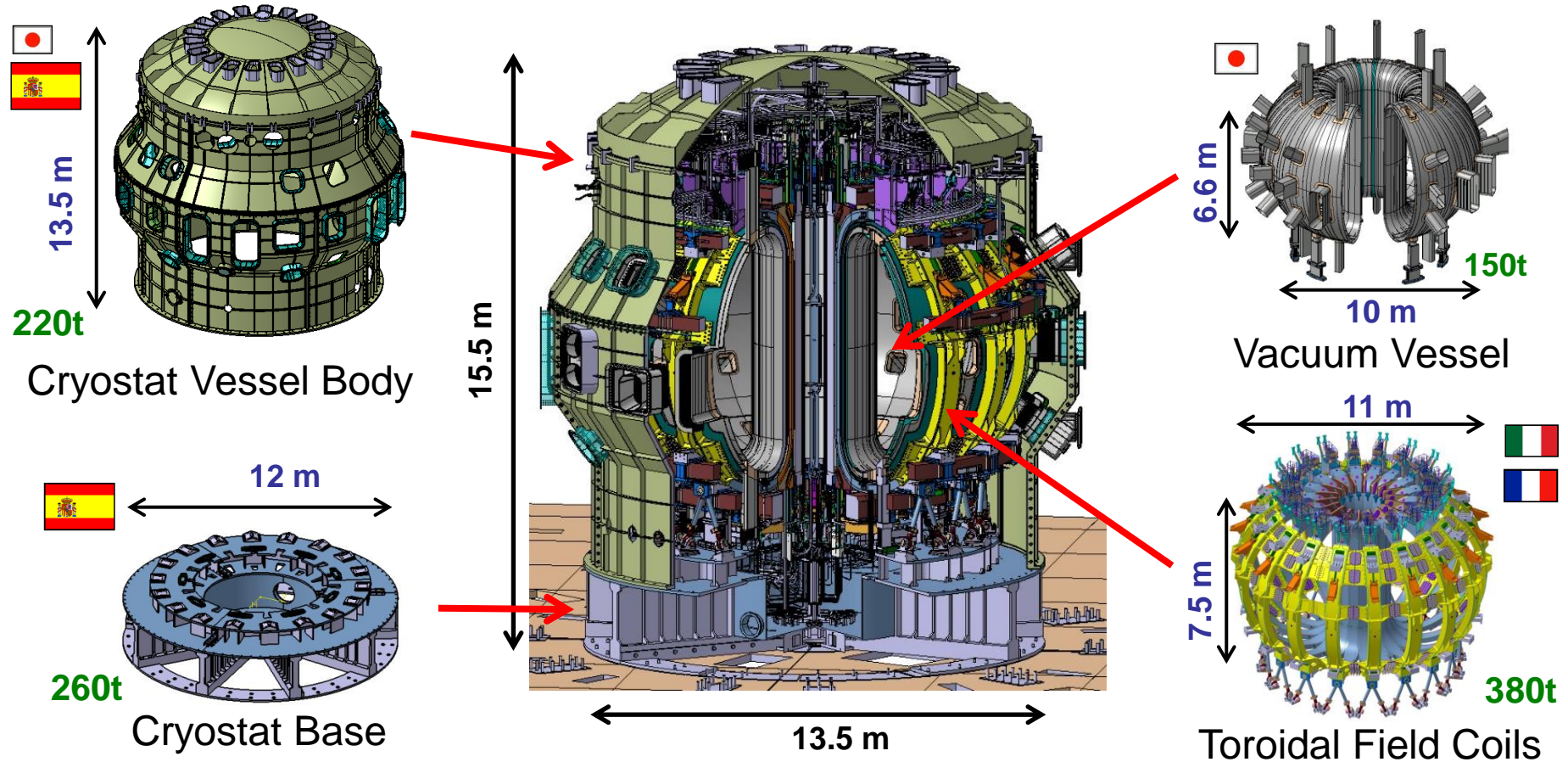
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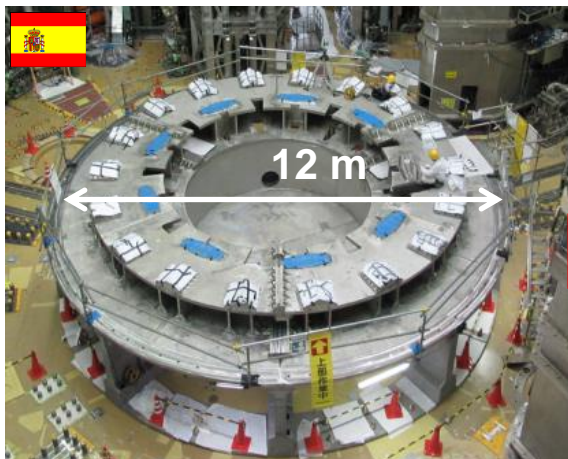
1. Introduction of JT-60SA Construction
2. Assembly Technology
3. Application to Onsite & Sector Assembly of VV
4. Manufacturing of TF Coil
5. Summary



JT-60SA is fully superconducting machine.

- Size of JT-60SA is about half of ITER.
- The total weight is over 2600 tons.
- Structure is so complicated that a tight tolerance is required.

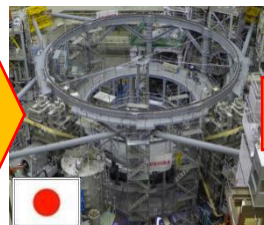
Started in Jan. 2013



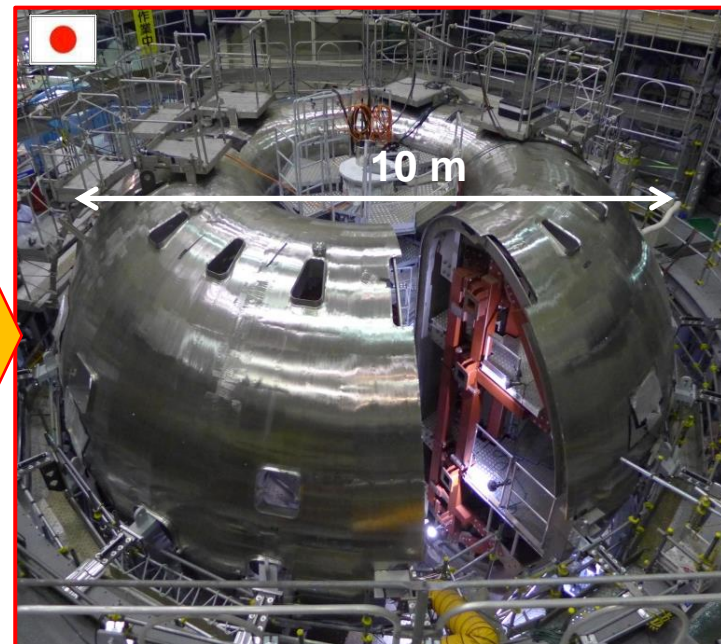
Cryostat Base
(280 tons)



Lower EF Coils
(100 tons)



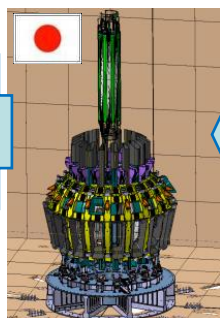
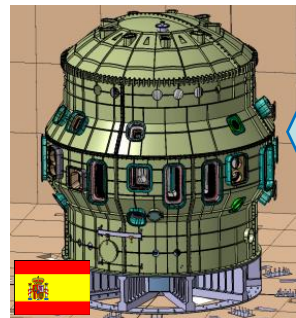
Assembly Frame



Vacuum Vessel 340° Sector
(Oct. 2015)

We are here!

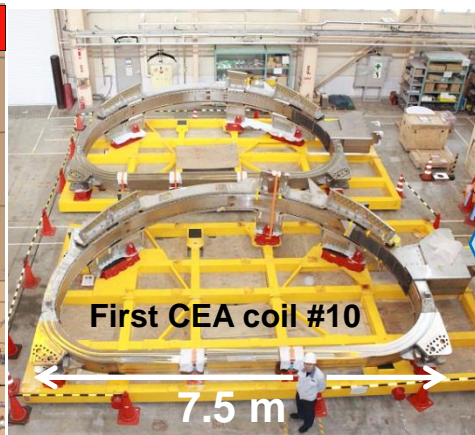
First Plasma in 2019



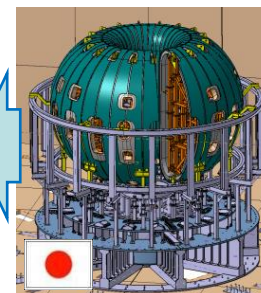
PF Coils
(185 tons)



TF Coil (370 tons)



First CEA coil #10



VV Thermal Shield
(28 tons)



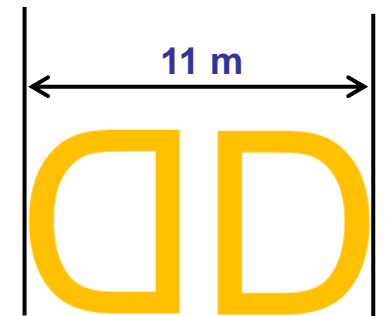
There are two major issues in manufacturing and assembling the components of JT-60SA, whose size and weight are over 10 m and 2600 tons.

1. Tight tolerances of manufacturing & assembly

- Reduce the magnetic field error (below $10^{-4} B_{\text{tor}}$)
- Keep proper gaps between components

> **Tolerance is about 0.01% of the scales of 10 m size components, namely, less than 10 millimeter.**

Schematic of TF Coil



Tolerance: 2mm

2. Smooth assembly without backward process



Development of assembly technology with an efficient assembly process.

To realize the tolerance & smooth assembly, assembly process was developed.

Careful assessment by three-dimensional CAD

- Development of assembly flow
- Control of gap between components.
- Design of special jigs for shape control and onsite transportation.

Metrology for positioning with high accuracy

- Lines of sight of the laser light are acquired to measure the position in torus hall.
 - Many reference points (~ 80) are sets to recognize the position of laser tracker.
- > Spatial resolution of measurement is less than 0.5 mm.

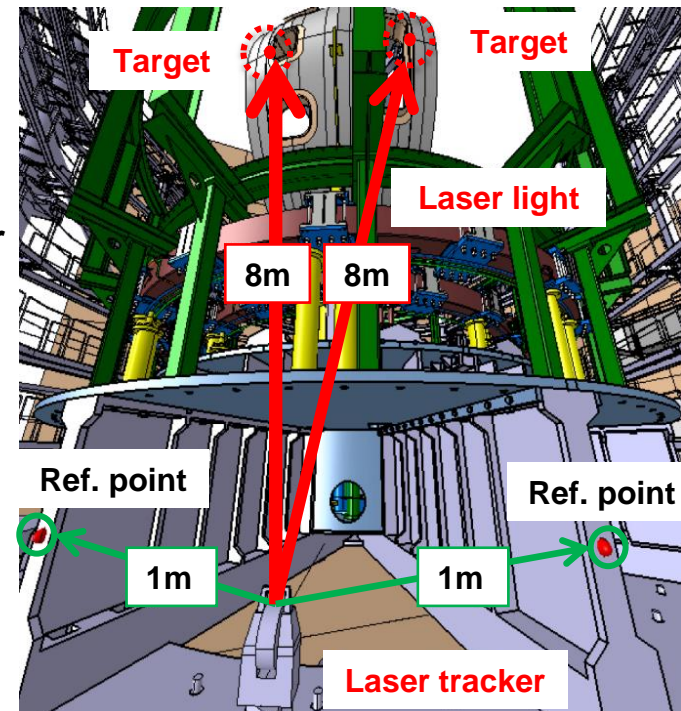
Setting of the sector of vacuum vessel



Target Reflector

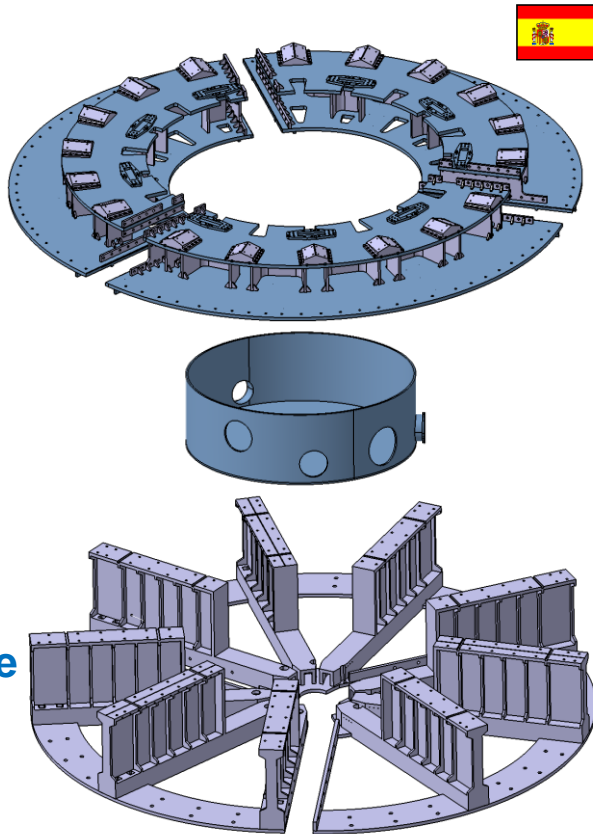


Laser Tracker



**Cryostat Base (CB) is 260 tons and 12 m of diameter.
Seven parts are manufactured in factory and assembled onsite.**

Parts of CB



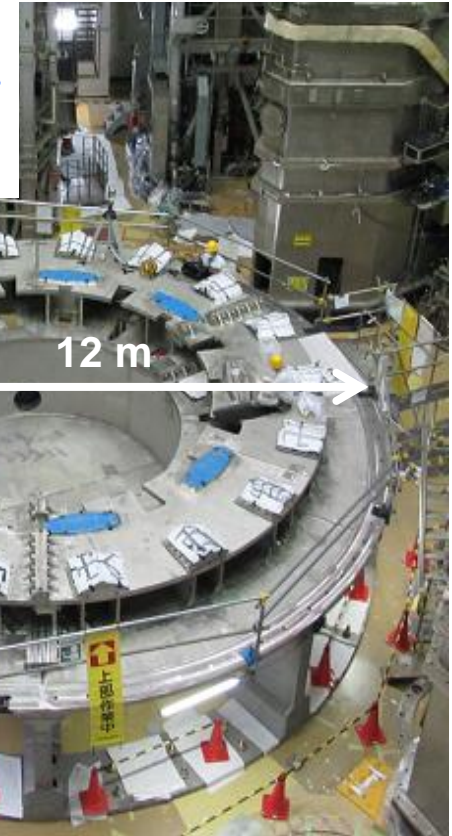
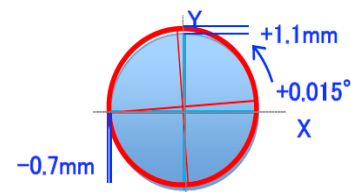
Double Ring
(three pieces)

Inner Cylinder
(one piece)

Lower Structure
(three pieces)



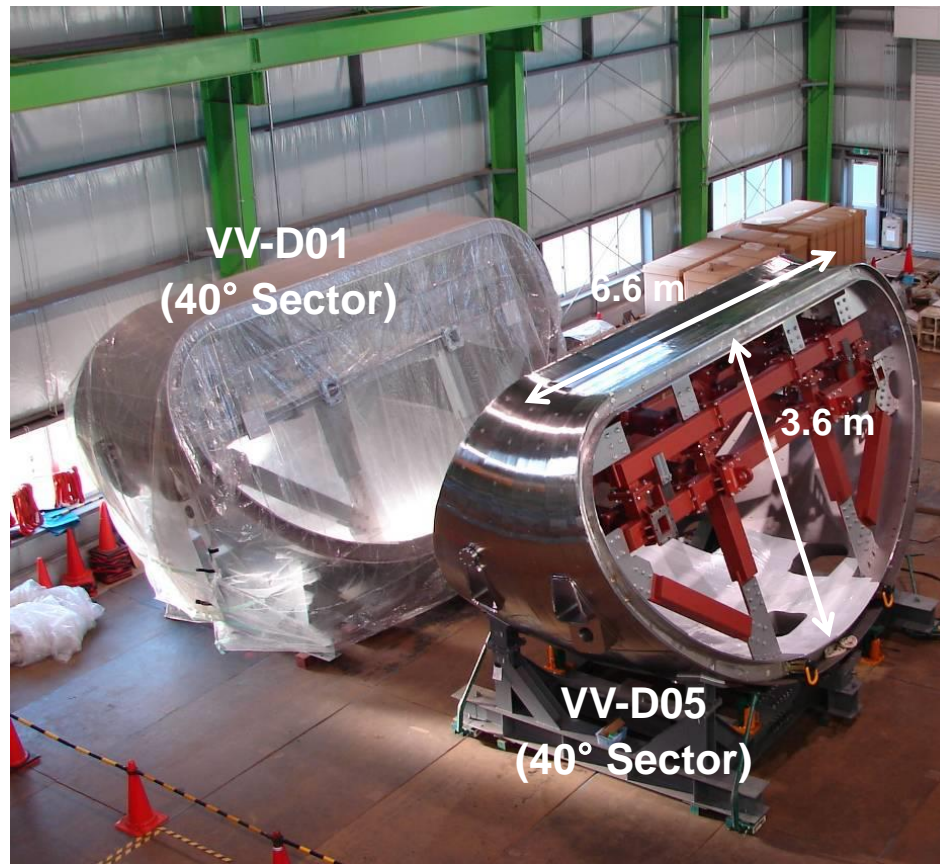
Assembly by laser metrology



**Manufacturing accuracy:
1 mm within tolerance.**

**Assembly accuracy:
~2 mm of allowable level.**

Ten sectors of vacuum Vessel (VV) were manufactured in factory and assembled onsite.

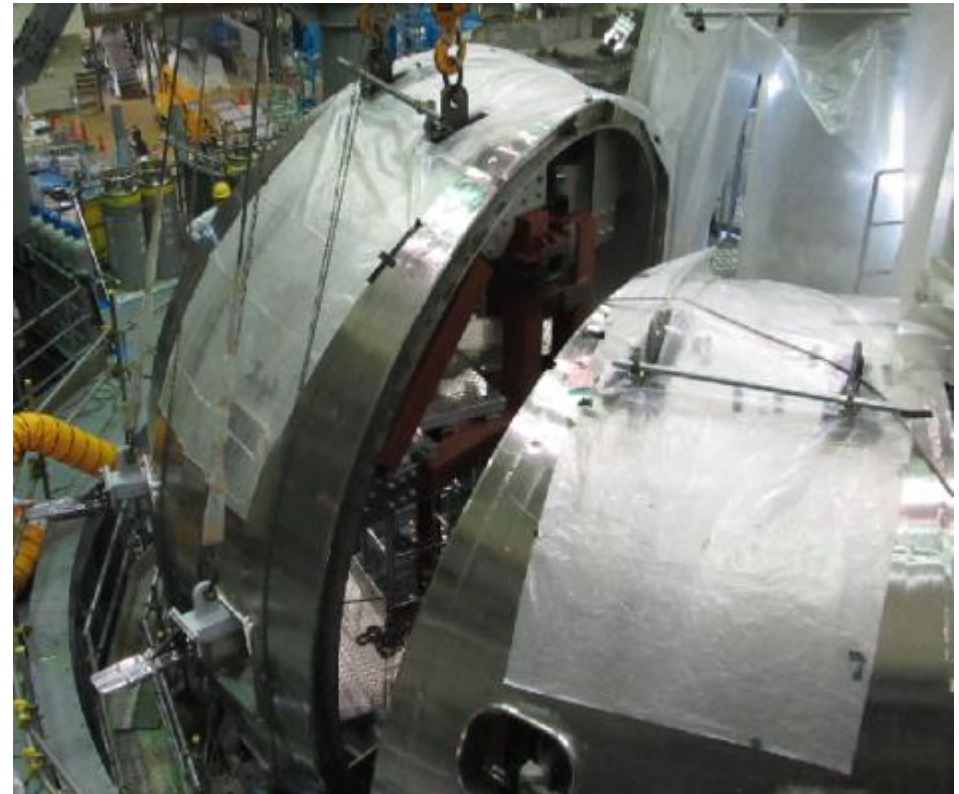
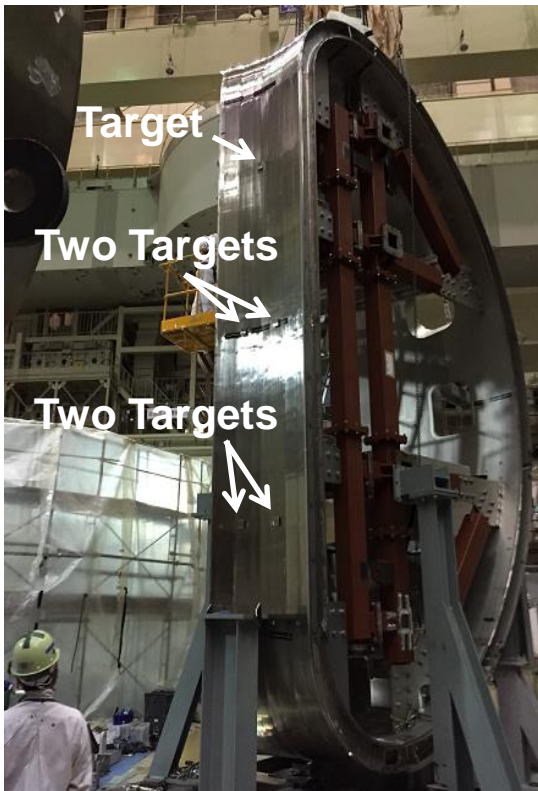


Manufacturing accuracy : ± 2 mm at inboard (IB) and ± 5 mm at outboard (OB)
within tolerances of ± 10 mm at IB and ± 20 mm at OB

Prior to assembly of sector, target points for laser measurement were equipped on each sector, and then carefully set on CB with adjusting the alignment.

5 target points on IB
for the position and
orientation

Pre-set on cryostat base for alignment
while shrinkage of **4mm / weld line** is
taken into account.



To avoid the accumulation of welding deformation through sequential joint of sectors, **two types of welding joint are applied.**

Direct welding

Welding

Weld Line

Weld Constraint

One welding line
Toroidal shrinkage of 4 mm.

40°+40°

40°+40°

40°+40°

Welding via splice plate

Welding

Welding

Splice plate

Weld Constraint

Splice Plate

Weld Line

Two welding lines
Toroidal shrinkage of 8 mm.

80°+40°

80°+30°

Added 40° sector

Added 30° sector

Added 30° sector

80°+30°

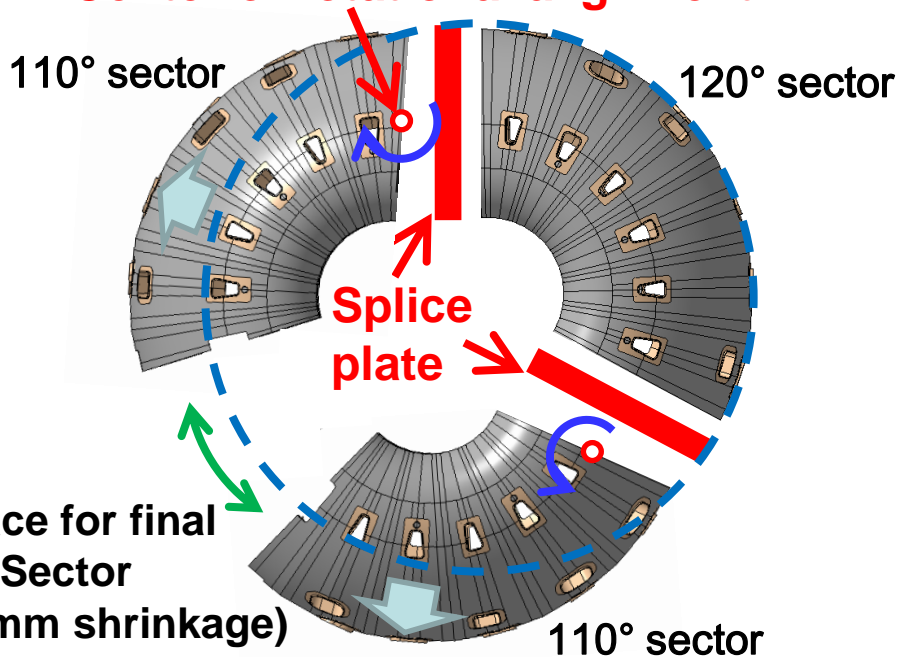
Three large sectors were mutually jointed by welding via splice plates.

The sequence is as follows:

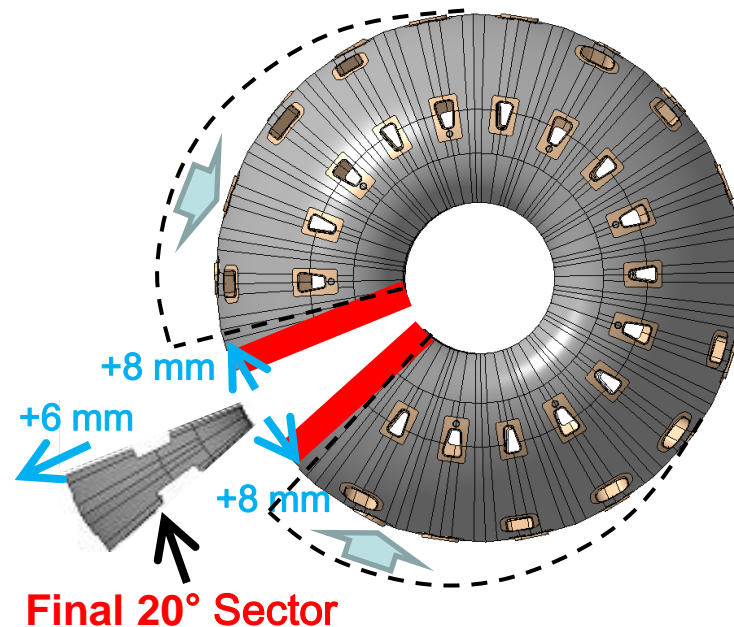
- 120° sector as center is fixed and then welded with two 110° sectors.
- 110° sectors were outwardly set by taking into account of 8 mm toroidal shrinkage due to the final sector welding.
- Final sector will be set back by 6 mm in the radial position.
- **Outward off-alignment of 8mm will be compensated by welding shrinkage of the final sector.**

Set of two 110° sectors

Center of rotational alignment

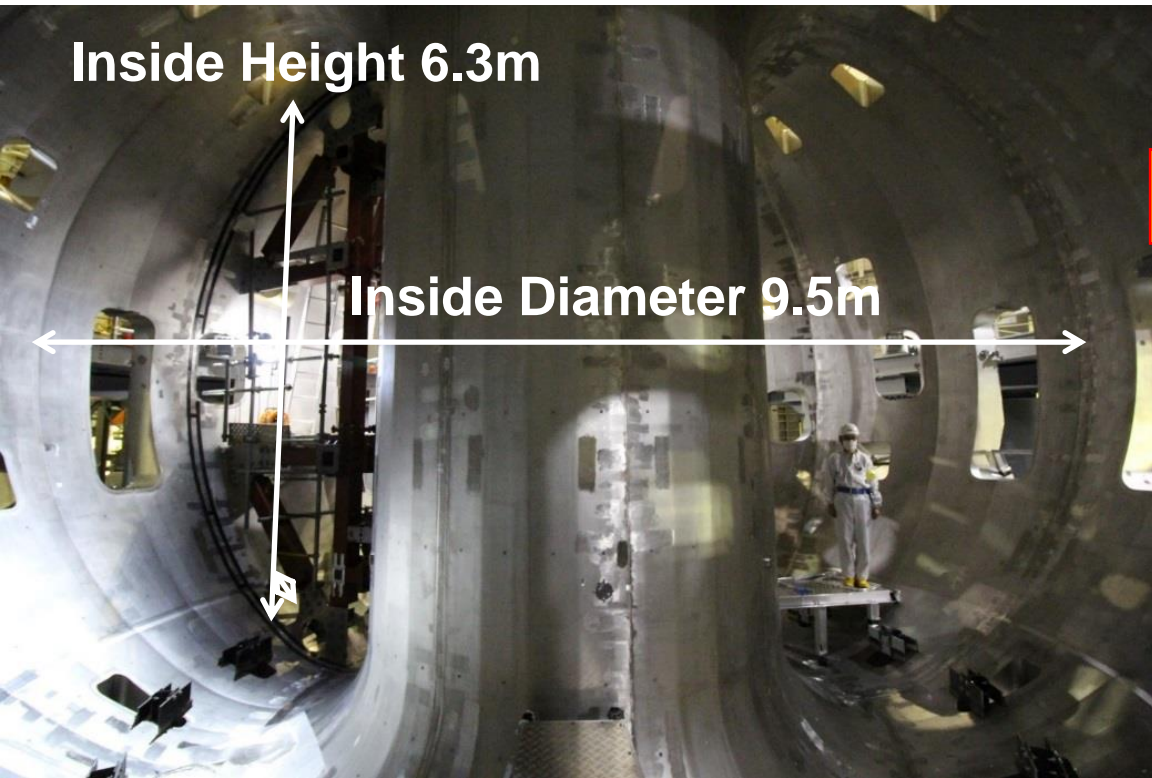


Shape after welding of final sector



**Accuracy of 340 degree sector:
 ± 4 mm (IB) & $+8/-2$ mm (OB)
within tolerance.**

Inside Vacuum Vessel

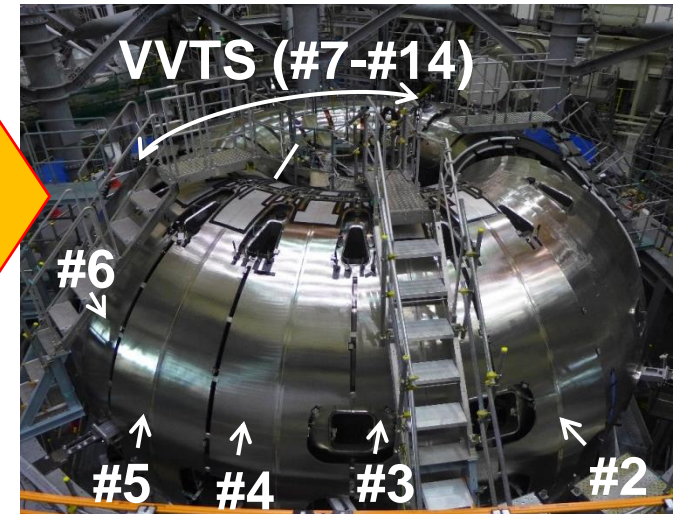


Assembly of VV Thermal Shield

Start: in Feb., 2016

Completion: Nov., 2016

VV Thermal Shield Assembly



The assembly technology for JT-60SA is expected to be applied to the ITER assembly.

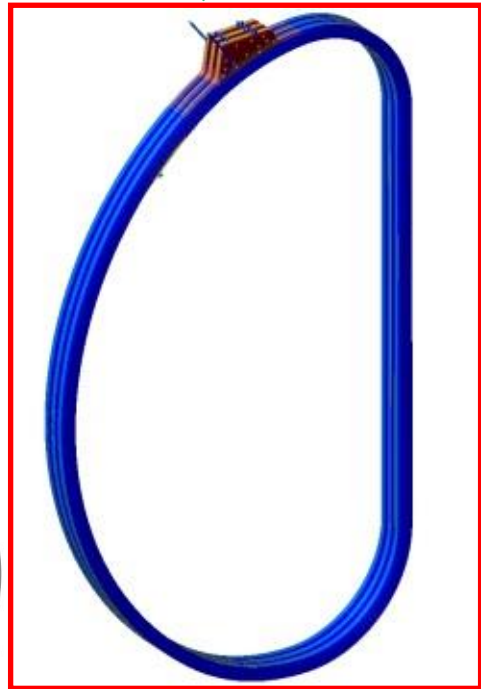
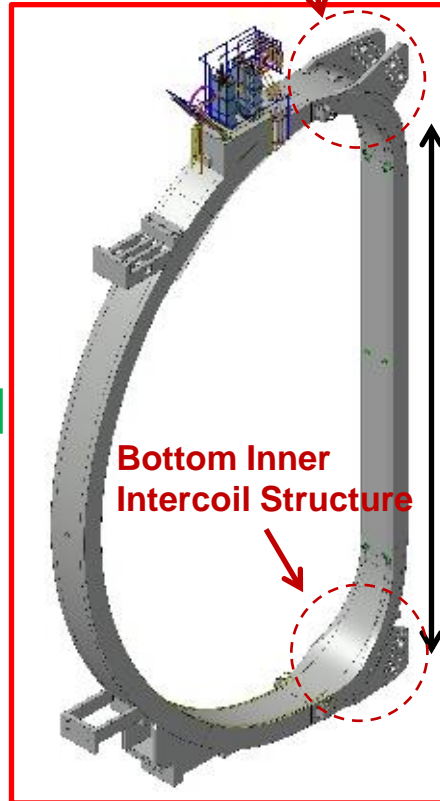
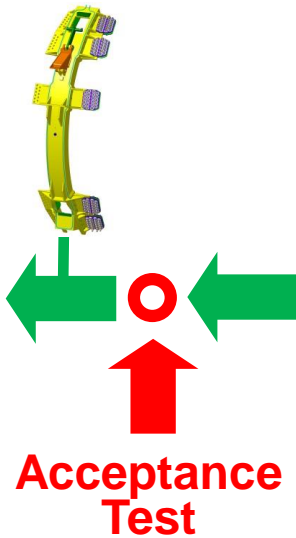
Outer Intercoil Structure

Top Inner Intercoil Structure

NbTi strand Conductor

CEA
(SDMS)




ENEA
(ICAS)



Acceptance Test

Straight Leg

Integration

CEA (GE)  ENEA (ASG) 



Casing

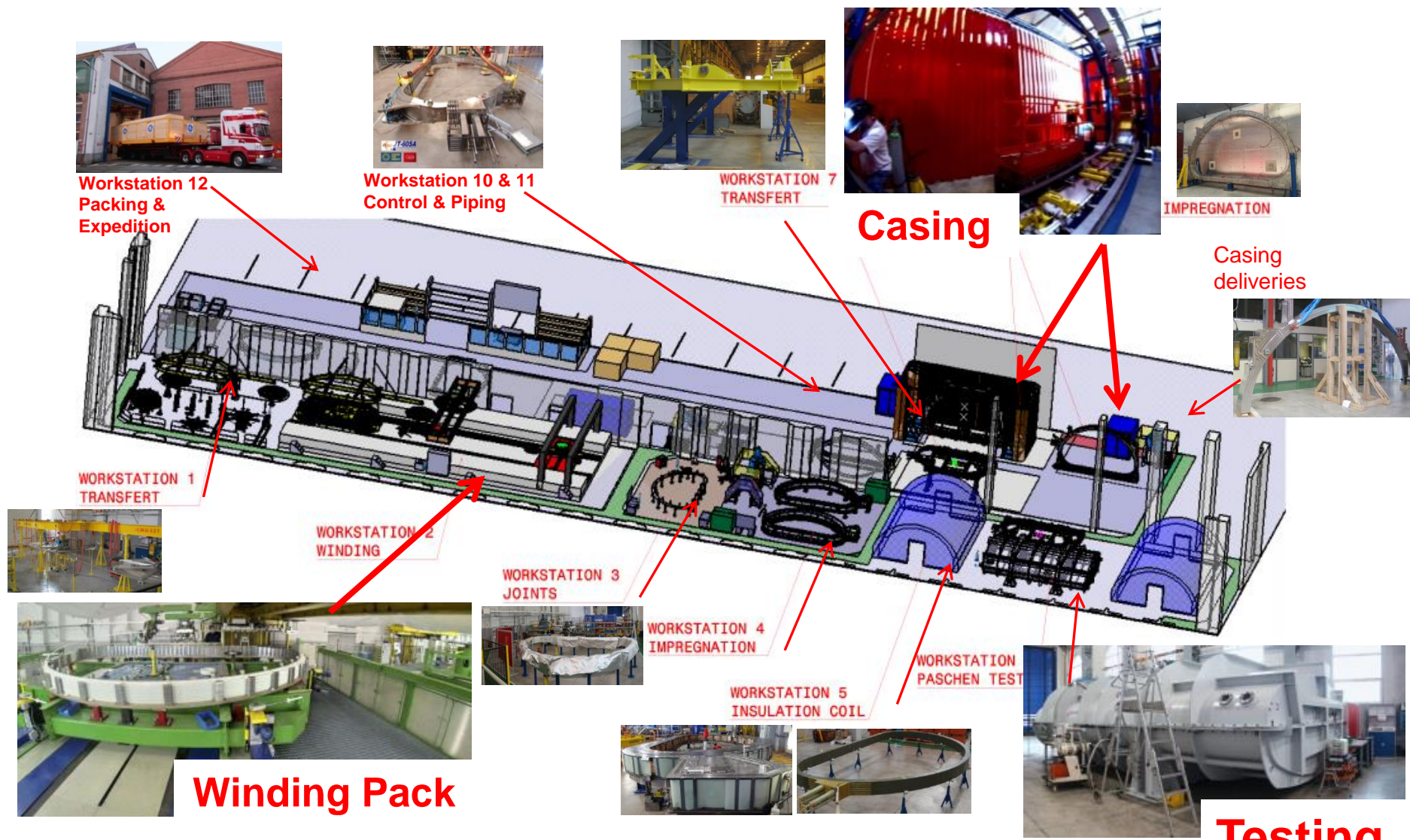
CEA (GE)  ENEA (ASG) 

Coil Case

ENEA (Walter Tosto) 

Winding Pack

CEA (GE)  ENEA (ASG) 



TF coils are manufactured and tested in the inline factory to keep the high quality assurance.

Three important process are shown.

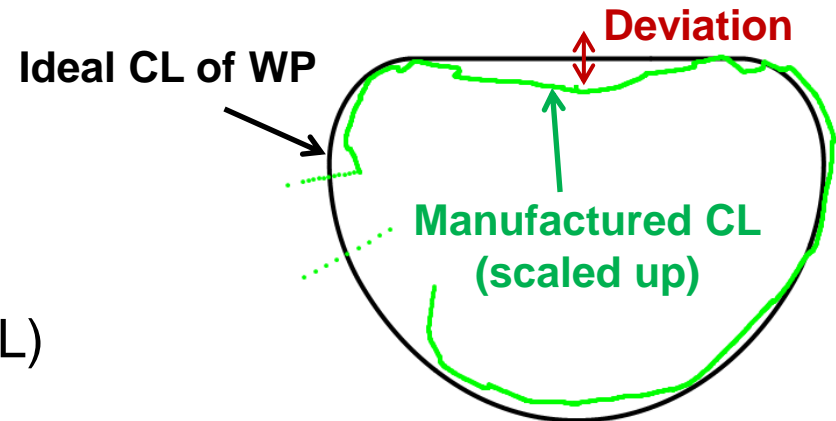
- **Winding Pack (WP)**
- **Casing**
- **Test**

In the WP process, double pancakes were manufactured with reference frame **to control the D-shape and planarity.**

WP was manufactured in acceptable accuracy.

- Deviation from the ideal Center Line (CL) in the D-shape is smaller than design tolerance. (~2 mm)
- Cross section of WP is within tolerances.
144 ± 1.5 mm (T) x 342 ± 1 mm (W)
(design tolerance ± 3 mm & ± 5 mm)

Winding controlled in D-shape & planarity



Linearity on straight leg is required to be well controlled to suppress the magnetic field error. The followings measures are taken.

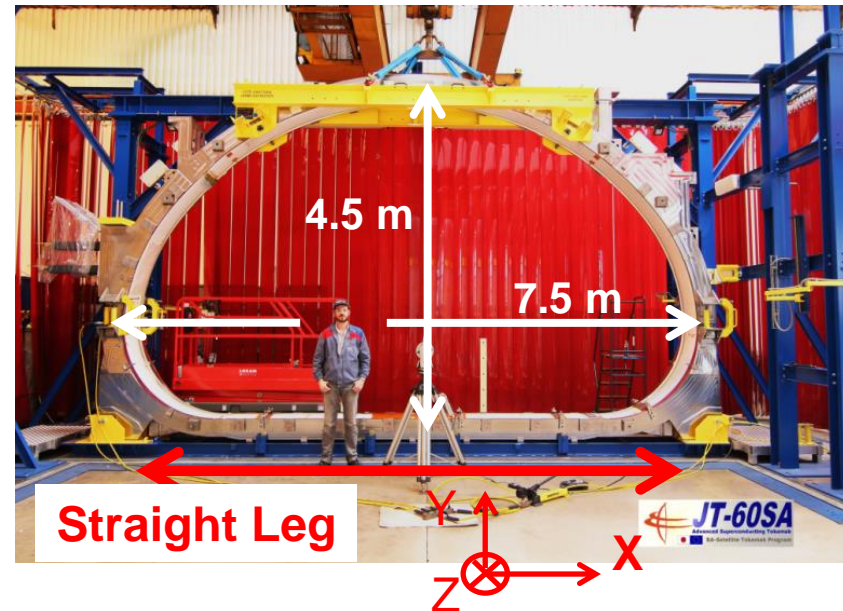
WP was positioned in high accuracy in the case by using laser tracker.
(Placed: -0.14 mm in X, +0.15 to +0.36 mm in Y)

Progressive counter bending was applied to straight leg in order to compensate longitudinal weld shrinkages. (deformation ≈ 2 mm)

By manual transverse MAG simultaneous welding, shrinkage was < 3 mm as expected.

TIG twin heads robot was applied to enhance the efficiency of work.

Coil Case from F4E



Longitudinal welding by TIG twin heads



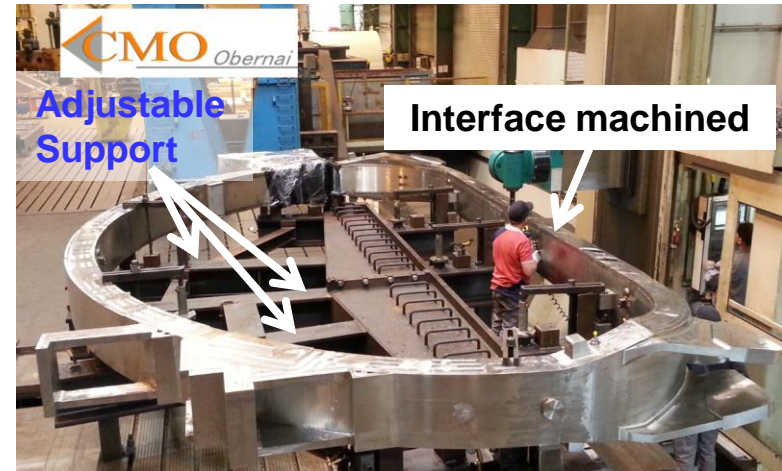
To realize the designed tolerance of the distance from the center line to the interface surface, **Interface surfaces were machined.**

- Support stage with adjustable 10 points for stress free condition
- No turning over the coil

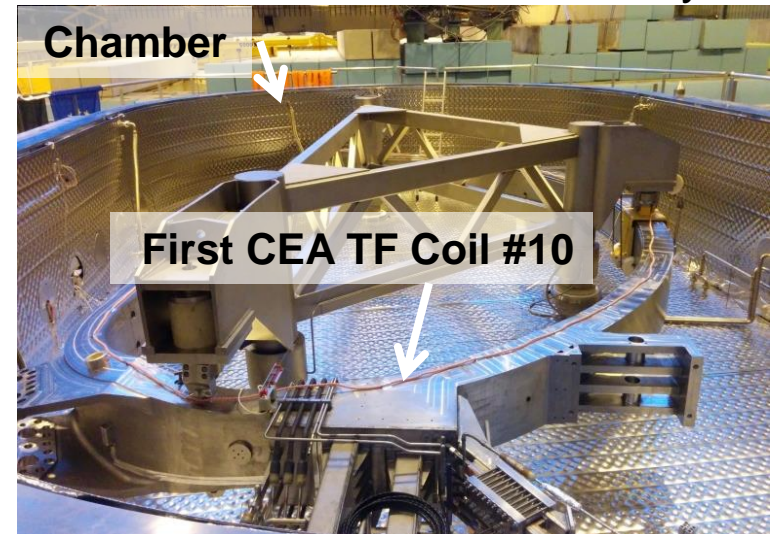
First TF Coil was tested beginning 2016, and five TF Coils fulfilled performance requirements.

- Room temperature test
- Cold test (Current test, etc.)

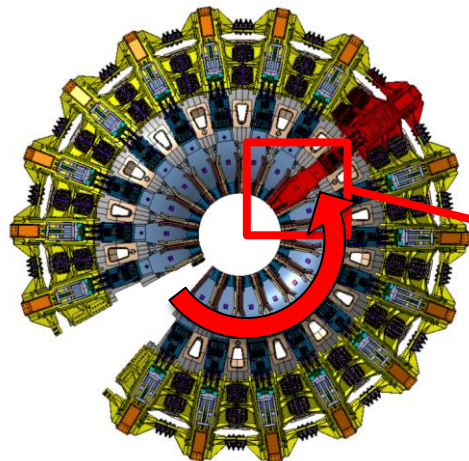
Planarity & horizontality are adjusted to ± 0.05 mm



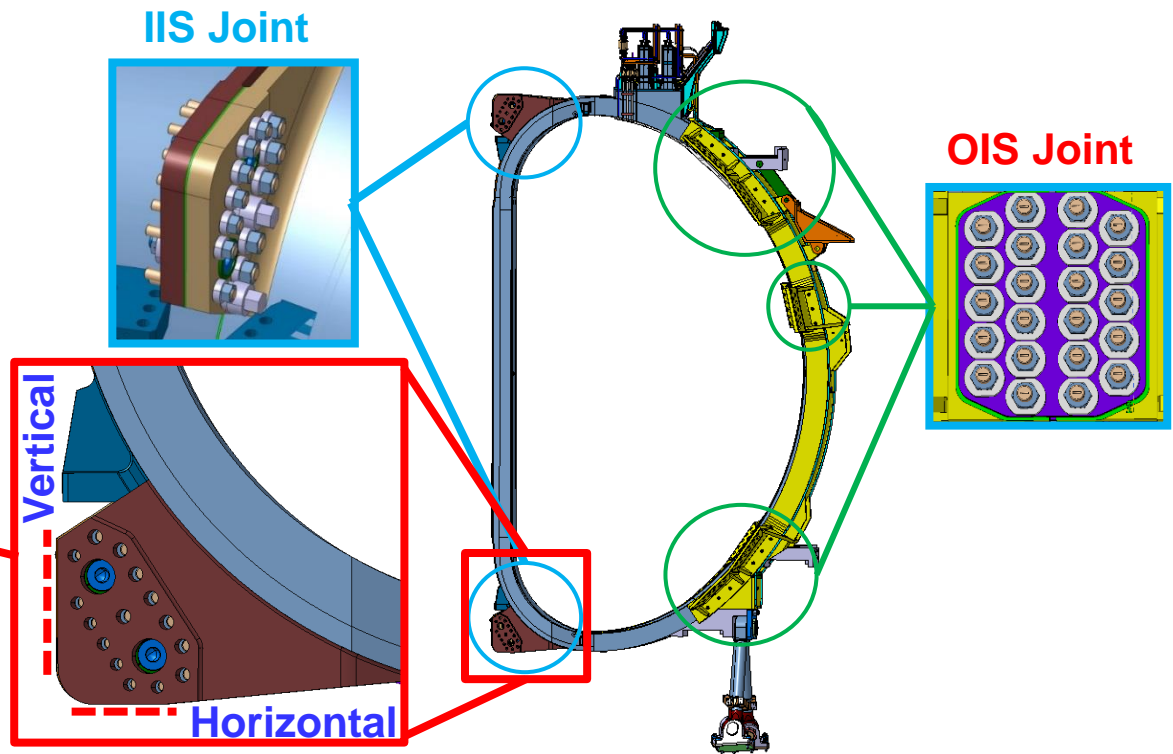
First Coil in Cold Test Facility



- TF Coils are aligned each other on the reference planes of lower Inner Intercoil Structure (IIS).
- **This tolerance is ± 1 mm in order to achieve face-to-face contact between IISs.**
- IIS & Outer intercoil Structure (OIS) are jointed with neighbour coil by bolts.



Position of first coil



Lower IIS ref. planes

- **Assembly technology for JT-60SA has been developed.**
 - Assembly procedure by using three-dimensional CAD
 - Metrology of the assembly by using a laser tracker
 - Welding technology by predicting welding shrinkage
- **Cryostat base is assembled with allowable accuracy as low as 2 mm.**
- **340° vacuum vessel is successfully assembled with allowable accuracy of ± 4 mm (IB) & $+8/-2$ mm (OB).**
- **TF coils are manufactured with allowable accuracy of ± 1.5 mm, and delivered to Japan.**
- **Assembly of TF coils starts in this December.**