

Max-Planck-Institut für Plasmaphysik, EURATOM Association, Greifswald

Final Assessment of Wendelstein 7-X Magnetic Field Perturbations Caused by Construction Asymmetries

T. Andreeva¹, V. Bykov¹, T. Bräuer¹, K. Egorov¹, M. Endler¹, J. Fellinger¹, J.Kißlinger², M. Köppen¹

¹ Max-Planck-Institut für Plasmaphysik, EURATOM Association, Teilinstitut Greifswald, Wendelsteinstraße 1, D-17491 Greifswald, Germany

² Max-Planck Institut für Plasmaphysik, EURATOM Association, Boltzmannstr. 2, D-85748 Garching, Germany

Motivation

Wendelstein 7-X (W7-X), currently under commissioning at the Max-Planck-Institut für Plasmaphysik in Greifswald, Germany, is a continuation of the helical advanced stellarator line, with the final goal to demonstrate the reactor capability of modular stellarators.

Most of the envisaged magnetic configurations of the machine are very sensitive to symmetry breaking perturbations which are the consequence of unavoidable construction displacements and manufacturing tolerances. In order to keep the magnetic configuration of the machine as designed and to confirm compensation capabilities provided in W7-X, the level of error fields needs to be quantified for all possible sources of perturbation. One of such sources is the sequential torus assembly procedure after the placement of magnet system modules on the machine base.



Conclusions

 \blacktriangleright Non-systematical coil deformations due to the sequential torus assembly: maximum WP cross-section displacements < 2 mm in each direction.

➤ Corresponding magnetic field perturbation varies from $1.17 \cdot 10^{-4}$ to $1.25 \cdot 10^{-4}$ (dependently on reference operation case), and its maximum value corresponds to the low iota case.

This presentation shows results of the evaluation of the influence of the asymmetrical torus assembly as well as a comparative analysis for different sources of W7-X error fields.



FIG. 1. Wendelstein 7-X, October 2014.



➤ A comparison of the analyzed sources of magnetic field perturbation showed that, even with a safety margin to cover calculation uncertainties and small inaccuracies of the FE models, the corresponding cumulative estimation is $S_{14} < 2 \cdot 10^{-4}$. This level of the magnetic field perturbation is below the compensation capacities of the installed trim coils and leaves enough potential to eliminate the impacts of possible additional magnetic field perturbations. Hence, the compromise between physical needs and engineering challenges can be successfully met.

Comparison of different sourcesof magnetic field perturbation for standard
operation case> manufacturing tolerancesMagnetic field perturbation with 50 as-built non-planar winding
packs (NP WPs), real W7-X coil allocation and CAD coil
positioning:S14≈ 0.75 ·10⁻⁴ (mostly compensated by optimized

module positioning)

 $\times 10^{-4}$



Standard case:Standard case:no perturbationperturbation $B_{11}/B_0 \sim 2.7 \ 10^{-4}$

Finite element calculations on deformations of W7-X magnet system and resulting magnetic error field

> sequential torus assembly after module positioning

deviations are partly systematic, max variation in non-symmetrical part: 2.0 mm
reason of possible magnet system deformation: the sequential loading of the machine base, the connection of adjacent modules to each other and the removal of temporary supports. Deformations are calculated with 360° ABAQUS FE Model, including W7-X machine base.

• simulation of error field: deformed filaments of 70 coils derived from FE analysis served as an input. Corresponding magnetic field perturbation S_{14} varies from 1.17 to $1.25 \cdot 10^{-4}$, its maximum value is found in low iota case, dominating component B_{11} .

TYPICAL RESULTS OF FE ANALYSIS: displacements along WP of NPC1 in half-module HMx1, where x=1,...,5.



FIG. 2. Wendelstein 7-X magnet system, top view. NPC – non-planar coil, PC – planar coil.



FIG. 3. CATIA view of one module with temporary supports (yellow) under NPC5, NPC1 and NPC4.





➢end of module positioning

Magnetic field perturbation with 50 as-built NP WPs, real W7-X coil allocation and real W7-X coil positioning:

 $S_{14} \approx 0.34 \cdot 10^{-4}$ (will be compensated by trim coils)

EVOLUTION OF MAGNETIC FIELD PERTURBATION DURING

OPTIMISED MODULE POSITIONING



Standard case	1.20	0.13	0.09	0.02	1.21
Low shear case	1.19	0.10	0.10	0.02	1.20
Inward shifted case	1.19	0.14	0.08	0.02	1.20
Outward shifted case	1.21	0.12	0.09	0.02	1.22
Low mirror case	1.22	0.13	0.08	0.02	1.23
High mirror case	1.18	0.12	0.09	0.02	1.19
Limiter case	1.21	0.11	0.10	0.02	1.22
Low iota case	1.24	0.11	0.08	0.03	1.25
High iota case	1.16	0.14	0.1	0.01	1.17

>uncertainties of parameters of the magnet system

deviations are partly systematic, max variation in non-symmetrical part: 1.8 mm
reason of possible magnet system deformation : variations of coil case thickness, gap sizes and friction factors at various sliding contact support elements, differences in bolt preloads and structure material properties in the five modules. Deformations are calculated with 72° ANSYS Global FE Model .

• simulation of error field: 50 random sets derived from FE analysis of 5 modules were compiled and served as an input. The average value of the magnetic field perturbation S_{14} is $0.2 \cdot 10^{-4}$, the maximum value $0.32 \cdot 10^{-4}$, dominating component B_{11} .

E-mail: tamara.andreeva@ipp.mpg.de

FIG. 4. W7-X trim and control coils.

Trim and control coils compensation capacities

current	B ₁₁ / 3T / 10 ⁻⁴	B ₂₂ / 3T / 10 ⁻⁴	B ₃₃ / 3T / 10 ⁻⁴	B ₄₄ / 3T / 10 ⁻⁴
trim coils 86.4 kA	6.67	2.67	1.67	0.87
control coils 20 kA	1.07	2.67	3.47	2.93

errors M05 M01 M04 M02 M03

Sequential torus assembly after module positioning (mainly removal of temporary supports)

For 50 initially ideal NP WPs with CAD positioning derived from FE analysis deformations contribute to magnetic field perturbation as following:

 $S_{14} \approx 1.21 \cdot 10^{-4}$ (will be compensated by trim coils)

Incertainties of parameters of the magnet system (variation of structural characteristics) For 50 initially ideal NP WPs with CAD positioning derived from FE analysis deformations contribute to magnetic field perturbation as following:

 $S_{14} \approx (0.2-0.3) \cdot 10^{-4}$ (will be compensated

by trim coils)

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