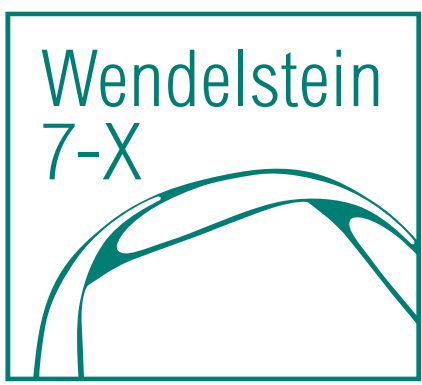


THE WENDELSTEIN 7-X ECRH PLANT - EXPERIENCE WITH RELIABLE LONG PULSE OPERATION OF A MULTI MW GYROTRON INSTALLATION

S. Marsen, L. Krier, H.P. Laqua, D. Moseev, J.W. Oosterbeek, S. Ponomarenko, T. Stange, H. Braune and the W7-X TEAM
Max-Planck-Institute for plasma physics, Wendelsteinstraße 1, Greifswald, Germany

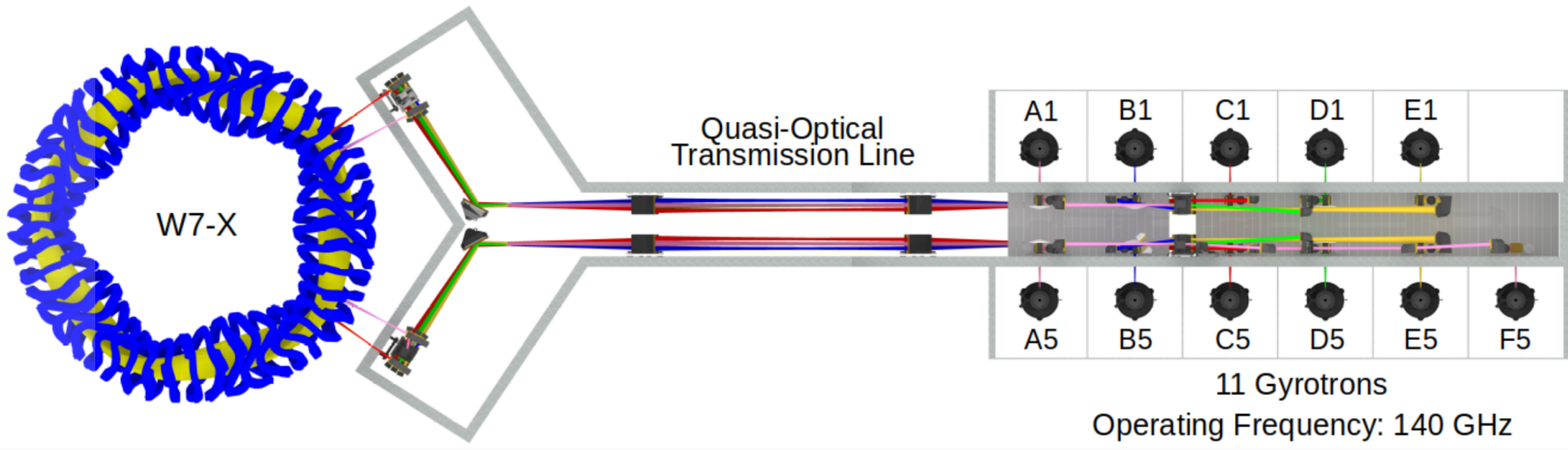


MAX-PLANCK-INSTITUT
FÜR PLASMAPHYSIK

INTRODUCTION

W7-X 10MW ECRH plant

- 11 gyrotrons
- CW operation (1800s)
- Total power $\Rightarrow$ 8.5MW in torus
- Quasi optical transmission line



Gyrotron reliability

- Automatic recovery systems in case of
 - $\Rightarrow$ Mode loss $\Rightarrow$ Acceleration voltage is reduced to operate reliably at max. power
 - $\Rightarrow$ Overcurrent on body $\Rightarrow$ Body voltage is switched off for a few ms
 - $\Rightarrow$ Arcing $\Rightarrow$ Gyrotron is switched off for ~ 100 ms
- Hardening of transmission line to prevent arcing

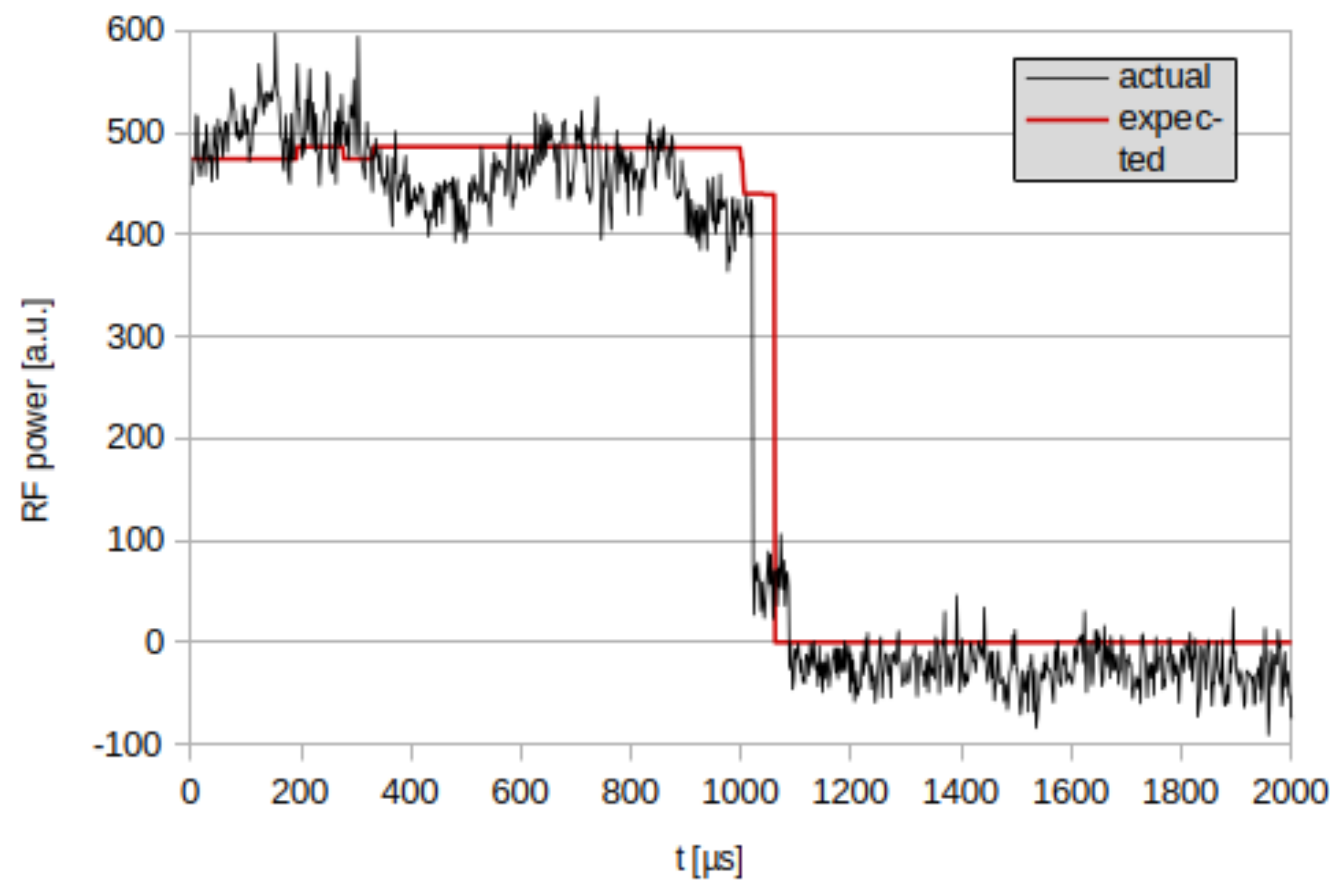
System level reliability

- High performance plasma scenarios require sufficient power continuously
- Lost power must be compensated
- New concept tested in OP2.3 $\Rightarrow$ total power feedback control

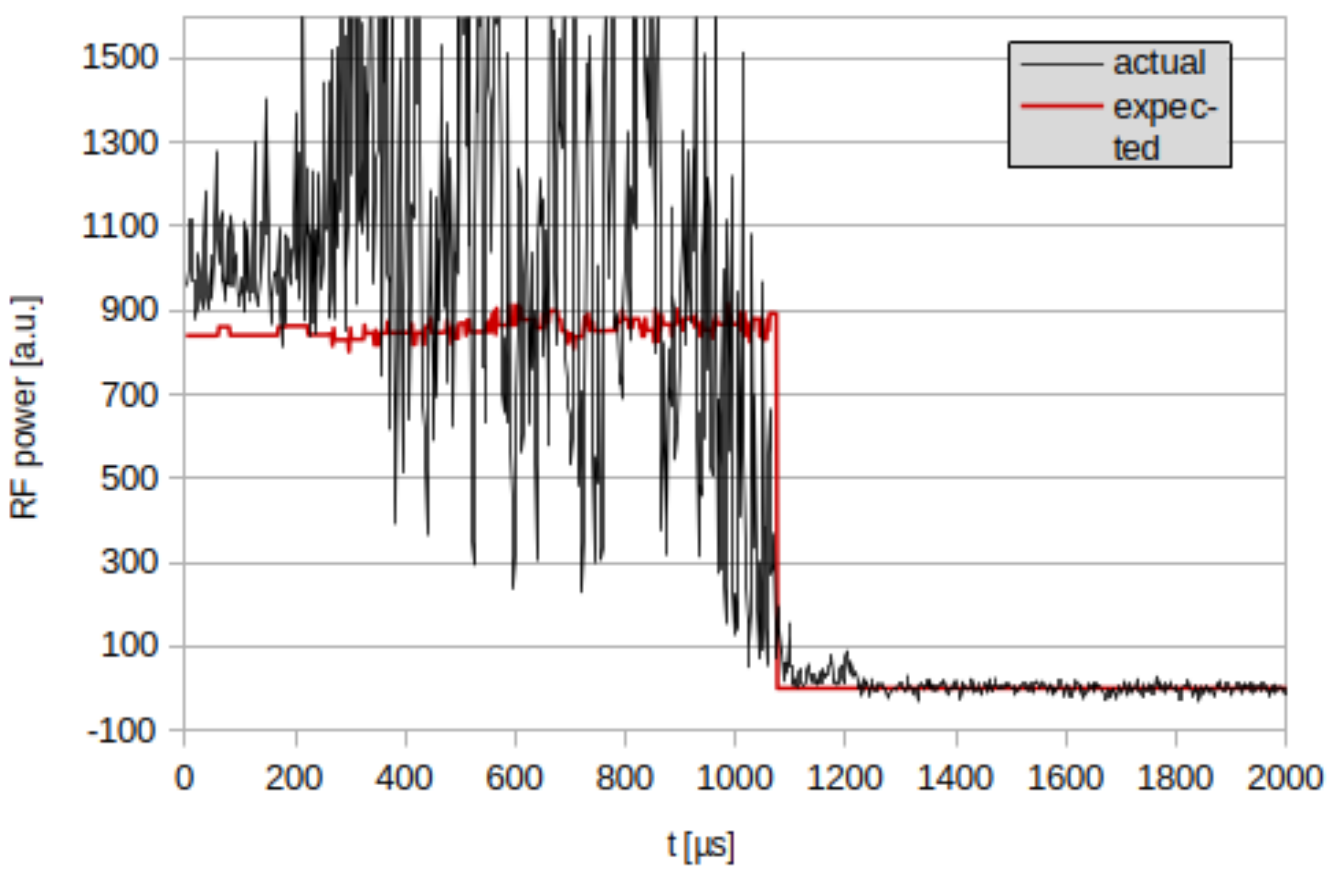
FASTER ARC DETECTION

- Fast arc detection crucial for reliable operation
 - $\Rightarrow$ Fully developed arc pollutes atmosphere $\Rightarrow$ all gyrotrons affected
 - $\Rightarrow$ Risk of further arcs strongly increased
- Classical arc detection: optical fibre viewing at mirror surface
 - $\Rightarrow$ Only fast enough if arc develops at mirror surface
- Faster arc detection by power measurement at end of transmission line
 - $\Rightarrow$ Comparison with power measured at MOU
 - $\Rightarrow$ Sensitive to arc at any position
 - $\Rightarrow$ Detection within some $10 \mu\text{s}$ possible
- Installed for almost all W7-X gyrotrons
- OP2.2/2.3 used to gain experience with system
- Arcs close to detector system cause strong fluctuations
 - $\Rightarrow$ Stray radiation due to multiple reflections of beam at arc and metallic surfaces enters detector
- Arc detection algorithm only reacts on loss of signal (absolute threshold)
- New version reacting on amplitude of high pass filtered signal planned for OP2.4

Comparison of actual and expected power at end of transmission line



Drop of power $\Rightarrow$ gyrotron is switched off within $20 \mu\text{s}$



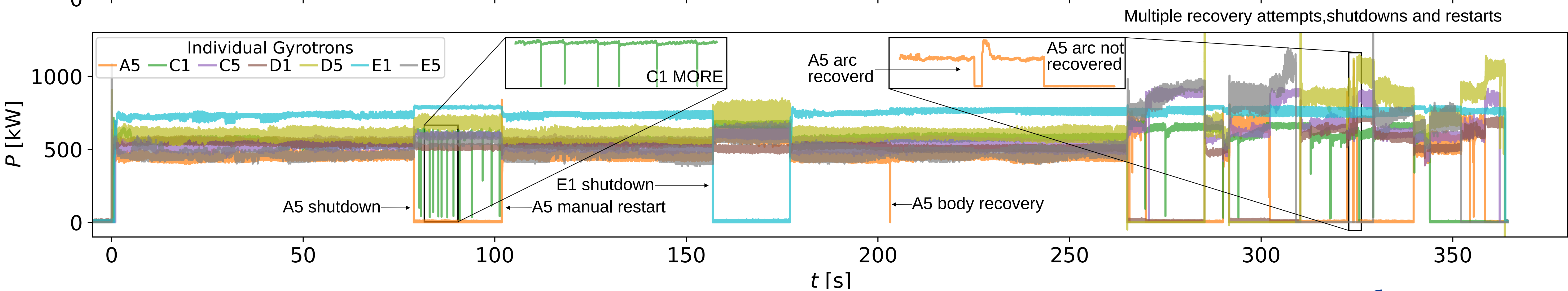
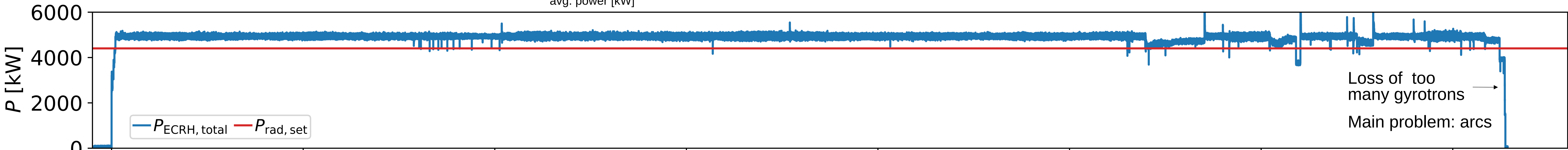
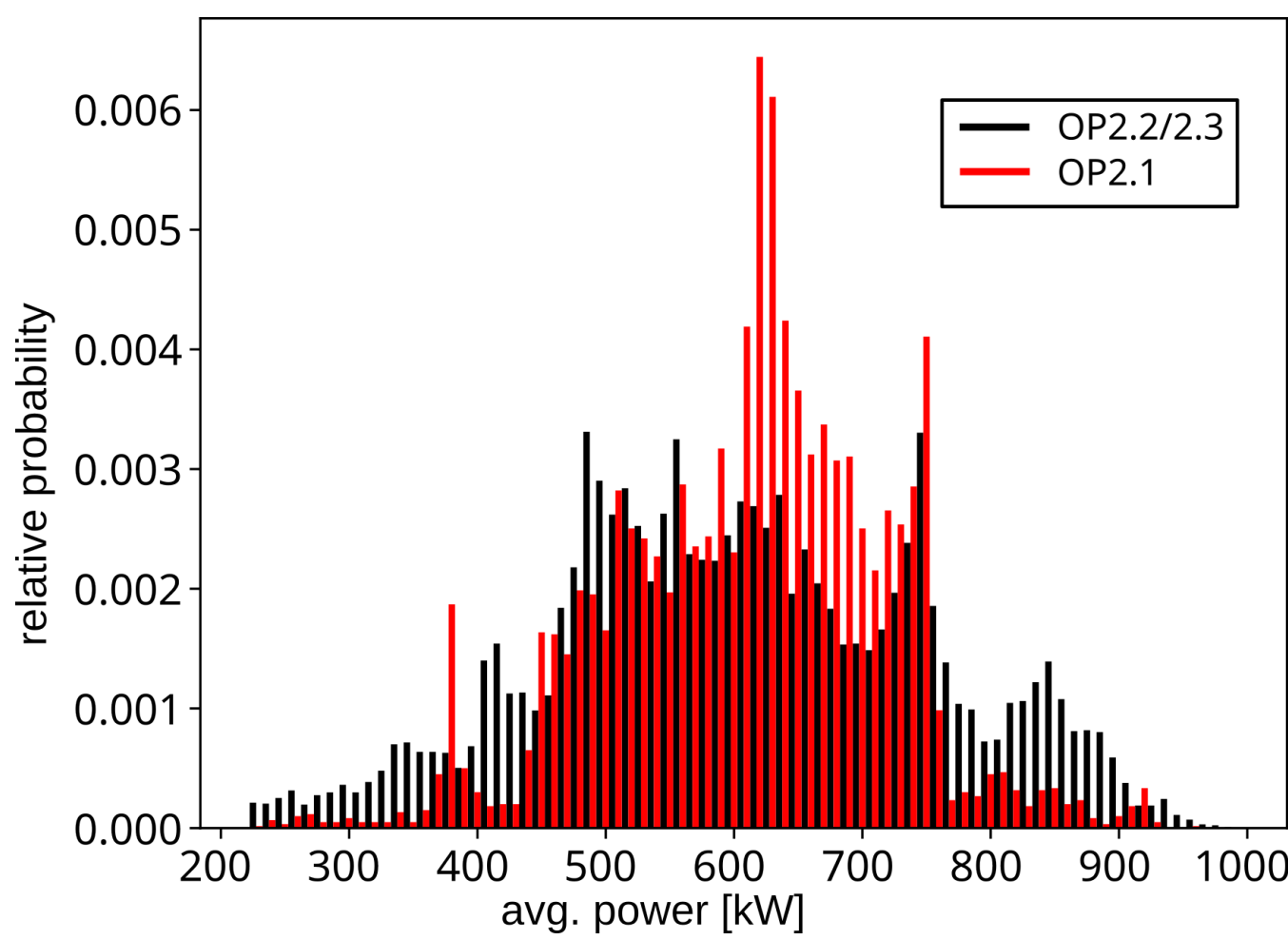
Strong fluctuations due to stray radiation entering detector $\Rightarrow$ gyrotron is switched off after > 1 ms

PERFORMANCE IN OP2.2/2.3

4300 W7-X experiment programs $\Rightarrow$ 99% successful

Gyrotron reliability

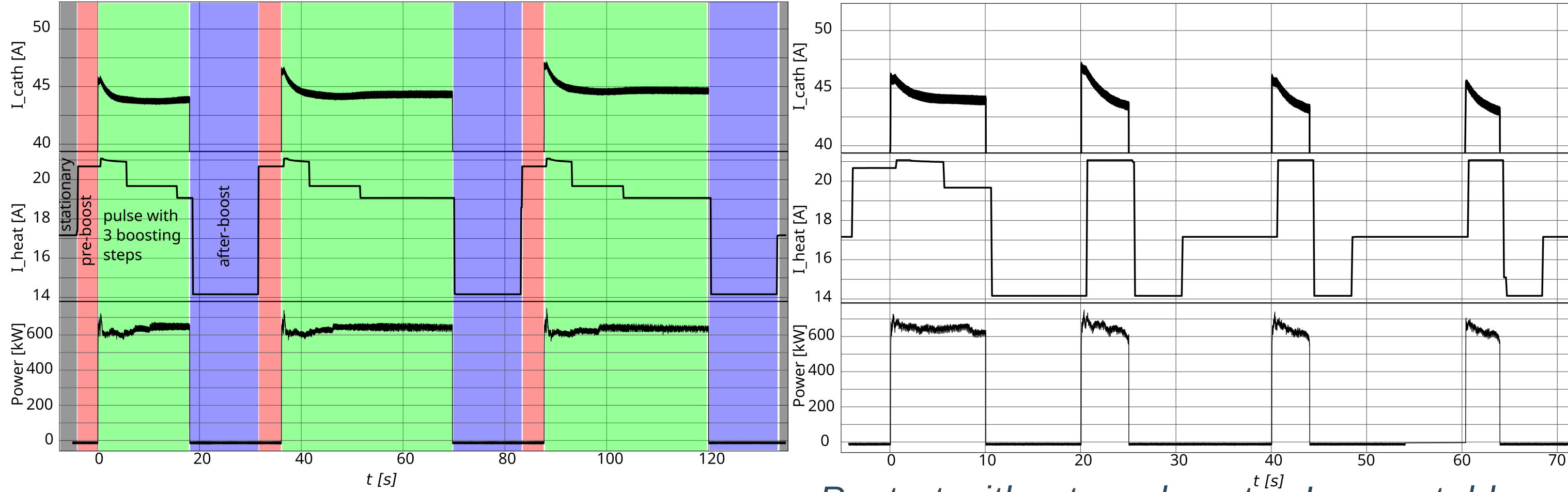
- More than 14000 individual gyrotron pulses
- 94% of pulses ran through without failure (92.4 in OP2.1)
- Average power during pulse increased



CATHODE HEATER BOOSTING

- Cathode current I_{cath} drops exponentially due to cooling by electron emission
- Compensated by actively boosting heater current
- Boosting has to start 5s before pulse (pre-boost)
- Surplus energy in heater extracted by reducing current after pulse (after-boost)
- Lost gyrotron cannot be replaced by spare one immediately
- Restart scenarios for tripped gyrotrons during a pulse:
 - $\Rightarrow$ Within < 3 s $\Rightarrow$ compatible with automatic restart attempts
 - $\Rightarrow$ Full cycle of after- and pre-boost, typically > 20 s

Comparison of different boosting schemes when restarting a gyrotron

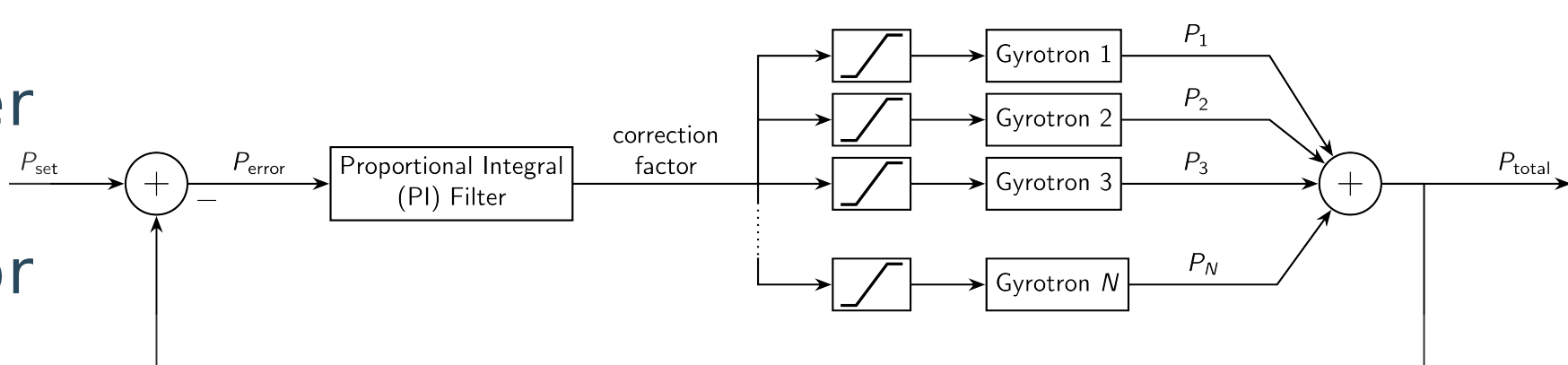
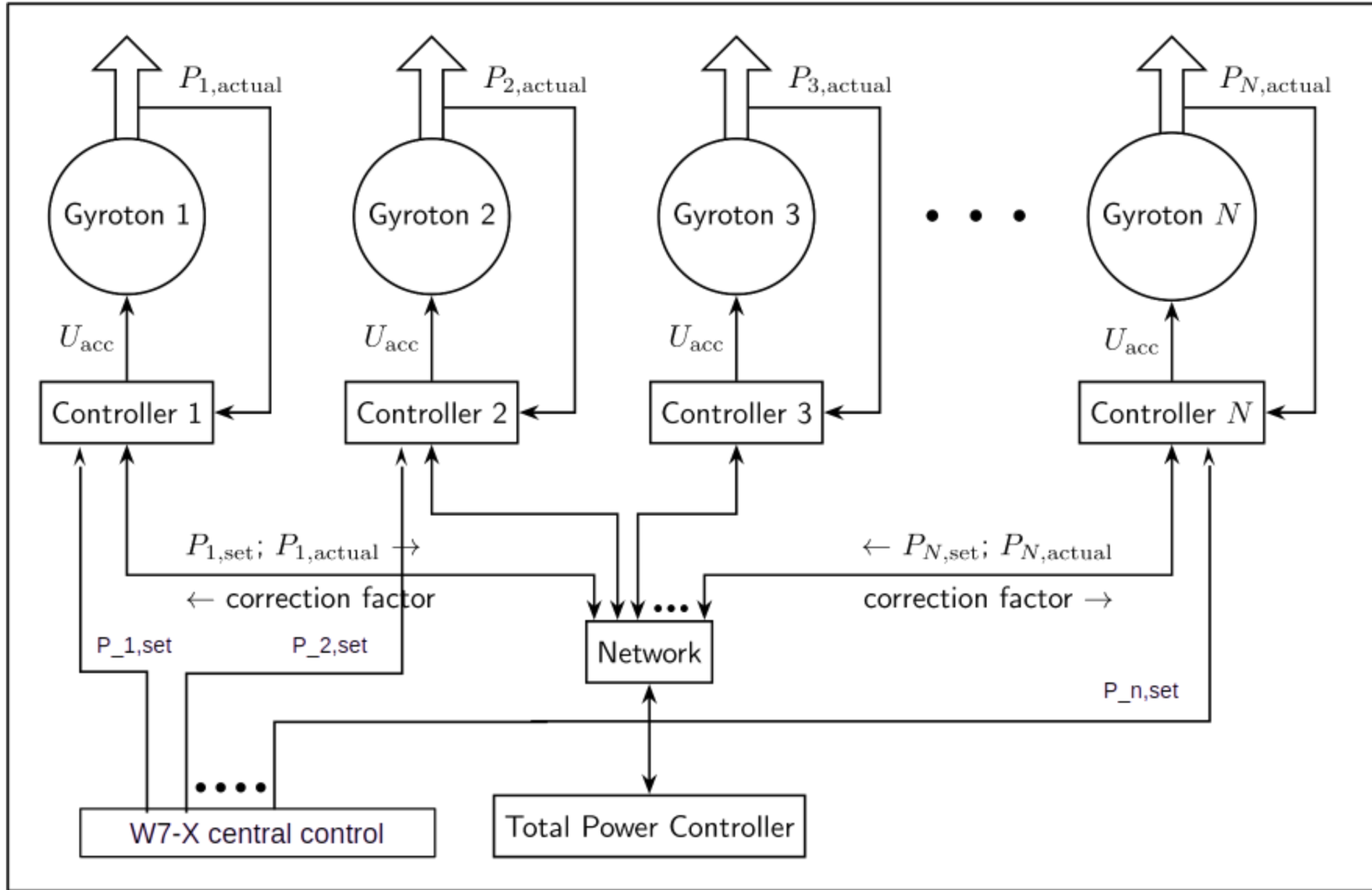


Restart with after- and pre-boost $\Rightarrow I_{\text{cath}}$ stable

Restart without pre-boost $\Rightarrow I_{\text{cath}}$ unstable, mode loss after a few seconds

TOTAL POWER FEEDBACK CONTROL

- Basic idea $\Rightarrow$ Equally increase power of all gyrotrons if one is lost
- Gyrotron power: $P_{\text{ECRH}} \propto V_{\text{acc}}$
- HV supplies act as amplifiers $\Rightarrow$ set point generated by FPGA based controller
- Software based feedback control on top of individual gyrotron control
- Implemented on RaspberryPi
- Ethernet communication with gyrotron controller
- Input $\Rightarrow$ actual power, power set point
- Output $\Rightarrow$ correction factor for power set point
- All gyrotrons are operated at 80...90% P_{max} $\Rightarrow$ loss of 1 or 2 gyrotrons can be compensated
- PI feedback controller increases power in ~ 100 ms after loss of gyrotron



System level reliability

- Envisaged milestone in OP2.3 $\Rightarrow$ 2GJ energy turnaround
- Achieved $\Rightarrow$ 1.8GJ, 5MW total power for 360s with feedback control
 - $\Rightarrow$ Multiple automatic recovery interventions $\Rightarrow$ time scales irrelevant for plasma
 - $\Rightarrow$ Loss of 2 gyrotrons was compensated by feedback controller, constant total heating power for 270s
- Still problems with arcing after ~ 5 min. high power operation
 - $\Rightarrow$ Thermal effect, further improvement of air conditioning planned for OP2.4



This work has been carried out within the framework of the EUROfusion Consortium, funded by the European Union via the Euratom Research and Training Programme (Grant Agreement No 101019720) — EUROfusion. Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or the European Commission. Neither the European Union nor the European Commission can be held responsible for them.



EUROfusion