

Advancing Interpretability in Artificial Intelligence Disruption Prediction Models: A Cross-Tokamak Perspective

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Outline

- JET Dataset
- Disruption prediction by ML algorithms
	- \checkmark CNN predictor
	- \checkmark Comparison among CNN, MLP and GTM
	- \checkmark CNN upgrade with vertical bolometer
- Unsupervised disruption predictor
	- \checkmark SOM predictor
- Conclusions and ongoing work

JET Dataset - UNICA

[1] E. Aymerich *et al*, *Nuclear Fusion 2021*, 61(3), 036013

ne-HRTS **Te, ne and Prad peaking factors (0D):**

- encode spatial information
- defined heuristically
- lose information as they spatially average profile values

Te, ne and Prad profile images (1D):

- no heuristic definition
- reports the entire profile values

CNN predictor architeture [2]

Te, ne and Prad profiles have been treated as a single image. I_i, P_{frac} and LM_{norm} are fed in downstream of the first filter block.

[2] E. Aymerich *et al*., Nucl. Fusion, vol. 62, p. 066005, 2022.

CNN disruptive pattern [2]

Radiated Power [W]

eVJ

6

 \overline{c}

5000

4000

3000

2000

1000

 $\times 10^{19}$

8

Electron Density [m⁻³]

Paths responsible for the alarms can be easily identified

- ❑ Impurity accumulation disruptive mechanism:
- \checkmark strong radiation from the central chords of BOL-H (Figure d)
- \checkmark electron temperature collapse at plasma core (LOS <23, Figure e)
- core electron density peaking (LOS <22, Figure f).

CNN disruptive pattern [2]

Paths responsible for the alarms can be easily identified

- ❑ Edge collapse disruptive mechanism:
- \checkmark rise of the plasma internal inductance (Figure b).
- radiation at the central chords of BOL-H (Figure d)
- cooling of the plasma between LOS 12 and 30 of HRTS (R between 3.13m to 3.46m, Figure e)

The further analysis of the BOL-V data allows to localize the radiation blob in the outboard of the plasma (chords 1-5, Figure c).

MLP and GTM predictor architetures [3]

Multiple condition alarm scheme of the GTM predictor proposed [4]

The peaking factors are defined as a '*core versus all*' metric [4] (*) excluding the X-point/divertor region from all (**) excluding the core region from all

Predictor performance comparison [3]

- Successful prediction (SP), Missed Alarms (MAs), False alarms (FAs)
- Cumulative fraction of predicted disruptions: reports the value, in per unit, of successful alarms activated before the corresponding warning $time(tD - talarm)$

CNN predictor upgrade adding vertical bolometer data [5]

The separation of the two different mechanisms makes the predictor alarm more interpretable:

top CNN branch provides larger warning times

bottom CNN branch detects the mode-locking phase.

The predictor allows to greatly reduce the number of FAs

The SOM resulting from the unsupervised training is coloured providing it only with the information related to the discharge ending state: *regular or disrupted*. No information about the precursors phase has been exploited.

samples from disrupted and regular pulses samples from disrupted pulses

[6] E. Aymerich *et al*., A self-organised partition of the high dimensional plasma parameter space for disruption prediction, **accepted for publication on Nucl. Fusion.**

The evolution of the pulse can be tracked in real time while the monitoring the velues of the original variable on the SOM component plains

Safe region disrupted region

The black dots track the position of the experiment on the map:

- beginning of the discharge flat-top
- ending of discharge flat-top

Regular pulse:

Flat and regular signal behaviors

The black dots track the position of the experiment on the map:

- beginning of the discharge flat-top
- ending of discharge flat-top

ending sample

Transition from safe to the disruptive region:

- \checkmark Increase of core radiation (increase of the *Radpf-CVA* and decrease of the *Radpf-XDIV* , Figure 4b)
- Subsequent decrease of core temperature

Last disrupted phase

✓ Rise of the locked mode (*MLnorm*)

Predictor performance comparison

Conclusions and future works

- ❖ CNN predictor achieves good performance and doesn't need any preprocessing of plasma profiles (ne, Te and Prad)
	- \checkmark Good a posteriori interpretability of the predictor answer for extrapolation of safe and disruptive path behaviors
	- \checkmark Easy portability of the predictor to different machines after rescaling the plasma profile with respect the machine dimensions.
- ❖ SOM predictor achieved good performance with unsupervised training
	- \checkmark No precursor phase is defined to interpret the predictor outcomes
	- \checkmark Real-time tracking of the discharge on the map
	- \checkmark Straight relation between the operative point evolution and features of the map regions for disruption monitoring.
- ❖ Ongoing work
	- \checkmark Developing profile standardization algorithms for predictor portability
	- \checkmark extracting rules from the SOM for a clear interpretation of the model's decisions during the discharge evolution.

Thank you

Neural networs

MLP models complex relationships between the input variable space \bar{I} and the output variable space $\overline{0}$

Input Layer
$$
\begin{cases} \bar{W}_1 \cdot \bar{I} + \bar{b}_1 = \bar{g} \\ \bar{h} = f(\bar{g}) \end{cases}
$$

\nOutput Layer $\begin{cases} \bar{h} = f(\bar{g}) \\ \bar{W}_2 \cdot \bar{h} + \bar{b}_2 = \bar{0} \end{cases}$

CNN consists of a cascade of blocks which performs a filtering of an input image to extract significant features

- \circ C_k convolutional layer
- \circ N_k batch-normalization layer
- \circ A_k nonlinear activation layer, with ReLU functions
	- P_{max} or P_{avg} are the max and average pooling layers

D dropout layer FC Fully connected layer

Self Organizing Map

A SOM projects a set of *N d*-dimensional input data $\mathbf{x}=[x_1, x_2, ..., x_d]$ into a 2D discrete **map topologically ordered**

Each input **x** is associated to a cluster of the map characterized by a weight vector **w** (barycenter of the inputs mapped in the node)

How the SOM works

❑ **Competition**

find the winning neuron, i.e., the closest to each input vector

❑ **Cooperation**

find the winning neuron's neighbors

❑ **Adaptation**

update the weights of winning neuron and its neighbors

$$
\mathbf{w}_j(n+1) = \mathbf{w}_j(n) + ah_{ij}[d(\mathbf{x}, \mathbf{w}_j(n))]
$$

 α learning rate

d distance function

h is the neighborhood function, it defines the winner neighborood

CNN predictor upgrade adding vertical bolometer data [5]

96893 is a regular pulse detected as disruptive by the CNN reference predictor [2], CNN-UP1 does not trigger an alarm, because the radiation pattern at chords #13-16 of BOL-H does not correspond to a radiation pattern of BOL-V.

CNN predictor upgrade with MHD spectrogram [7]

Remarkable reduction of FAs

CNN, responsible for processing the plasma profiles and Mirnov coils data, can yield longer warning times than the LM thresholding

CNN predictor upgrade with MHD spectrogram [7]

FA pattern in CNN reference predictor [2]:

- high radiation from central chords of BOL-H (figure 3d)
- ✓ decrease core electron temperature figure (figure 3e)
- peaking of the electron density at the core (figure 3f).

By adding the MHD spectrogram as input the CNN-UP2 output provides a limited rise of the disruptive likelihood both in time and value(figure 4a) with respect to the CNN reference predictor (figure 3a) .

Profile standardization

Definition of *resampling grids* to standardize the profile images among JET and AUG machines

AUG - ECE

Profile standardization

