Study of the halo current region resistivity on the DIII-D tokamak

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Outline

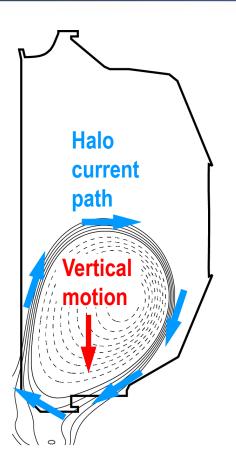
- The temperature and density of the halo current region were measured on DIII-D using the upgraded Thomson scattering diagnostic
- Deliberate downward vertical displacement events (VDEs) were employed and the halo current region upward expansion was captured by the core Thomson channels
- 'Type I' and 'type II' VDEs were studied using H-mode and ohmic target plasmas respectively
- 'Type I' VDE, having the current decay rate faster than the plasma vertical motion, characterizes by the electron temperature of the halo region in the range of 1–2 eV
- 'Type II' VDE has the opposite time scale dynamics and greater halo region electron temperature of 1–10 eV
- VDEs of both types result in the electron density of the halo region comparable with the core plasma density and quickly decreasing to the edge
- Peak halo currents exhibit values greater by about 5% in documented 'type II' VDEs
- Other key parameters of VDEs are also analyzed, providing a valuable input for validation of models



Introduction and Motivation



Halo currents can cause strong I_HxB forces during disruptions

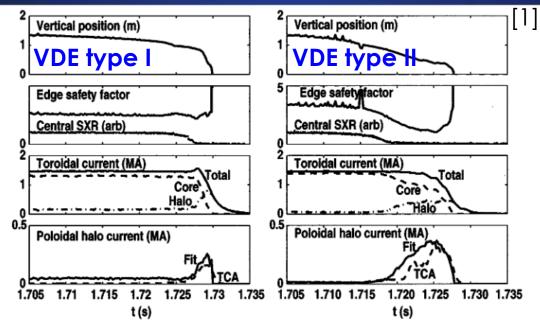


Poloidal halo current flowing in the SOL and vacuum vessel



- Elongated plasma in tokamaks is naturally vertically unstable
- Sudden loss of thermal energy or position control can lead to plasma moving vertically and touching the wall
- Moving, shrinking and decaying plasma induces toroidal and poloidal halo currents
- Halo currents partially flow through the vessel wall
- Interaction of poloidal halo current and toroidal magnetic field causes strong local and net vessel stress

Halo current dynamics is set by plasma motion and current decay rates



- Type I VDE is observed when plasma vertical motion is slower than current quench rate
 - Safety factor changes slowly and peak halo current is moderate
 - So-called "resistivity dominated" (cold) VDE
- Type II VDE is observed when plasma vertical motion and area reduction is faster than current quench rate
 - Safety factor quickly drops which causes greater peak halo current
 - "Motion-enhanced" (hot) VDE

Halo region resistivity and width are required to validate VDE/halo models

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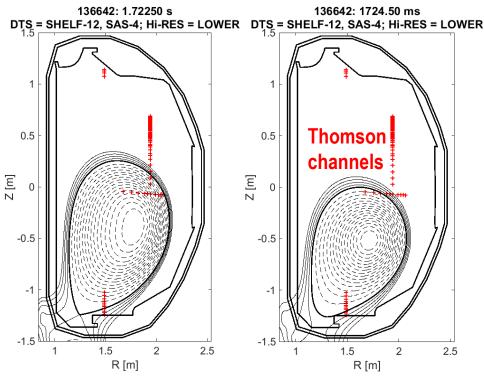
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[1] Humphreys PoP 1999

Key Tools and Scenario



Upgraded Thomson scattering is used to measure halo region's temperature and density

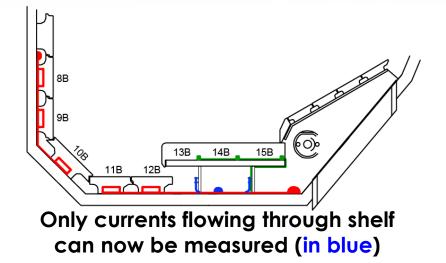


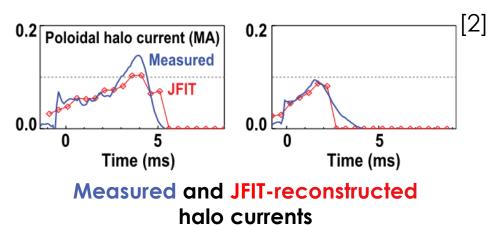
Configuration of Thomson scattering channels and VDEing plasma

- Thomson scattering provides absolute measurements of T_e , n_e along vertical, core, and divertor channels
- Recent upgrade with narrowbandwith polychromators enabled low T_e access (~1 eV)
- The bunch of Thomson's lasers can be triggered with a small time step (~0.1 ms) to cover a narrow time window



JFIT distributed current fitting code reconstructs halo current





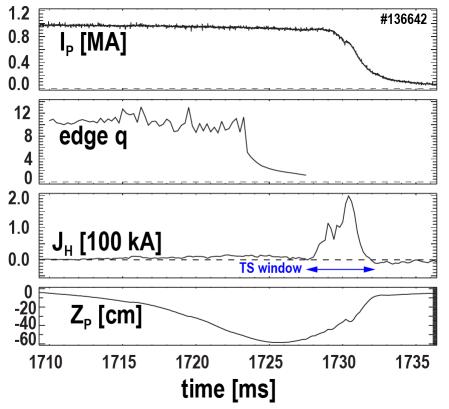
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8

- Instrumentation of DIII-D with halo sensors decreased over time to very limited coverage
- Halo currents can be reconstructed by fitting magnetic measurements using distributed current elements with JFIT code [1]
- Past experiments with wide halo sensor coverage exhibited good agreement between measured and reconstructed halo currents [2]
- Presently JFIT is the main tool to study halo currents

[1] Humphreys PoP 1999[2] Shiraki PoP 2016

Experimental approach: Deliberate VDE of H-mode and ohmic plasmas to study 'type I' and 'type II' halo cases



- Deliberate repeatable VDE can be reliably studied on DIII-D
- Downward VDE of H-mode plasma realizes 'type I' ('resistive') halo cases
- Ohmic plasma is used to study 'type II' ('motion-dominated') halo cases
- Thomson bunch is set to capture the expected time of the halo formation
- JFIT reconstructs halo current evolution

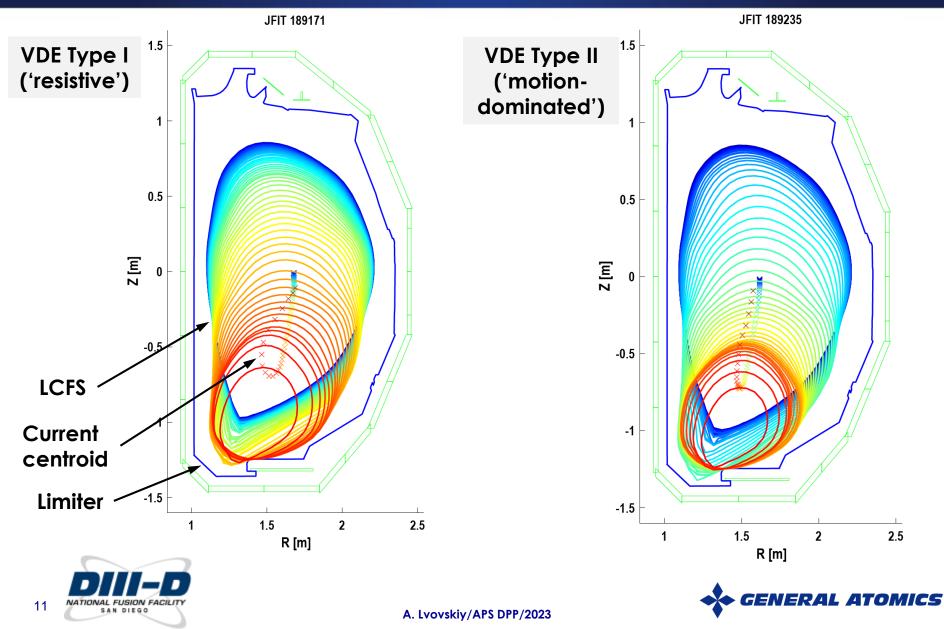


9

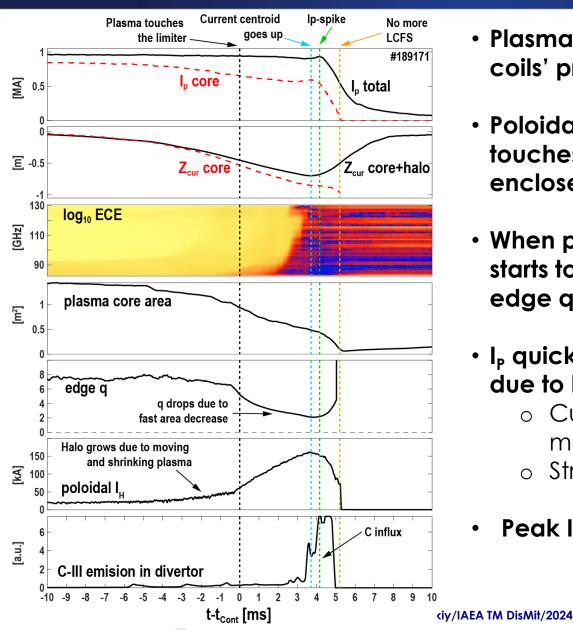




Plasma motion and shape evolution are well reconstructed by JFIT during VDE



Phenomenology of VDE and halo current

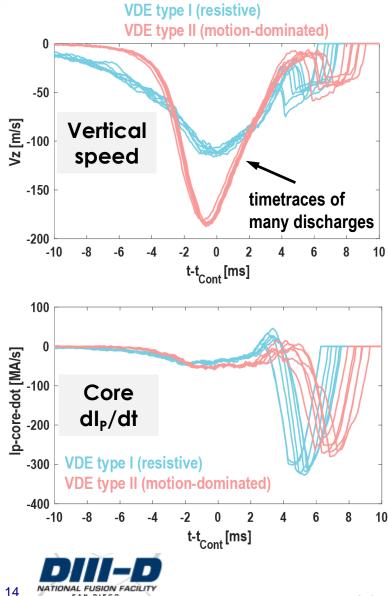


- Plasma is pushed downward via PFcoils' programming
- Poloidal I_H start growing before plasma touches the wall due to change in enclosed toroidal flux
- When plasma touches the wall and starts to shrink (at nearly constant I_P), edge q drops and poloidal I_H peaks
- I_P quickly decays after thermal quench due to highly resistive plasma
 - Current quench becomes the main driver of I_H as q increases
 - Strong carbon influx is observed
- Peak I_H=150 kA, stress = 28 kN/m²

Comparison of type I and II VDEs



VDE of H-mode plasma indeed shows type II (motiondominated) dynamics: greater V_z and slower current quench

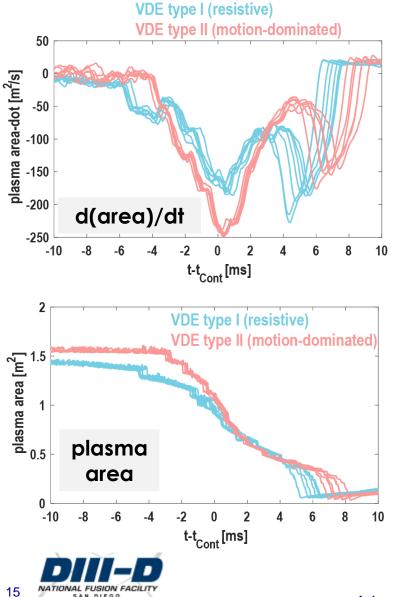


- Vertical speed of VDE type II reaches twice greater peak value compared to type I: v_z = 200 m/s vs 100 m/s, (γ_z = 400 rad/s vs 150 rad/s)
- Decay of core plasma current is slower for VDE type II compared to type I:

 $dI_P/dt = -250$ MA/s vs -300 MA/s ($\gamma_{ID} = 120$ rad/s vs 270 rad/s)

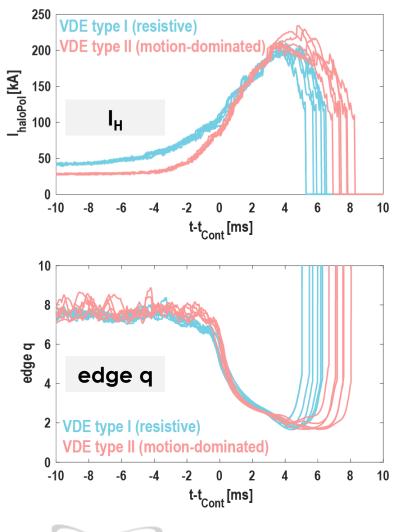
- Core current decay of VDE type II starts later after the vessel contact
- Both observations support more resistive nature of VDE type I

Shrinking rate of the core plasma area is also increased for VDE type II



- Core plasma area shrinks by almost 70% faster for VDE type II (motiondominated): -250 m²/s vs -150 m²/s
 - VDE type I shrinks slower but exhibits two peaks of about the same magnitude
 - 1st peak is when plasma touches the wall
 - \circ 2nd peak is during the CQ
- Both VDE type I and II have about the same core plasma area of 1 m² when they contact the vessel

VDEs of ohmic and H-mode plasma exhibit close halo current dynamics

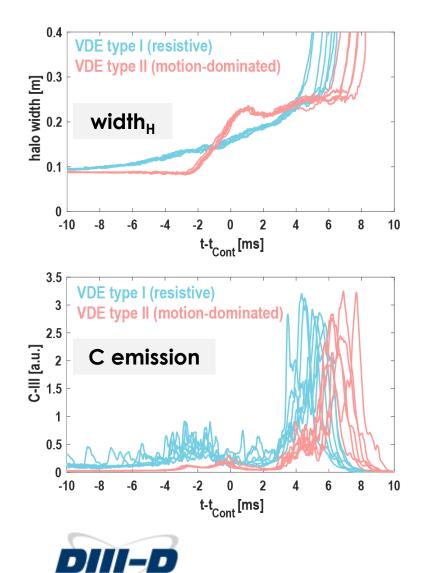


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16

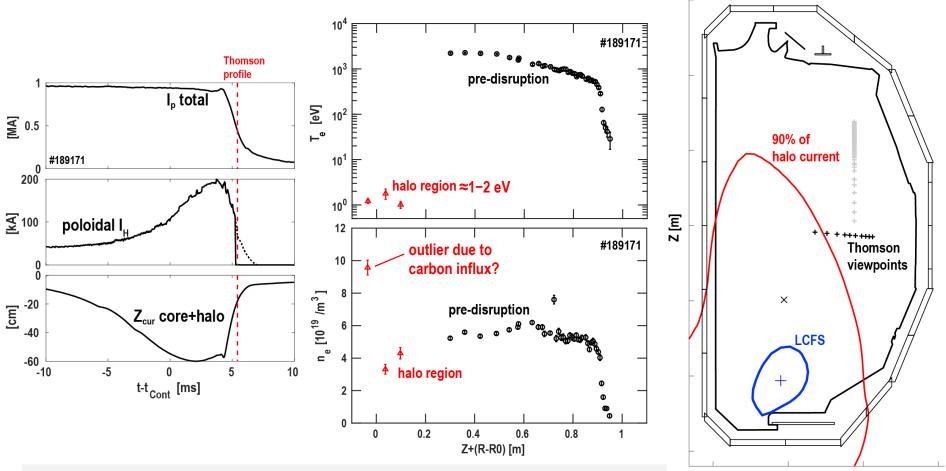
- Both VDE type I and II show about the same peak poloidal halo current
 - Halo type II is greater by 5%
 - However, halo type II is observed for 30% longer
- VDE type I has all typical signatures: slower V_Z, slower area shrinking, faster CQ rate, but lacks expected nearly constant edge q and much greater halo current
 - Edge q similarly decreasing both for VDE type I and II explains why VDE type I has about the same peak halo current $(I_{Hpol} = I_{Htor}/q)$
 - Target plasma experiencing TQ before it moves vertically may be required to enhance VDE I

VDE type II has different dynamics of halo width



- Width of the halo current decreases gradually for VDE I, while VDE II has clear phases with a plateau once plasma touches the vessel
 - Halo width here is the average distance from LCFS weighted with the halo current
- Both type I and type II VDE show about the same carbon influx as evidenced by filterscopes
 - Though unsaturated signals are available only for the floor region

Temperature of the halo region during type I VDE ('resistive') is about 1-2 eV

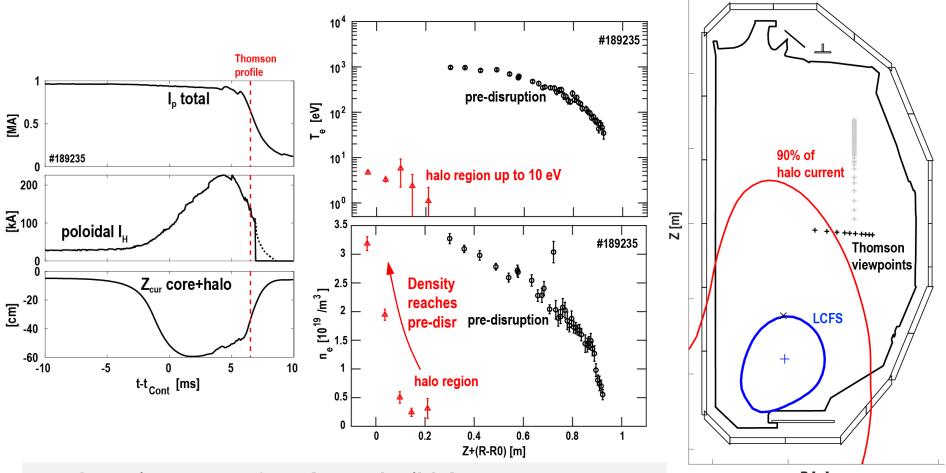


- Halo region $T_e \approx 1-2 \text{ eV}$ (reproducible)
- Halo region $\mathbf{n}_{\mathbf{e}}$ is comparable with the pre-disruption value
- Spitzer resistivity 6e-4 (Z=1.5, T_e =1.5 eV, InA=15)



R [m]

Temperature of the halo region during type II VDE ('motion-dominated') is up to 10 eV

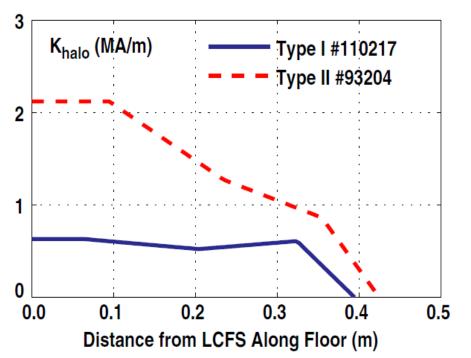


- Halo region $T_e \approx 1-10 \text{ eV}$ (reproducible)
- Halo region $\mathbf{n}_{\mathbf{e}}$ is comparable with the pre-disruption value
- Spitzer resistivity 6e-5 (Z=1.5, T_e =7 eV, InA=15)



R [m]

Temperature and halo current density profiles during VDE I and VDE II are in good agreement



Measured poloidal current distribution along the floor of the vessel at the time of peak halo current [1]

- Almost flat and low halo current density profile was measured during VDE I in contrast to peaked and elevated profile during VDE II [1]
- This is in good agreement with measured temperature profiles: flat and low during VDE I and peaked and elevated during VDE II
- These observations indicate that to correctly account I_HxB vessel forces both halo current amplitude and profile have to be considered
- Presented detailed experimental data will be valuable to improve and validate halo current models



[1] Eidietis NF 2011