# End-to-end in-pulse data analysis at ITER:

from magnetics measurements to live display

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- Provide a consistent **interpretation of the plasma state** (with uncertainties) from the measurements **during** each pulse.
- More specifically to provide accurate measurement parameters (MP) in time to prepare the next pulse in the control room.



- Magnetics synthetic diagnostic
- Data rates, raw data encoding and decoding
- Equilibrium reconstruction
- Performance for data access

- Obtain data by:
  - Mapping data from other machines/experiments
  - Synthetic diagnostic modelling
- Test the system with:
  - Realistic data rates
  - Realistic data noise generation

- Synthetic Diagnostics (SD) are used for various types of applications:
  - Design: to optimise the design and performance of the real diagnostic
  - Control: to support the development of control algorithms needed for the design of the Plasma Control System (PCS)
  - Physics: to support the physics interpretation and analysis
- In all these contexts, ITER uses the IMAS standard and further tools (also planned for the in-pulse analysis) like:
  - Persistent actors (Muscle3)
  - Bayesian frameworks (IDA and Minerva)

- Starting with a discharge scenario (eg, from JINTRAC, ASTRA, DINA, ...)
- Go back and re-create the raw diagnostic measurements for that scenario
- The first step is the magnetic measurements
- From there, we can reconstruct a plasma equilibrium
- And from an equilibrium most diagnostics and plasma parameters can be inferred
- And compared with original scenario data

#### **Synthetic Diagnostics for Magnetic Reconstruction**



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#### List of signals from the magnetic diagnostic

						-
	name	identifier	diagnostic	number	IDS node	
AD	Partial Flux Loops	55.AD.00-MSA	saddle	131	flux_loop	
AE	Continuous Flux Loops (Inner)	55.AE.00-MCH	saddle	40	flux_loop	
AF	Diamagnetic Loop (Main)	55.AF.00-MCL	saddle	3	flux_loop	
AH	Diamagnetic Saddles (Inner)	55.AH.00-MSA	saddle	6	flux_loop	
AI	MHD Saddles	55.AI.00-MSA	saddle	81	flux_loop	
A3	Tangential Coils (Outer)	55.A3.00-MLF	mirnov	180	b_field_pol_probe	
A4	Normal Coils (Outer)	55.A4.00-MLF	mirnov	180	b_field_pol_probe	
A5	Tangential Steady State Sensors	55.A5.00-MSS	hall	60	b_field_pol_probe	
A6	Normal Steady State Sensors	55.A6.00-MSS	hall	60	b_field_pol_probe	
AA	Tangential Coils (Inner)	55.AA.00-MLF	mirnov	144	b_field_pol_probe	
AB	Normal Coils (Inner)	55.AB.00-MLF	mirnov	72	b_field_pol_probe	
AJ	HF Sensors	55.AJ.00-MHF	mirnov	207	b_field_pol_probe	
AL	Divertor Equilibrium Sensors	55.AL.00-MLF	mirnov	12	b_field_pol_probe	
A9	Diamagnetic Compensation (Outer)	55.A9.00-MLF	mirnov	36	b_field_tor_probe_	
AC	Toroidal Coils	55.AC.00-MLF	mirnov	9	b_field_tor_probe	
AG	Diamagnetic Compensation (Inner)	55.AG.00-MLF	mirnov	6	b_field_tor_probe	
AP	Diamagnetic Compensation (Outer)	55.AP.00-MRG	rogowski_coil	358	rogowski_coil	

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- predictMagnetics:
  - read in pf\_active, pf\_passive, tf and lp to produce a magnetics IDS
  - adds consistent noise:
    - noise with a 1/f spectrum to simulate the effects of signal integrators
    - relative to signal intensity if energized, eg, std. dev. = 1% of average
    - absolute values when not energized, eg, std. dev. = 10kA
  - ready to be use as input for equilibrium reconstruction

#### **Magnetics Synthetic Diagnostic**



time [s]

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#### **Magnetics Synthetic Diagnostic**



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- 1585 signals for magnetics
  - 120 are proportional (voltages)
  - 1385 are integral (voltage and flux/field waveforms)
- From 2 MHz to 10 kHz during the pulse
- 2 MHz for 1 min pre- and post- pulse

• Currently testing:

150s @ 1kHz + 2s pre+post @ 2MHz \_\_\_\_\_ 10 GB

- Diagnostic data arrives encoded as a stream of 64-bit unsigned integers.
- To generate synthetic data we encode from floating-point doubles to 64-bit unsigned int.
- Knowing the range, we can decode to floating-point doubles.

$$x_{dec} = (x_{enc} + f_{min}) \times \frac{\Delta f}{\Delta R} = x_{enc} \times \frac{\Delta f}{\Delta R} + f_{min} \times \frac{\Delta f}{\Delta R}$$
  
with:  
$$\Delta f: \text{ final range} = f_{max} - f_{min}$$
  
Scaling Offset  
$$\Delta R: \text{ DAO range} = 2^{N} - 1$$

- Using EFIT++.
- Needs:
  - wall, pf\_passive: static data only, from Machine Description
  - pf\_active, tf, magnetics: static data (MD) and dynamic data (from scenario simulation).

#### **Equilibrium reconstruction**

![](_page_14_Figure_1.jpeg)

by L Appel @ UKAEA

#### **Data flow**

![](_page_15_Figure_1.jpeg)

#### **Timings per time point (single core)**

![](_page_16_Figure_1.jpeg)

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#### **Conclusions & future work**

Conclusions:

- Workflow created from simulation to synthetic magnetics data to equilibrium.
- Using realistic data access patterns (data decoding) and noise.
- Ready for live display in the control room.

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#### Next steps (~1 year):

- UDA+IMAS performance (XPOS ←→ SDCC) needs to improve by ~2 orders of magnitude.
- Need to implement data streaming.
- Thorough comparison with experimental data  $\rightarrow$  experimental data mapping

## Thank you!

### **Questions? Comments?**

## **Reminder on IMAS**

Integrated Modelling & Analysis Suite is the collection of physics software that will be used to support ITER operations and research as defined in the ITER Integrated Modelling Programme.

Data Model	<ul> <li>Machine independent data structures</li> <li>Can serve as code coupling interface</li> <li>Meta-data and provenance</li> </ul>				
Generic Tools	<ul> <li>Data access, storage, discovery, manipulation, visualization</li> <li>Support for simulation, management and exploitation of datasets / databases</li> </ul>				
Applications	<ul> <li>Independent physics codes</li> <li>Complex workflows</li> <li>Experimental data processing pipelines</li> <li>Multi-machines databases</li> </ul>				

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#### **Magnetics Synthetic Diagnostic**

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![](_page_21_Figure_5.jpeg)

![](_page_22_Figure_1.jpeg)