# Transport barriers in the drift wave model

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#### Drift wave model

The drift wave model assumes that the motion of confined plasma particles is influenced by the drift  $\mathbf{E} \times \mathbf{B}$ , in which the electric field has a fluctuating component referring to the electrostatic fluctuations defined as:

$$\tilde{\phi}(\mathbf{x},t) = \sum_{m,l,n} \phi_{m,l} \cos(m\vartheta - l\varphi - n\omega_0 t).$$
(1)

Assuming two dominant spatial modes, (M, L) and (M + 1, L), the resultant map can be described as follows

# Particle escape time





#### **Plasma Profiles**



Figure 1. Plasma profiles used. In (a) Equilibrium electric field, (b) parallel velocity and (c) safety factor

# Shearless transport barrier

The extremum point in the winding number profile  $\Omega(I)$  identifies a condition of the shearless barrier.

Figure 3. Particle escape. As the perturbation increases, the faster the particles escape.

# Transmissivity parameter spaces



$$\Omega = \lim_{n \to \infty} \frac{\chi_{n+1} - \chi_0}{n}$$



Figure 2. Phase spaces, (a) in red the shearless barrier and (b) Stickness (Partial barrier).

#### Main references

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Figure 4. Transmissivity, the fraction of escaping orbits. In the black regions, there is a total barrier.



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Figure 5. Transmissivity, the fraction of escaping orbits. In the black regions, there is a total barrier.

# Conclusions

- For non-monotonic profile of  $\mathbf{E}(I)$ , the system exhibits Shearless transport barrier
- Adding other perturbative modes increases the degree of freedom
- The perturbation modes destroy the shearless barrier
- the remnants of the shearless barrier, act as partial barriers

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