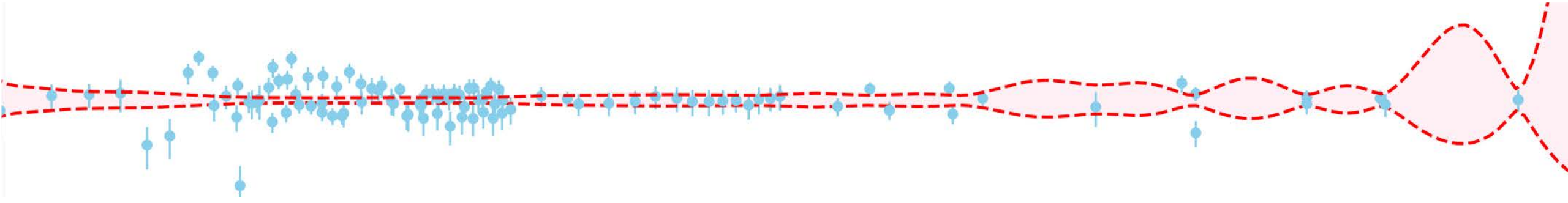


# A Comparison of Gaussian Process Regression and GLS Results for $^{235}\text{U}(n,f)$ Cross Section



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# Introduction

## ■ Nuclear data evaluation

- Model-based evaluation

TALYS, EMPIRE, CCONE, CoH, SUMMY, etc.

- Experimental data-based evaluation (non-model fit)

- GLS (Generalized Least-Squares method)  Well-established in ND community

- GPR (Gaussian Process Regression)  Popular in ML

# Basic formula of GPR (1/2)

● **Formula:**

$$\Pr(\mathbf{t}_* | \mathbf{t}) = \mathcal{N}(\mathbf{t}_* | \boldsymbol{\mu}_*, \boldsymbol{\Sigma}_*)$$

$$\left\{ \begin{array}{l} \text{Mean: } \boldsymbol{\mu}_* = \mathbf{C}_{\mathbf{xx}^*}^\top \mathbf{C}_{\mathbf{xx}}^{-1} \mathbf{t} \\ \text{Covariance: } \boldsymbol{\Sigma}_* = \mathbf{C}_{\mathbf{x}^* \mathbf{x}^*} - \mathbf{C}_{\mathbf{xx}^*}^\top \mathbf{C}_{\mathbf{xx}}^{-1} \mathbf{C}_{\mathbf{xx}^*} \end{array} \right.$$

where the partial covariance  $\mathbf{C}$  is expressed as

$$\left\{ \begin{array}{l} C(x_i, x_j) = \mathcal{K}(x_i, x_j) + \boxed{(dt_i)^2 \delta_{ij}} \quad \text{Normal use (white noise, w/o correlation)} \\ \quad \rightarrow C(x_i, x_j) = \mathcal{K}(x_i, x_j) + \boxed{\text{cov}(x_i, x_j)} \quad \text{Modified (w/ correlations)} \\ C(x_{*i}, x_j) = \mathcal{K}(x_{*i}, x_j) \\ C(x_{*i}, x_{*j}) = \mathcal{K}(x_{*i}, x_{*j}) \end{array} \right.$$

To take into account experimental correlations, a noise term was modified.

# Basic formula of GPR (2/2)

- GPR uses a **kernel function**  $\mathcal{K}$  in  $\mathbf{C}$  to represent the correlation between training data.
- This study investigated results for two typical kernel functions.

## ● Kernel function

### ➤ Radial Basis Function (RBF) kernel

$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$

### ➤ Matérn 3 kernel

$$\mathcal{K}_{\text{Matern},3/2} = \sigma^2 \left(1 + \frac{\sqrt{3}}{\ell} |x_i - x_j|\right) \exp\left(-\frac{\sqrt{3}}{\ell} |x_i - x_j|\right)$$

➤ **Newly incorporated in this work**

where

$\ell$ : Length-scale parameter  
 $\sigma$ : Magnitude parameter

➤ **“Hyperparameters”**, which is optimized so that the log-evidence becomes maximum:

$$\Theta_{\text{opt}} = \underset{\Theta}{\operatorname{argmax}} [\ln p(\mathbf{t}|\Theta)]$$

➤ Log-evidence

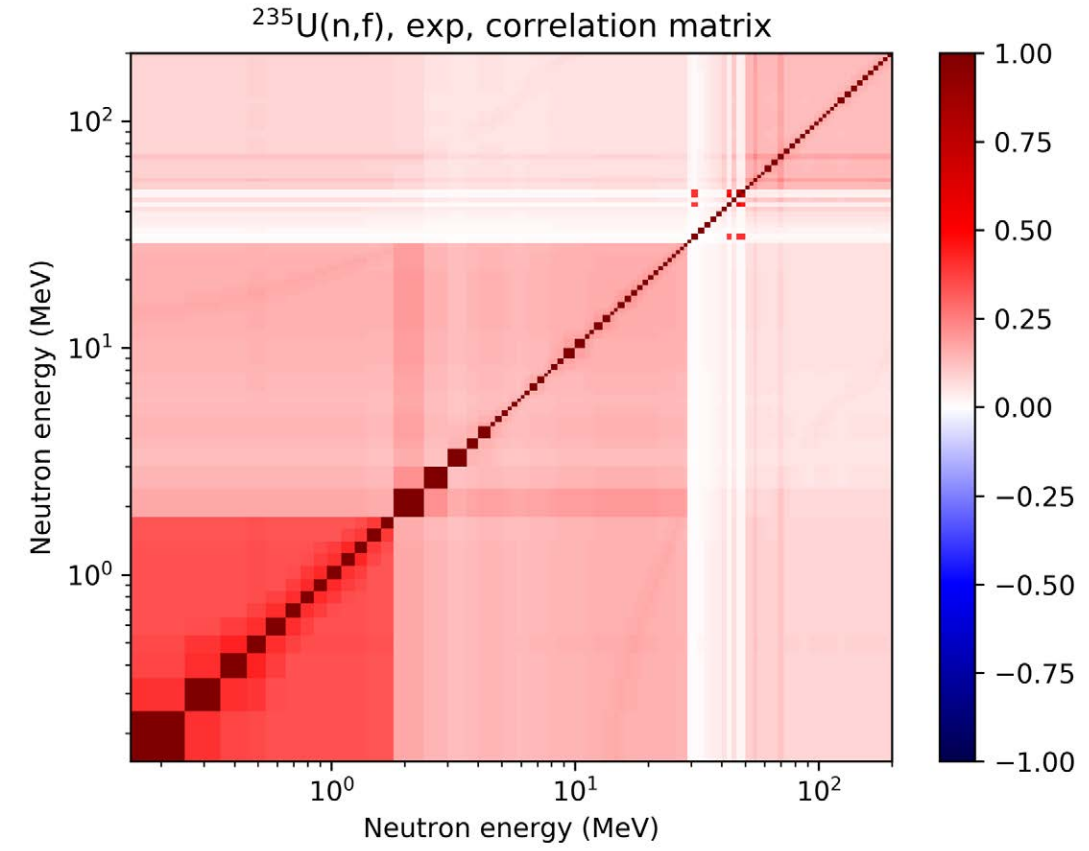
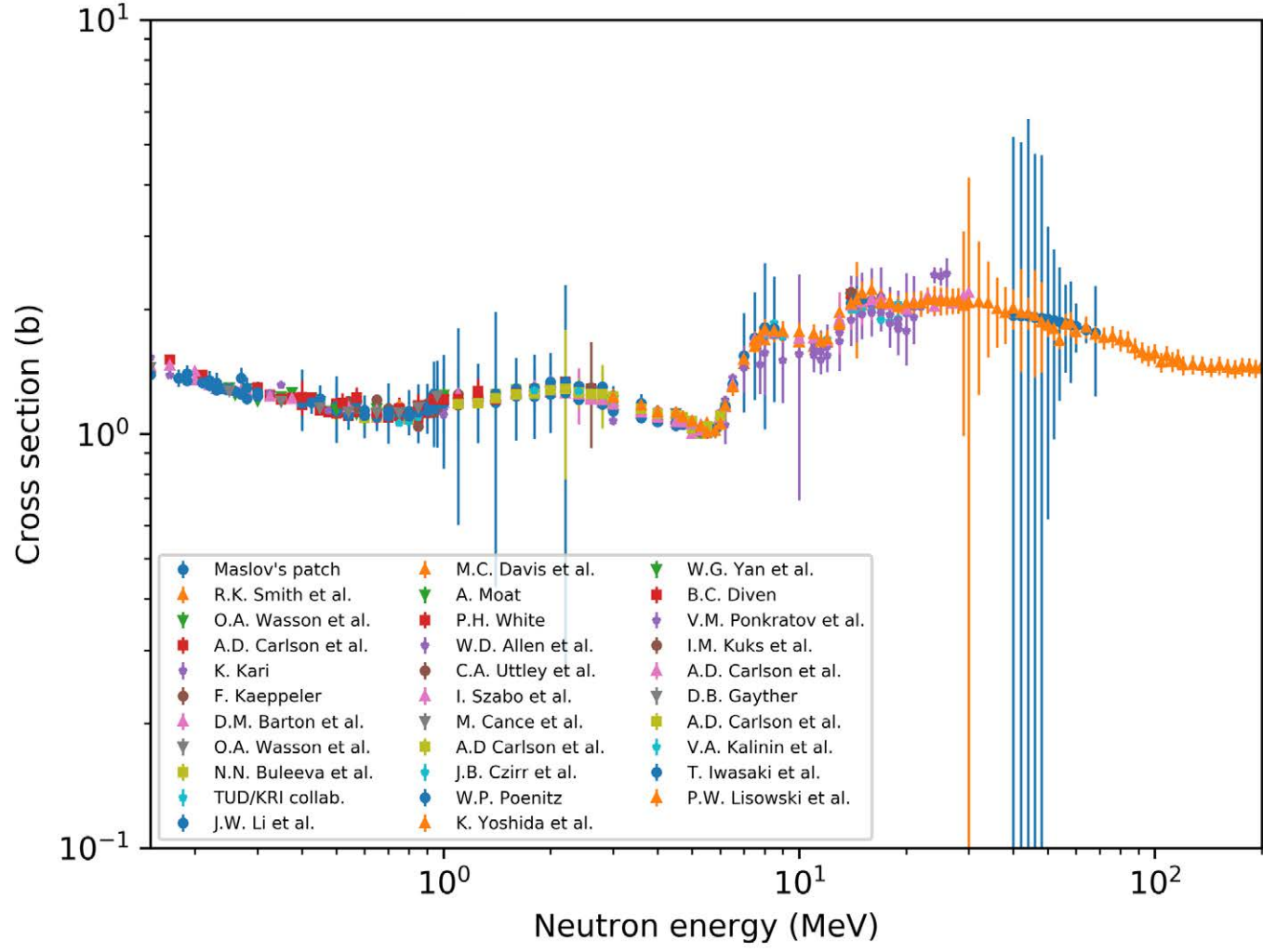
# Experimental datasets for $^{235}\text{U}(n,f)$ cross section and GLS results

# Experimental datasets for $^{235}\text{U}(n,f)$ cross section

No. of data points: 657; Energy range: 150 keV – 200 MeV

Given by Georg SCHNABEL

- u5\_absexpcov.csv
- u5\_exp\_datafram.csv

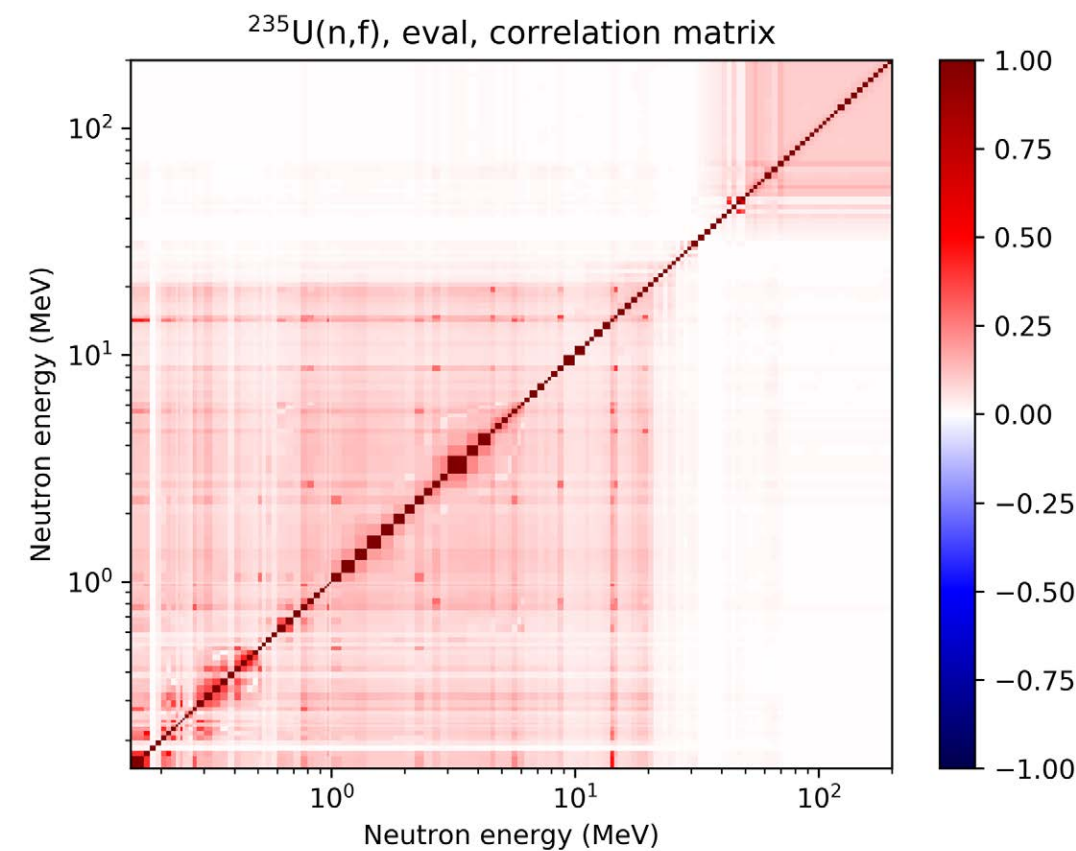
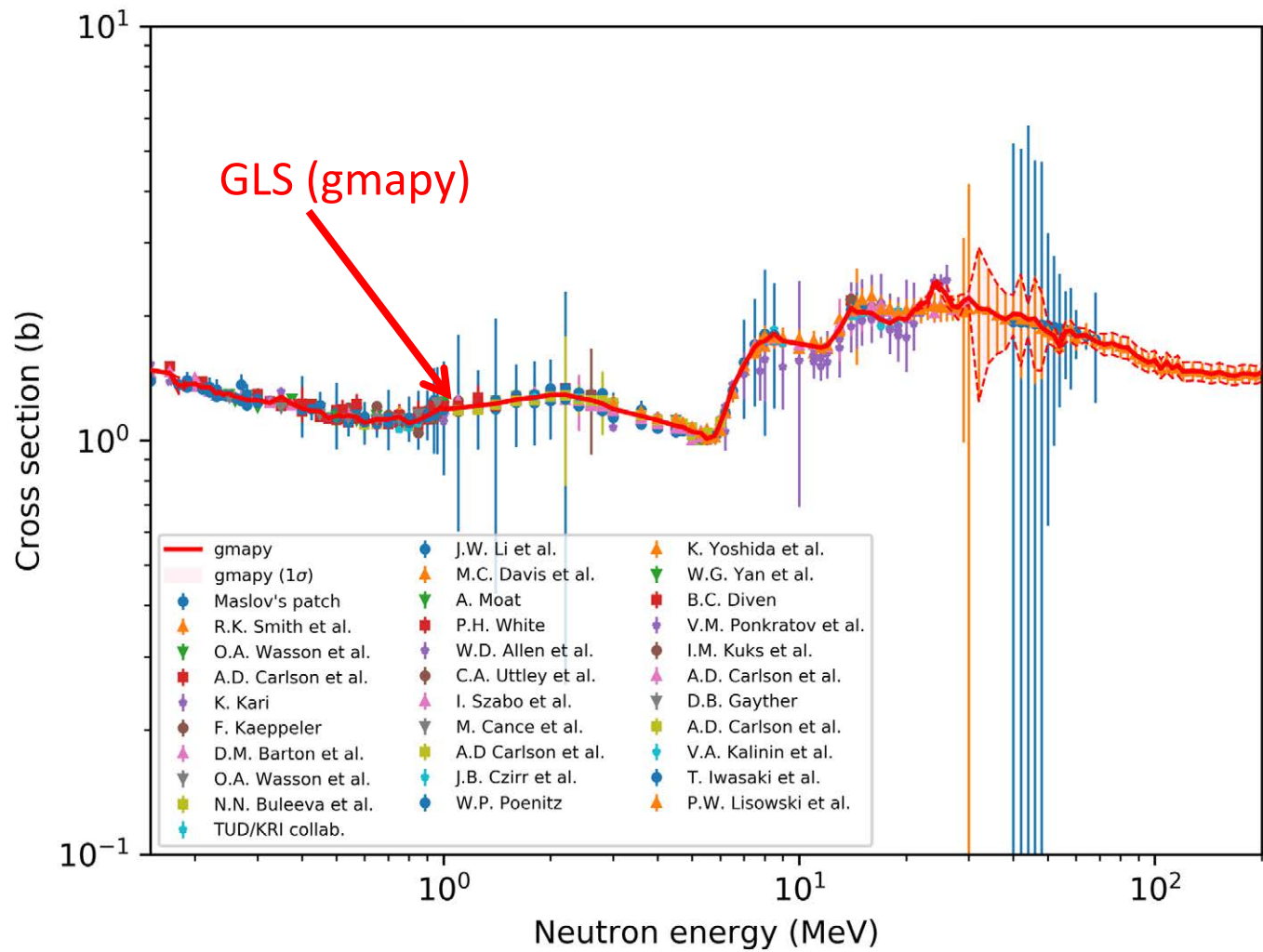


Experimental correlation matrix

# GLS results

Given by Georg SCHNABEL

- u5\_evalcovmat.csv
- u5\_eval\_dataframe.csv



Evaluated correlation matrix

gmapy: <https://github.com/IAEA-NDS/gmapy>

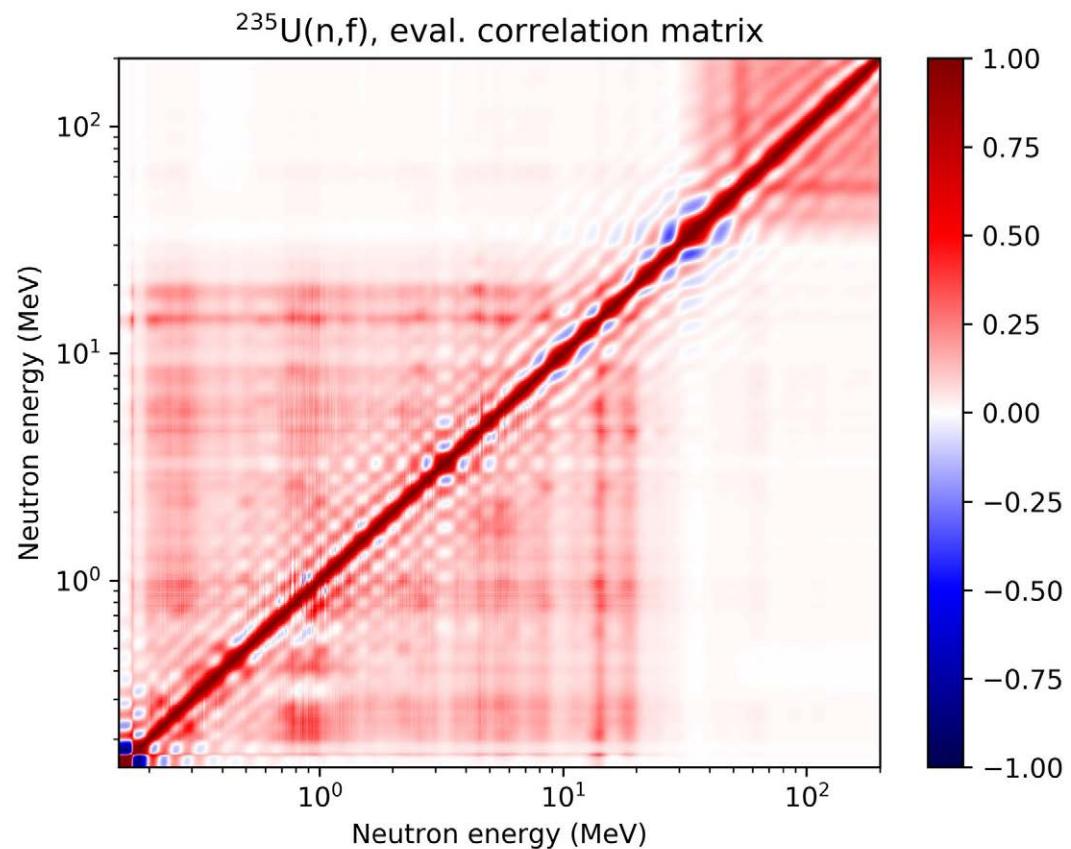
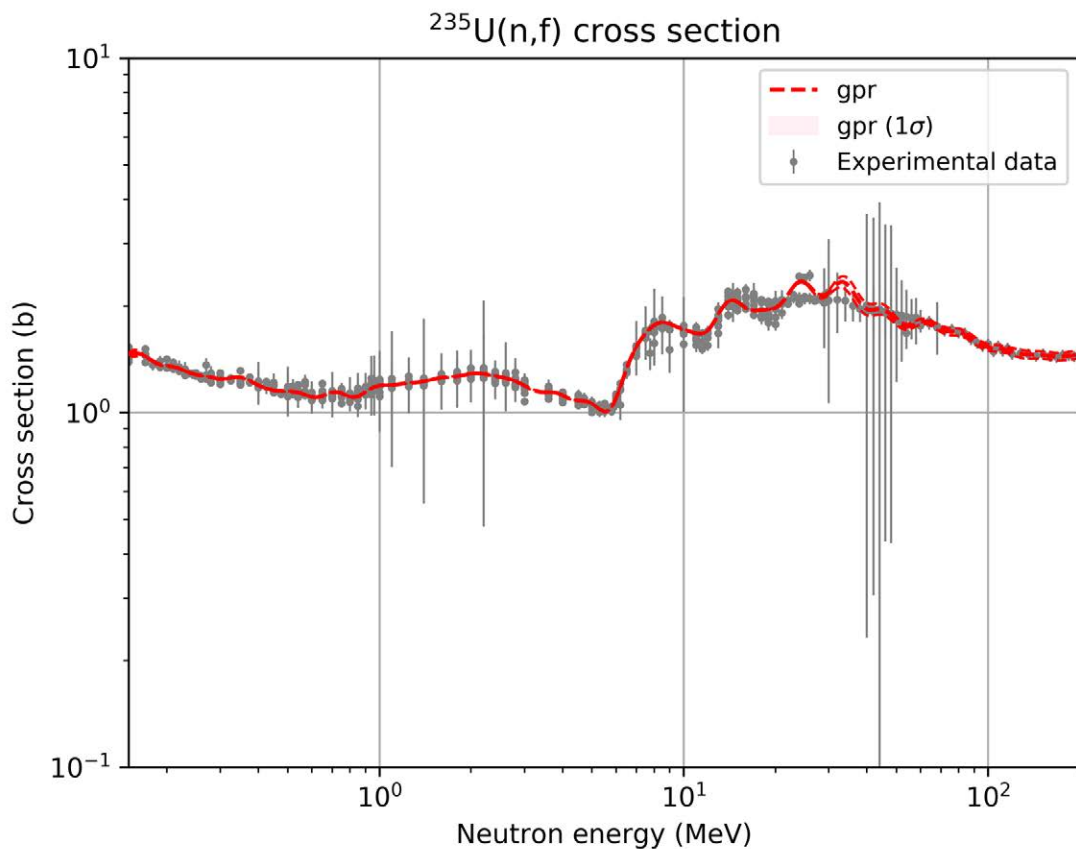


# GPR results for RBF kernel

# RBF kernel

- $\ell = 0.10$  (Length-scale parameter)

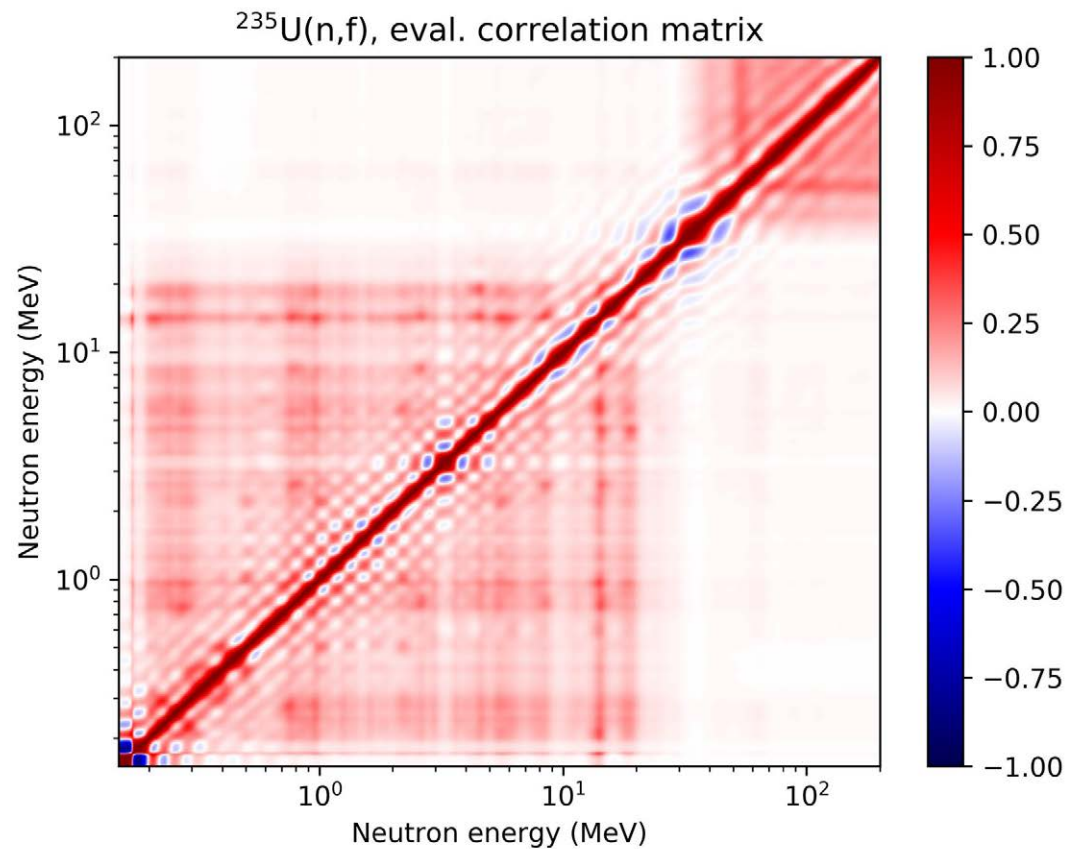
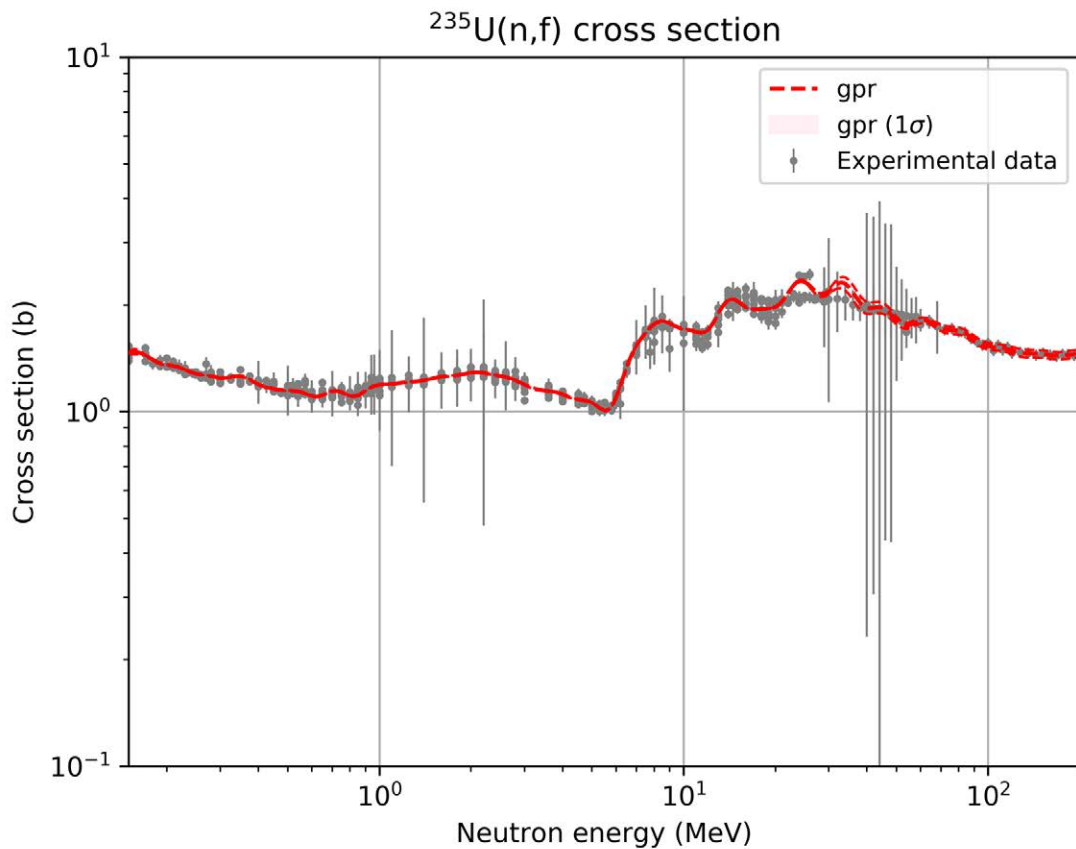
$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



# RBF kernel

- $\ell = 0.09$

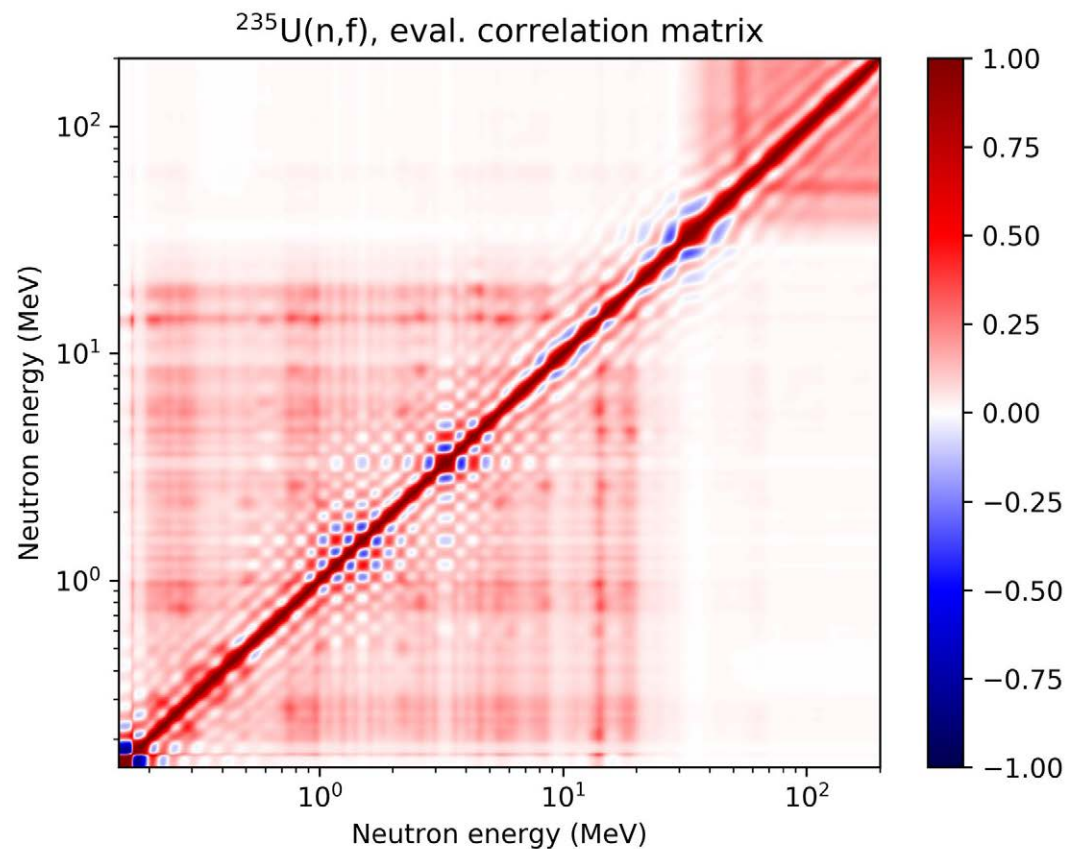
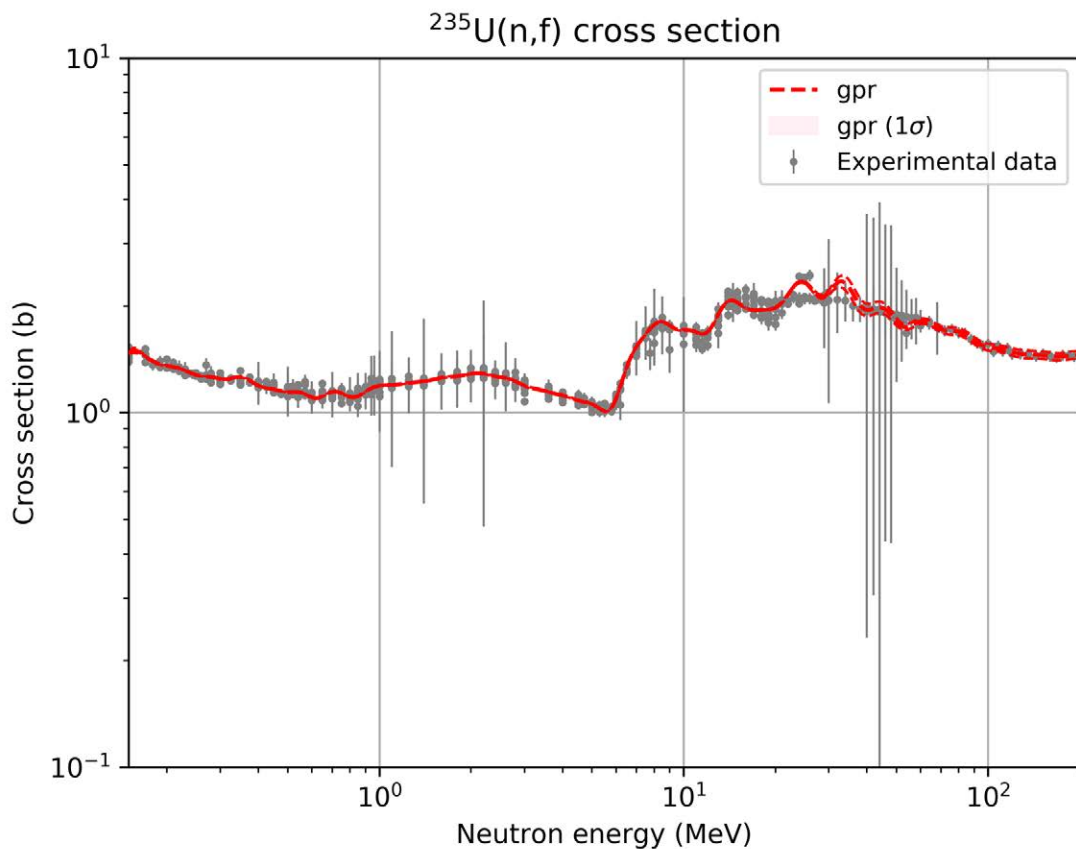
$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



# RBF kernel

- $\ell = 0.08$

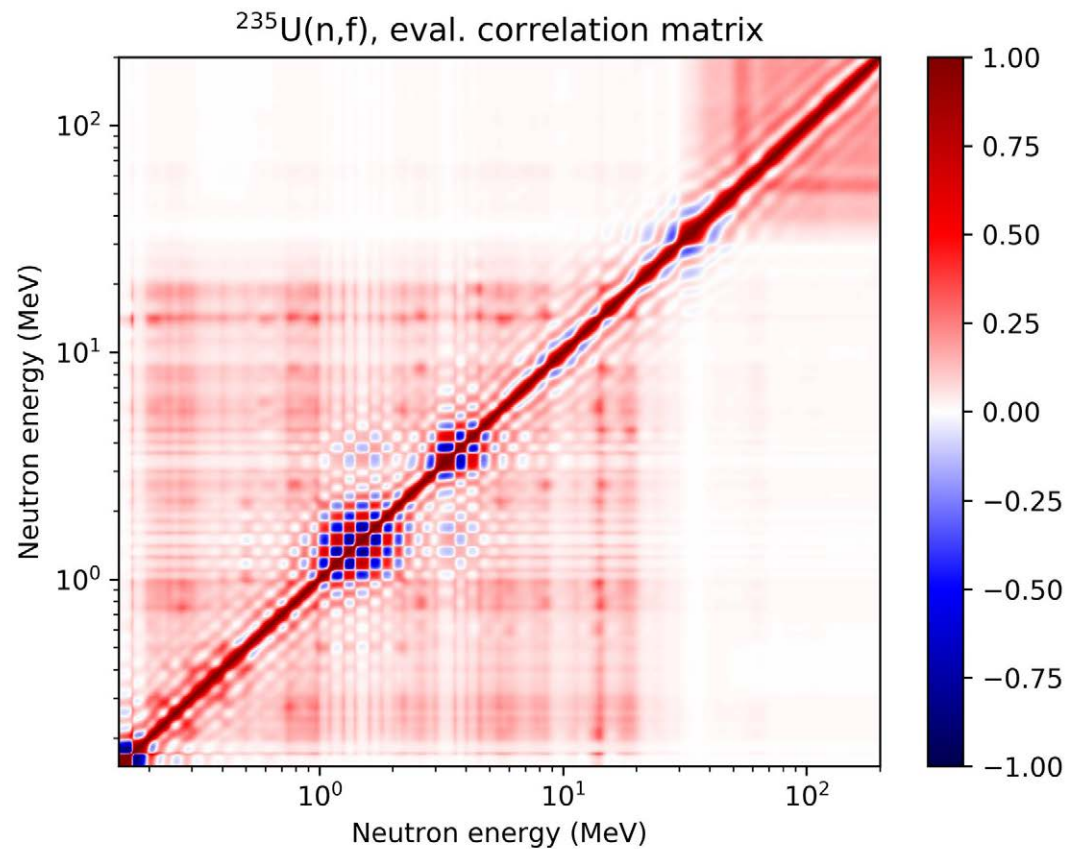
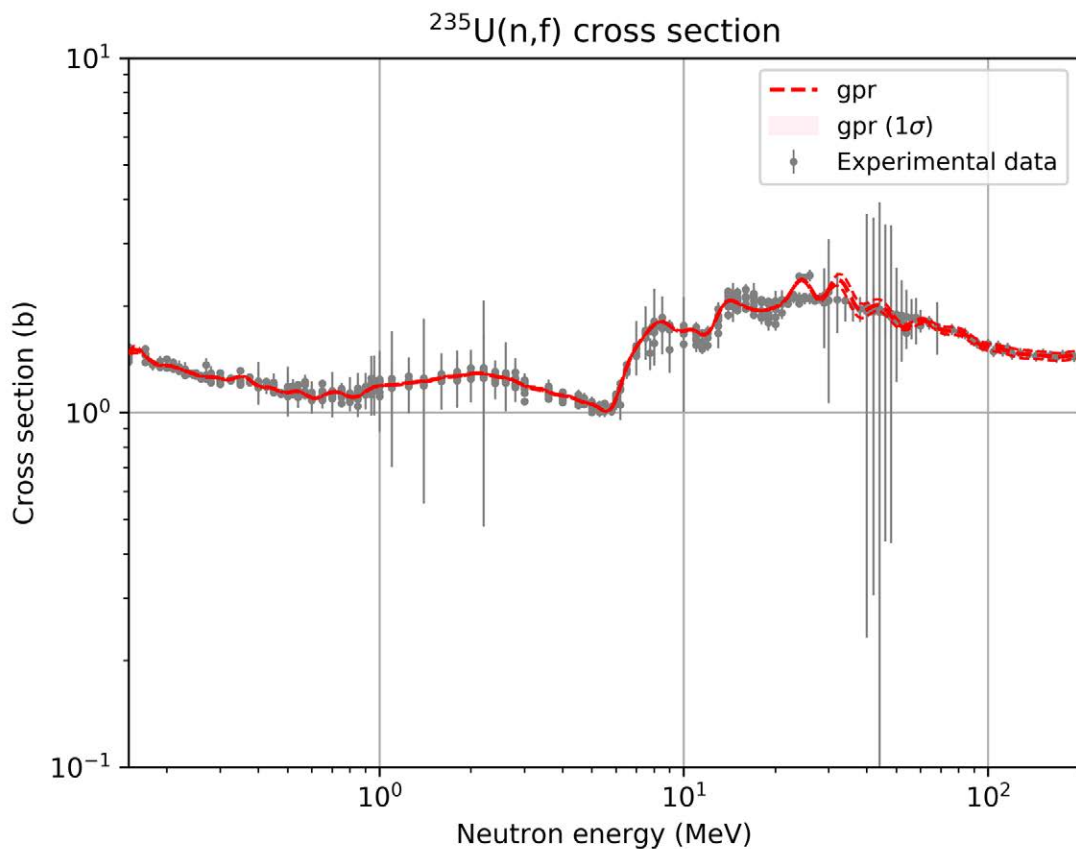
$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



# RBF kernel

- $\ell = 0.07$

$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$

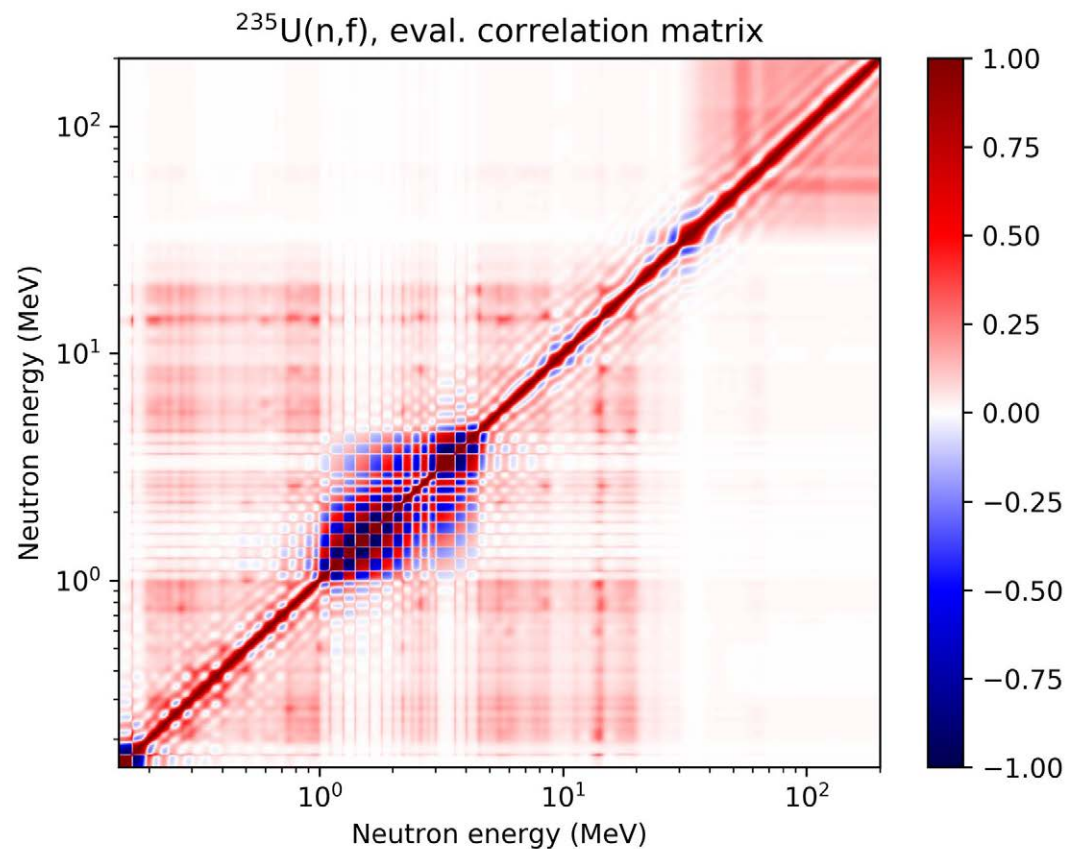
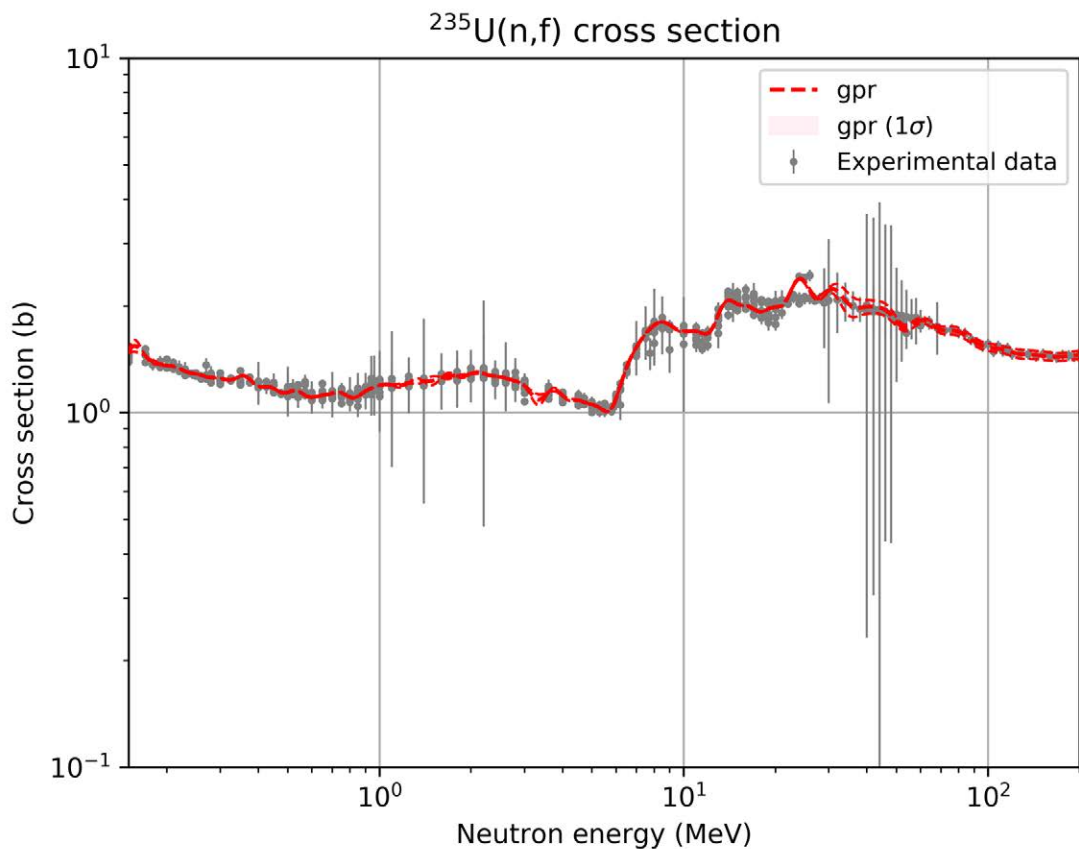




# RBF kernel

- $\ell = 0.06$

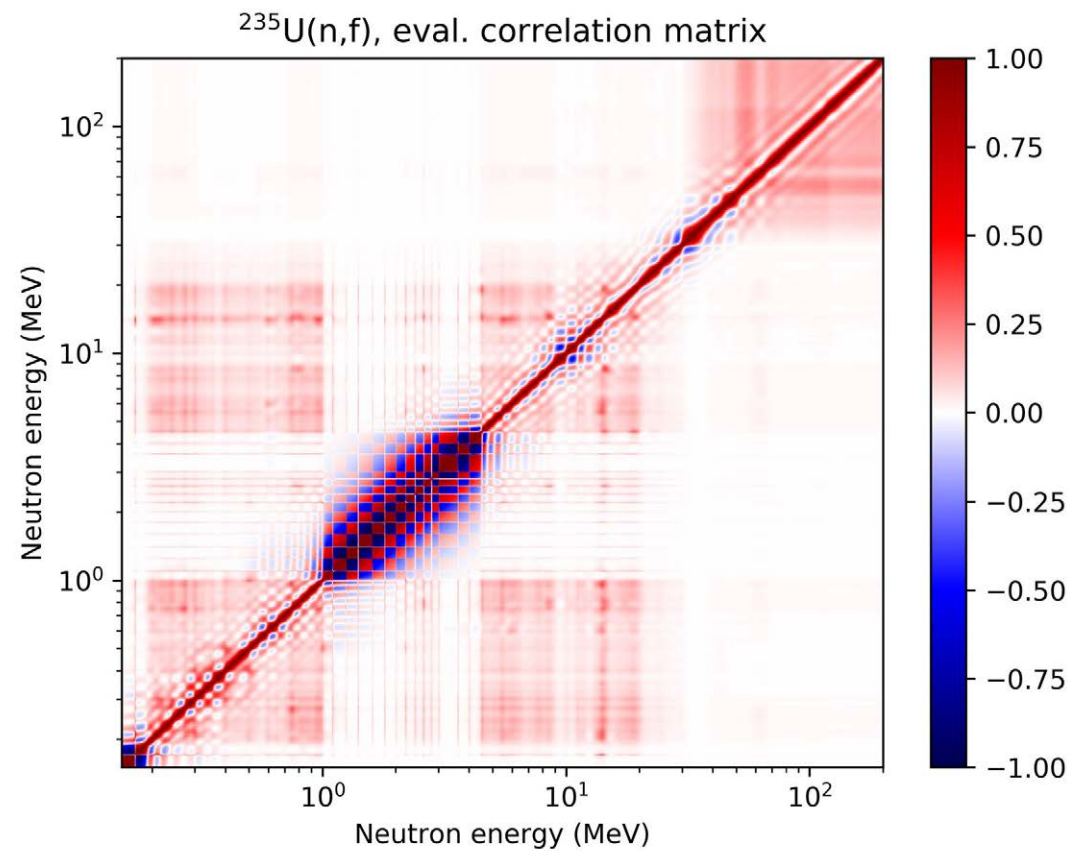
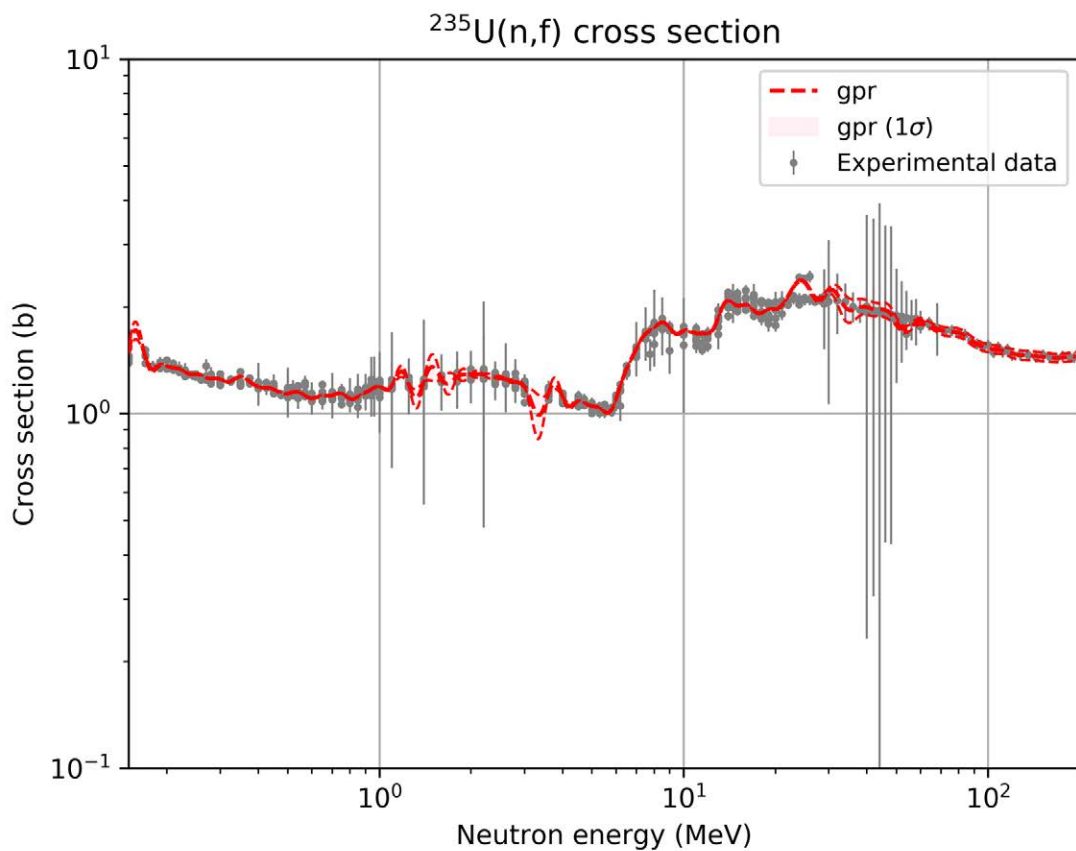
$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



# RBF kernel

- $\ell = 0.05$

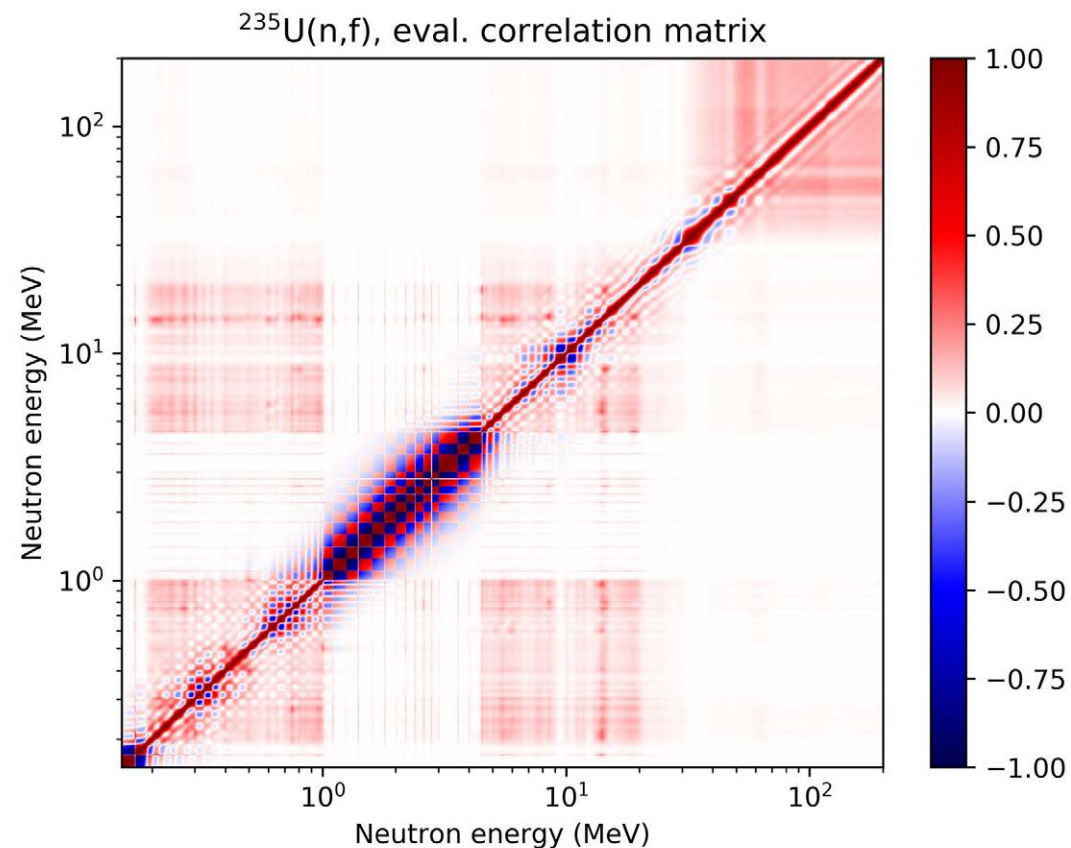
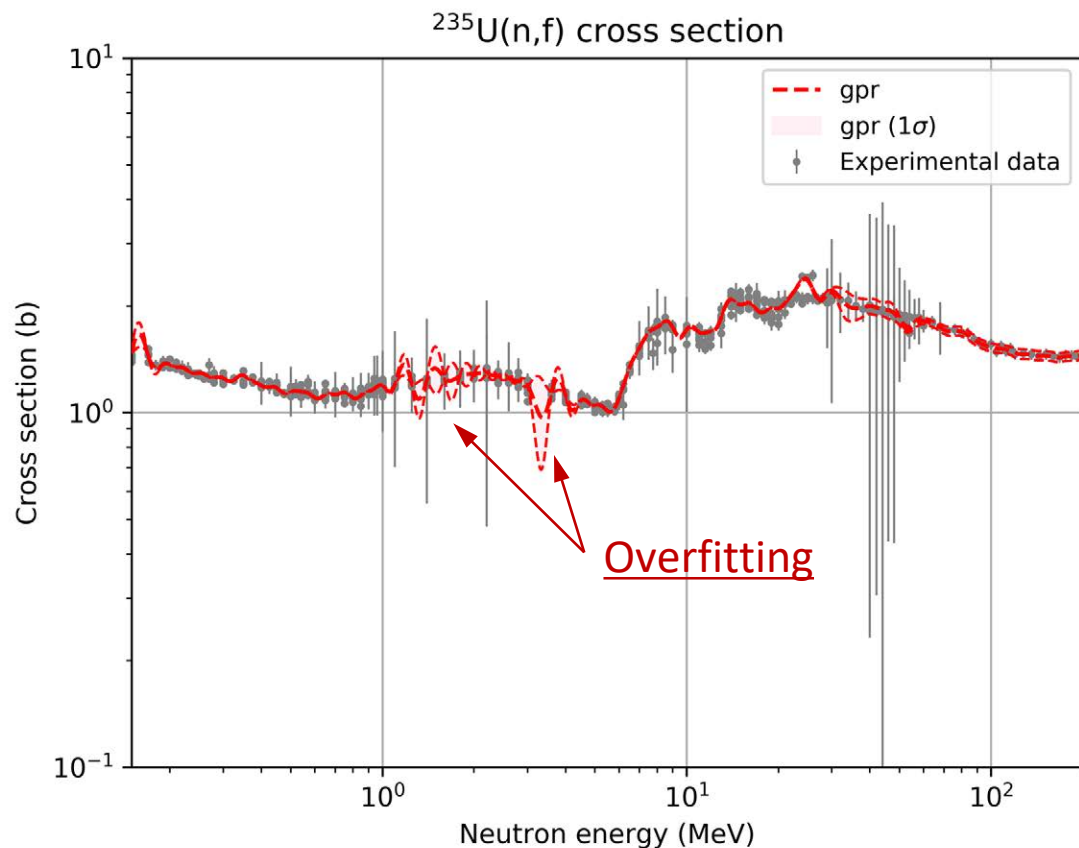
$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



# RBF kernel

- $\ell = 0.043$  (mathematically optimal)

$$\mathcal{K}_{\text{RBF}} = \sigma^2 \exp\left(-\frac{(x_i - x_j)^2}{2\ell^2}\right)$$



- Results with the RBF kernel are sensitive to hyperparameters.
- Overfitting was observed at the optimal point

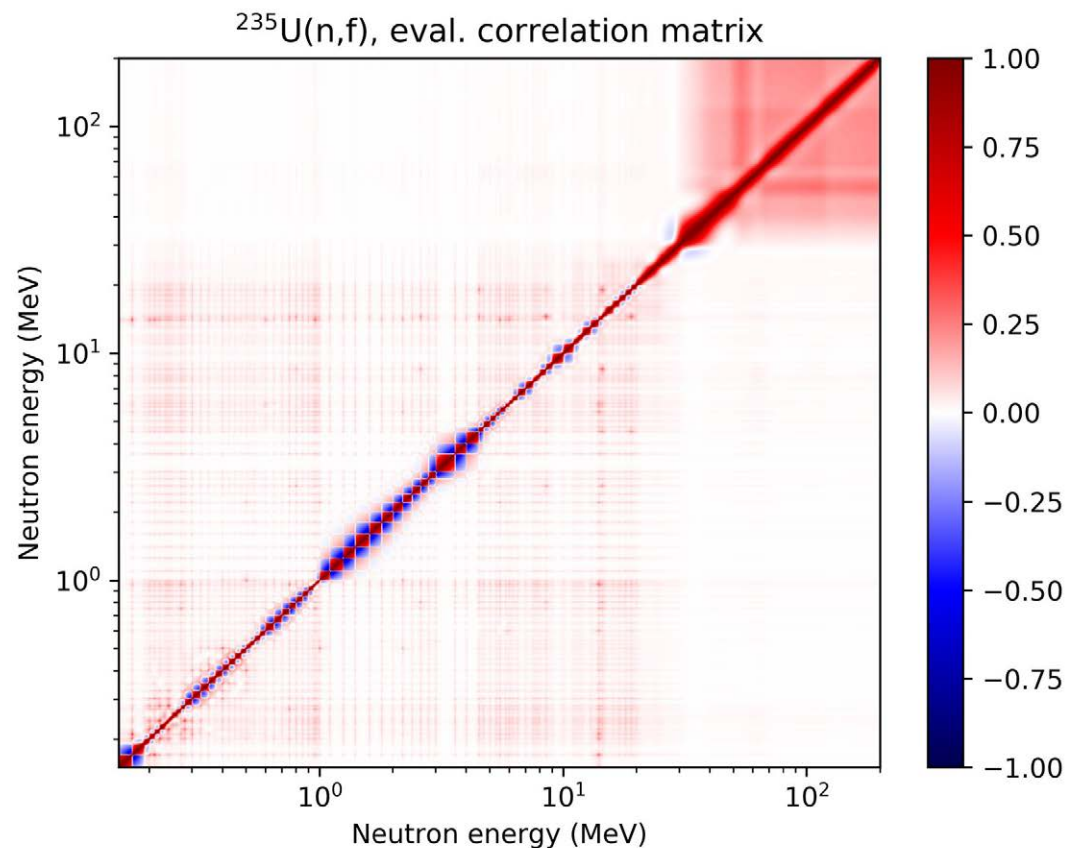
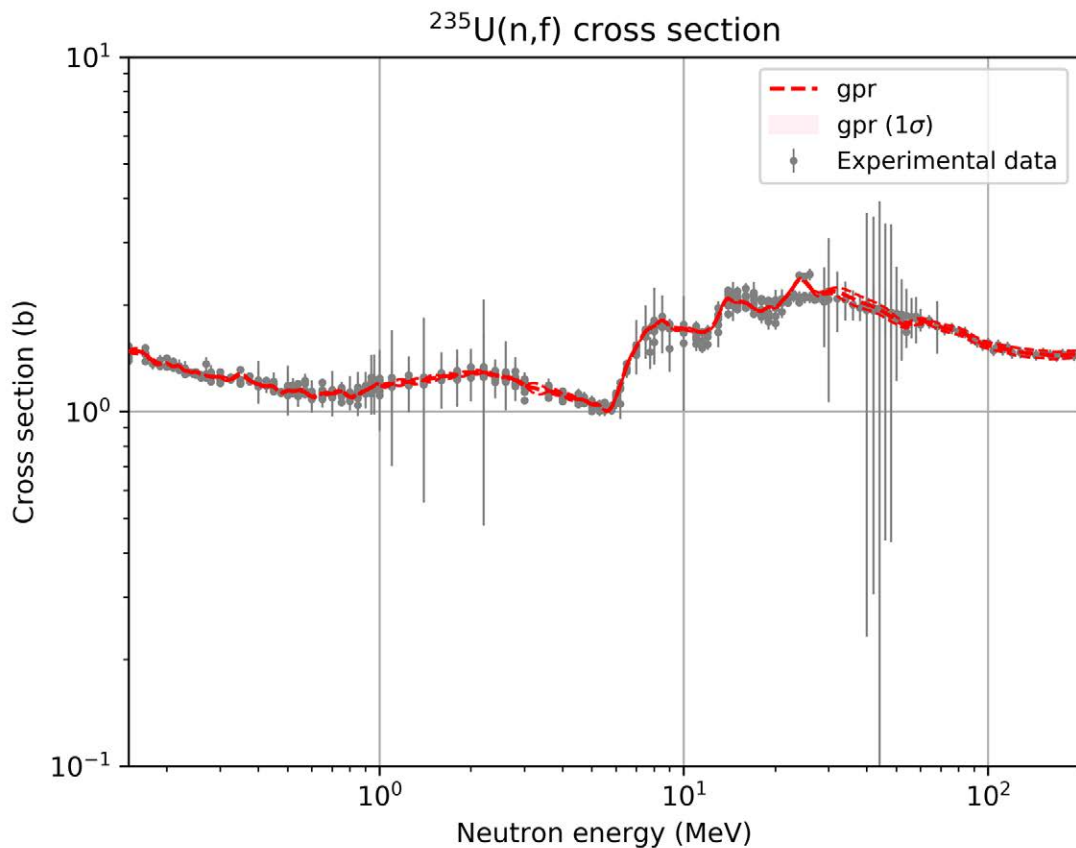


# GPR results for Matérn 3 kernel

# Matérn 3 kernel

- $\ell = 1.0$

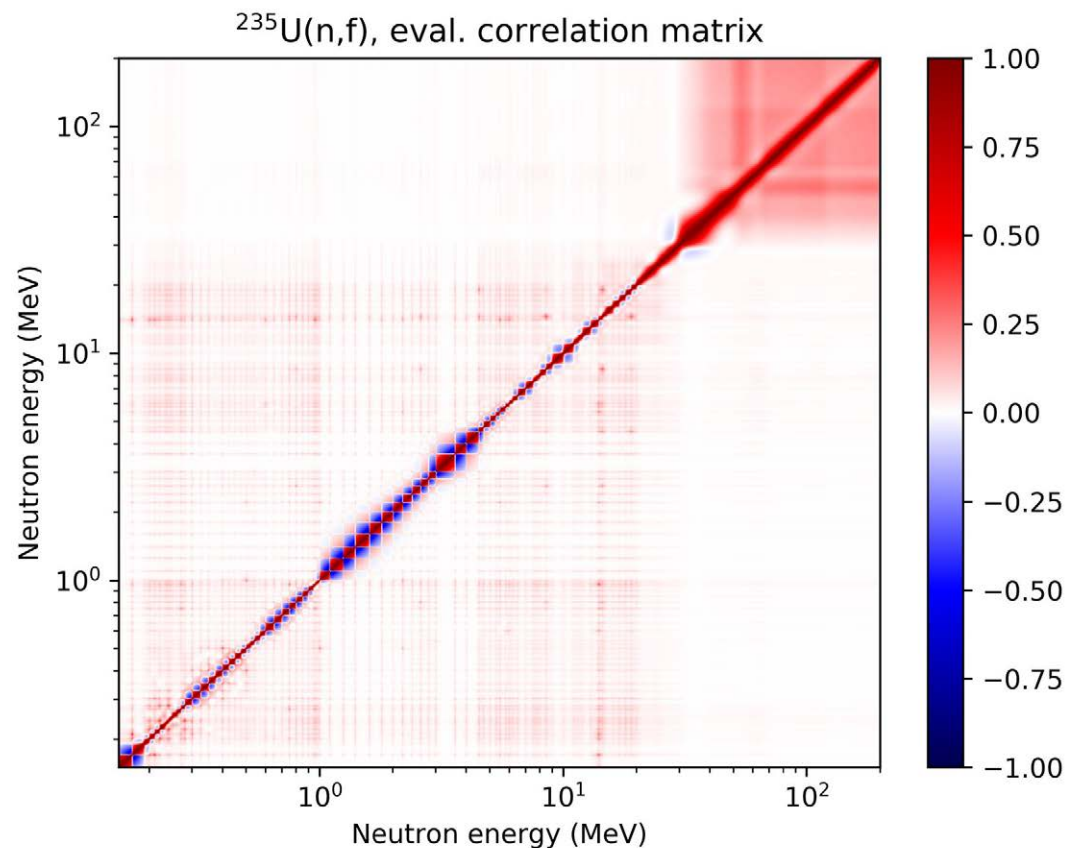
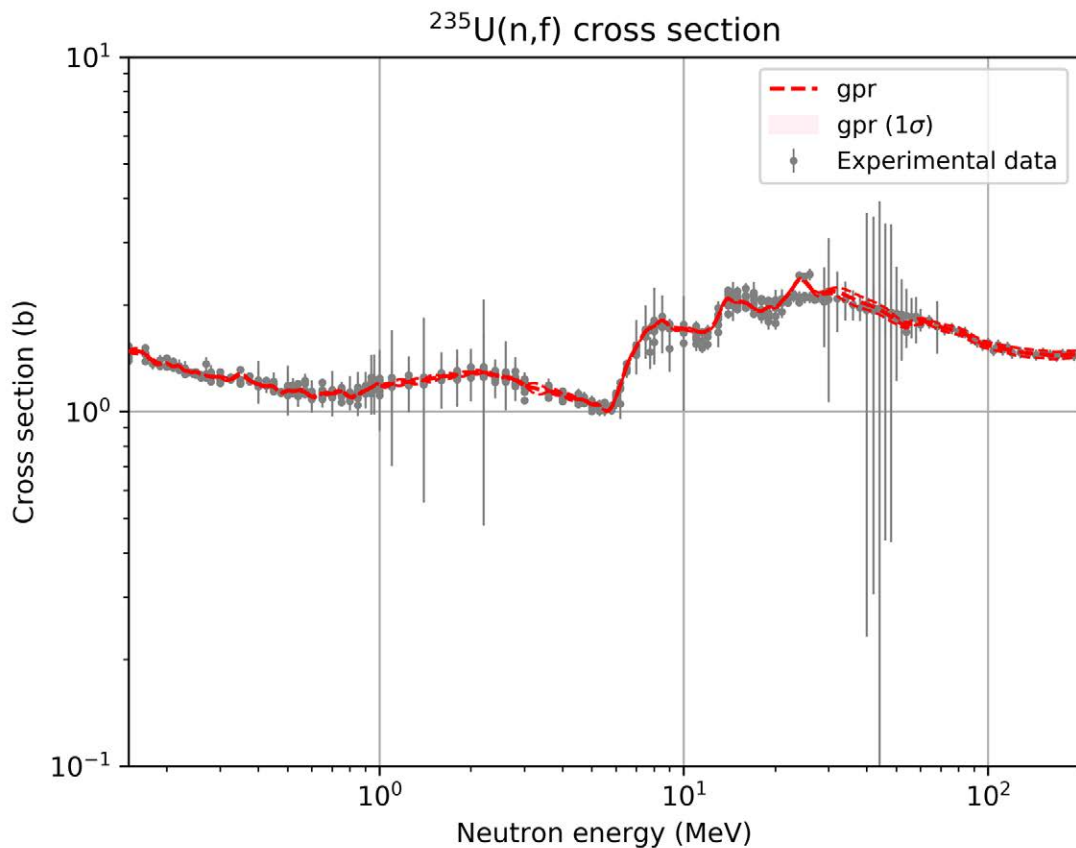
$$\kappa_{\text{Matern},3/2} = \sigma^2 \left( 1 + \frac{\sqrt{3}}{\ell} |x_i - x_j| \right) \exp \left( -\frac{\sqrt{3}}{\ell} |x_i - x_j| \right)$$



# Matérn 3 kernel

- $\ell = 0.9$

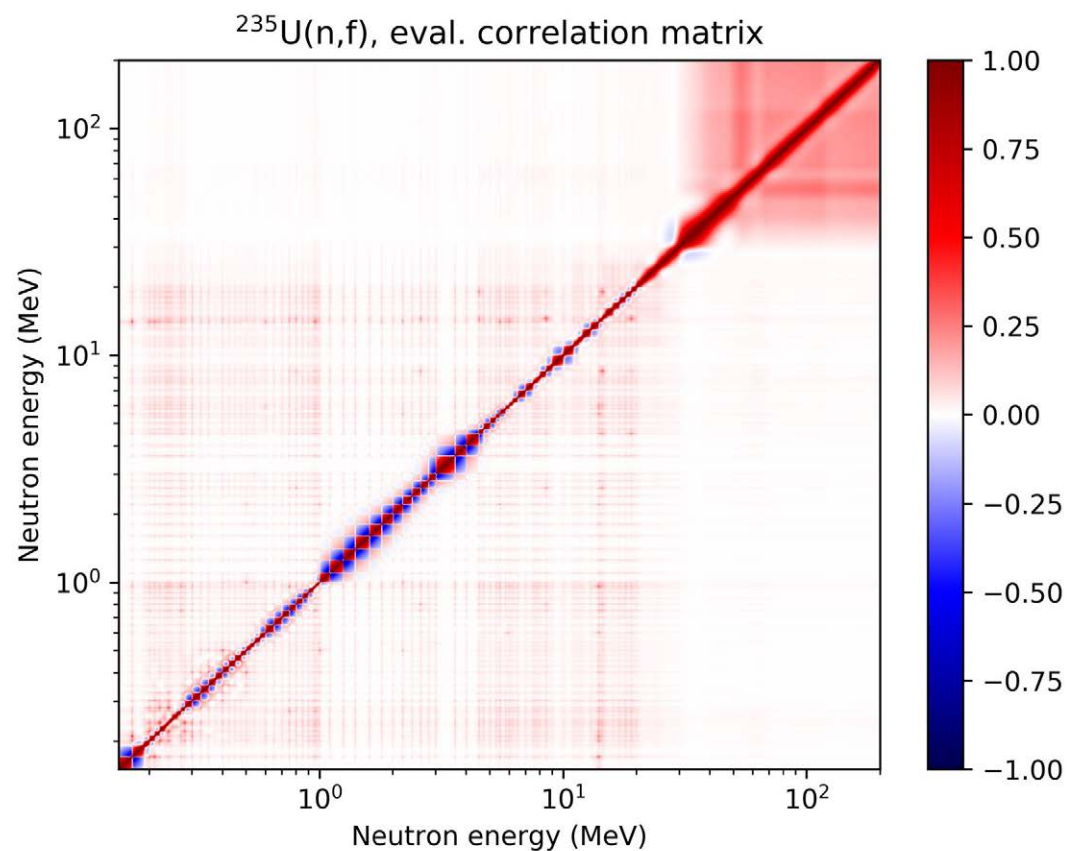
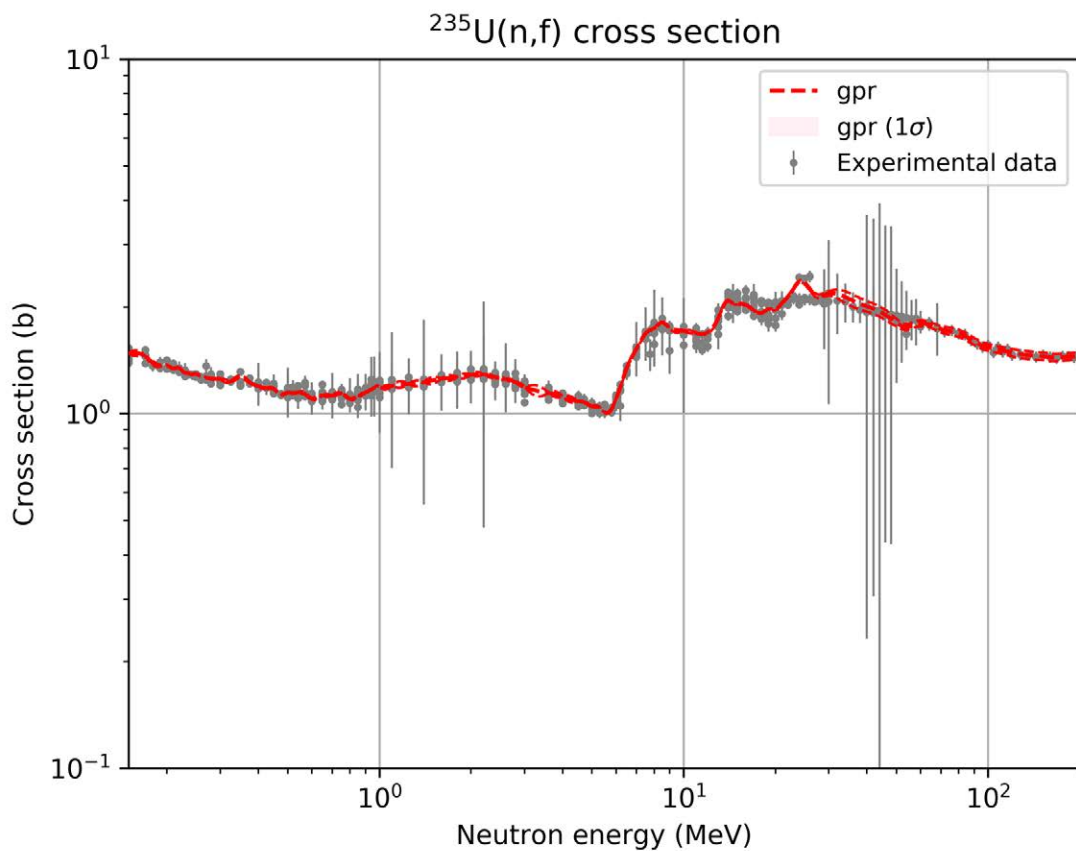
$$\kappa_{\text{Matern},3/2} = \sigma^2 \left( 1 + \frac{\sqrt{3}}{\ell} |x_i - x_j| \right) \exp \left( -\frac{\sqrt{3}}{\ell} |x_i - x_j| \right)$$



# Matérn 3 kernel

- $\ell = 0.8$

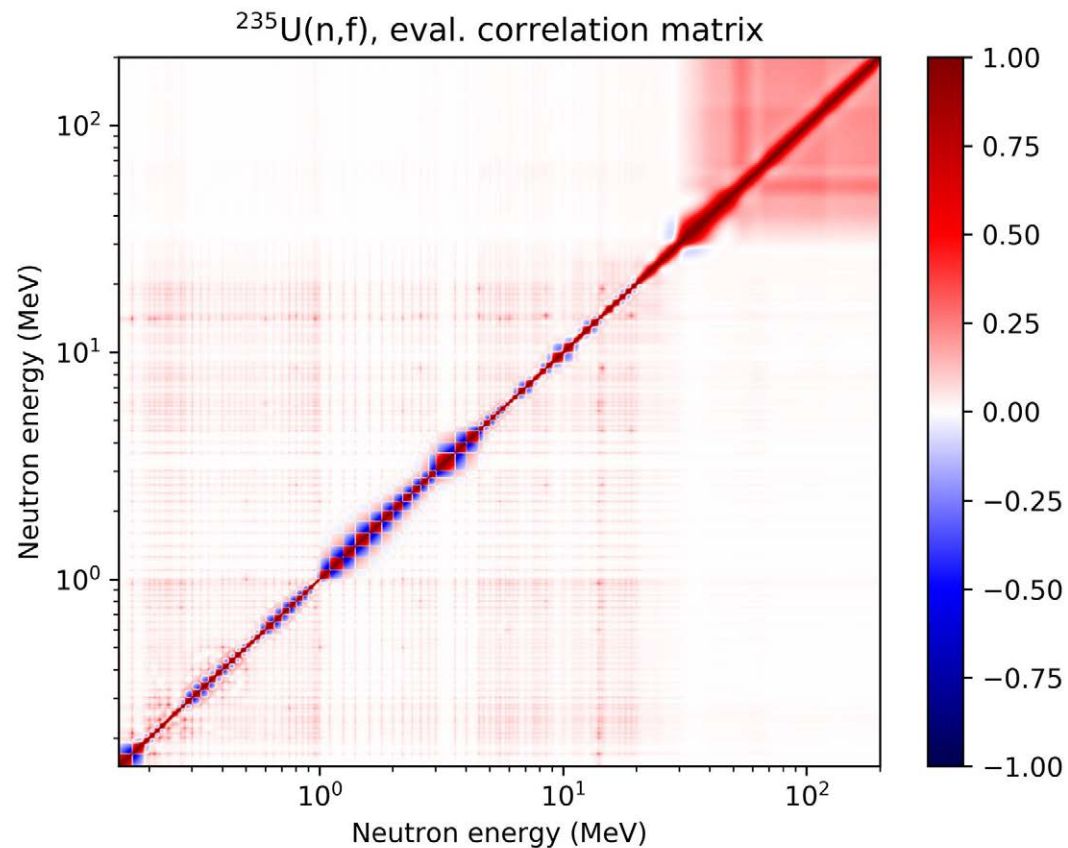
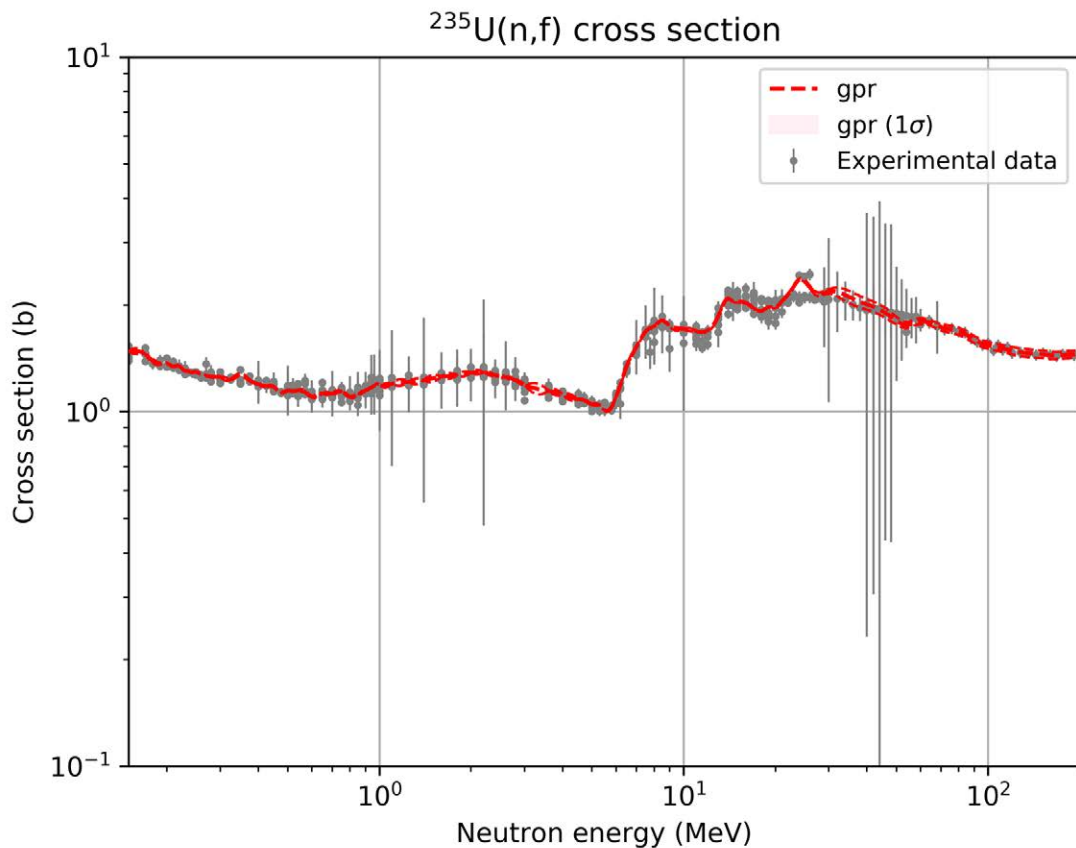
$$\kappa_{\text{Matern},3/2} = \sigma^2 \left( 1 + \frac{\sqrt{3}}{\ell} |x_i - x_j| \right) \exp \left( -\frac{\sqrt{3}}{\ell} |x_i - x_j| \right)$$



# Matérn 3 kernel

- $\ell = 0.7$

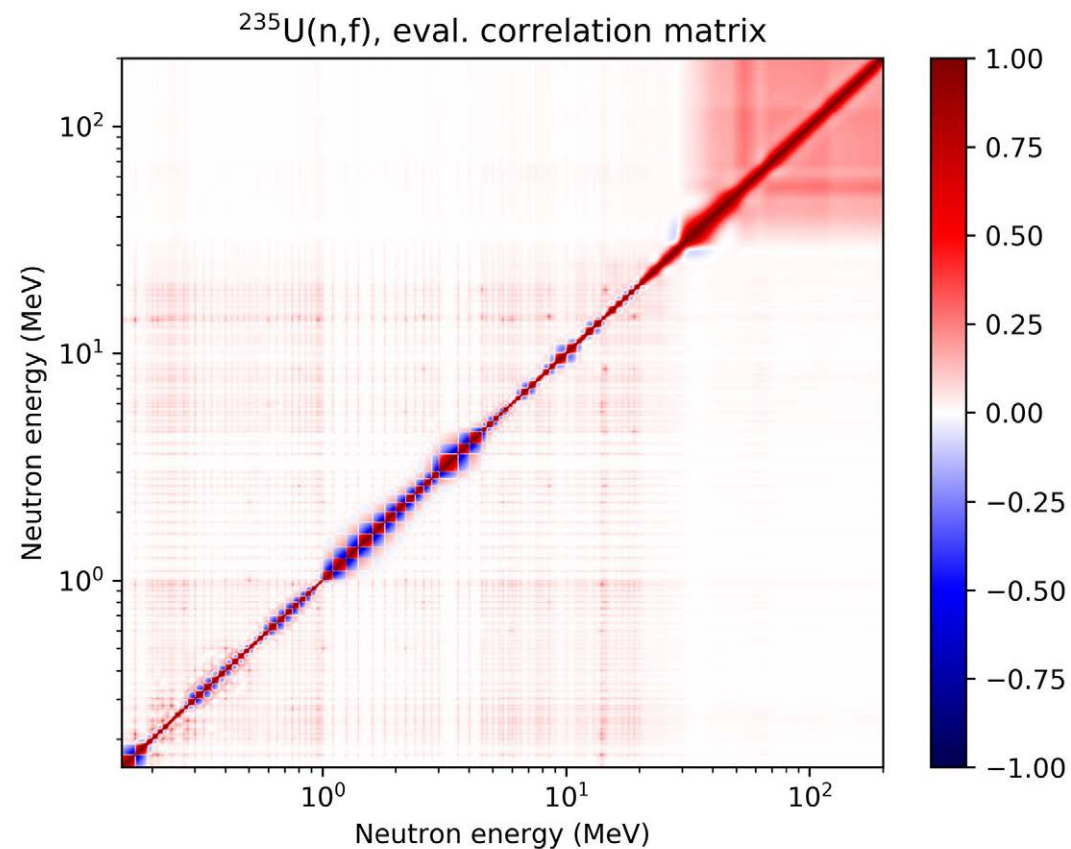
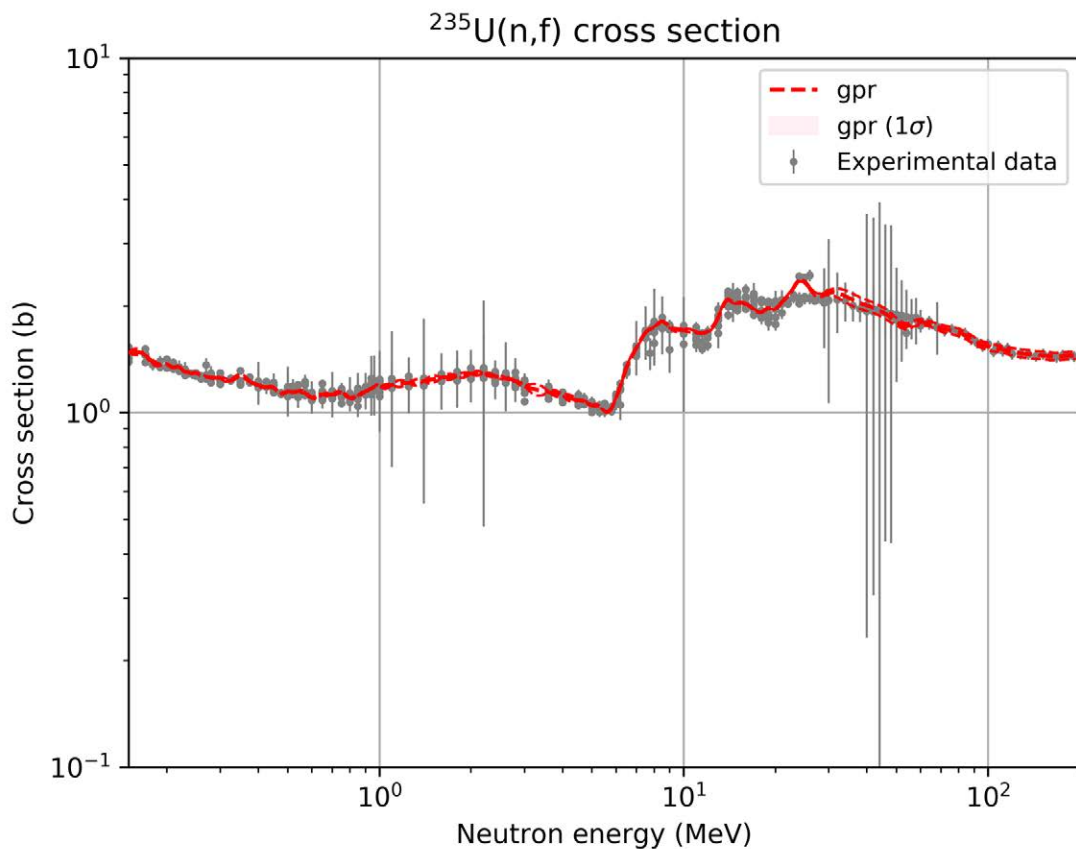
$$\kappa_{\text{Matern},3/2} = \sigma^2 \left( 1 + \frac{\sqrt{3}}{\ell} |x_i - x_j| \right) \exp \left( -\frac{\sqrt{3}}{\ell} |x_i - x_j| \right)$$



# Matérn 3 kernel

- $\ell = 0.41$  (mathematically optimal)

$$\kappa_{\text{Matern},3/2} = \sigma^2 \left( 1 + \frac{\sqrt{3}}{\ell} |x_i - x_j| \right) \exp \left( -\frac{\sqrt{3}}{\ell} |x_i - x_j| \right)$$



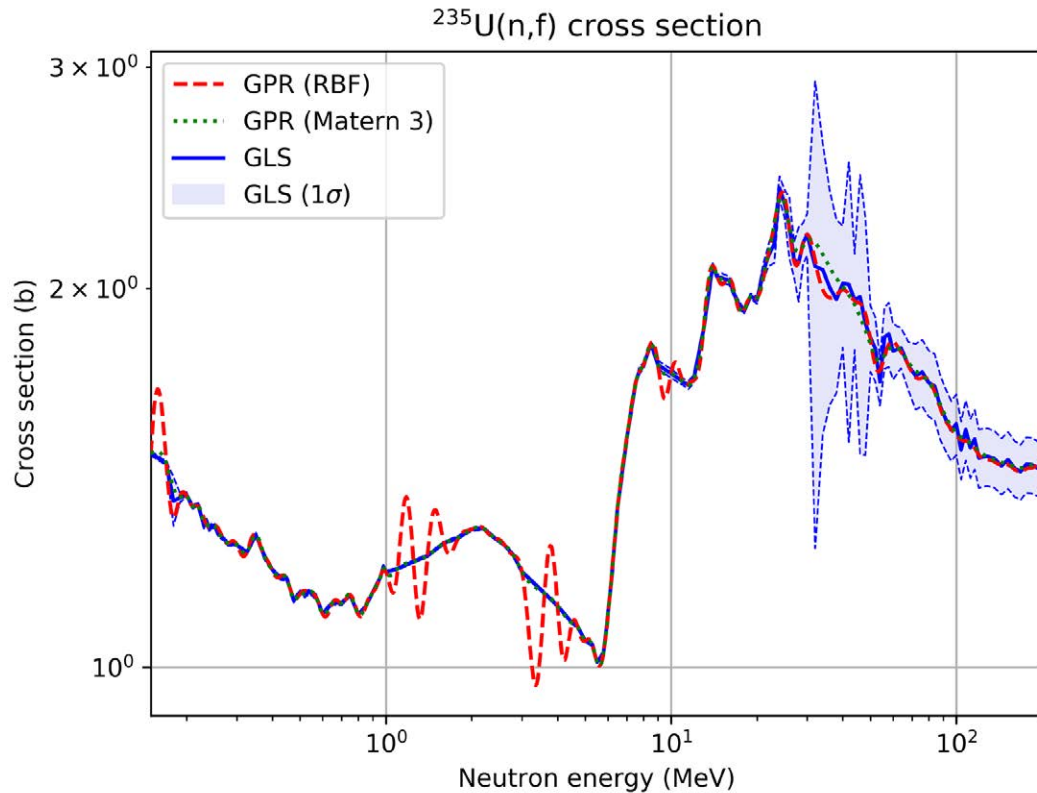
- Results with the Matérn 3 kernel are less sensitive to hyperparameters.

# Comparison with GLS results

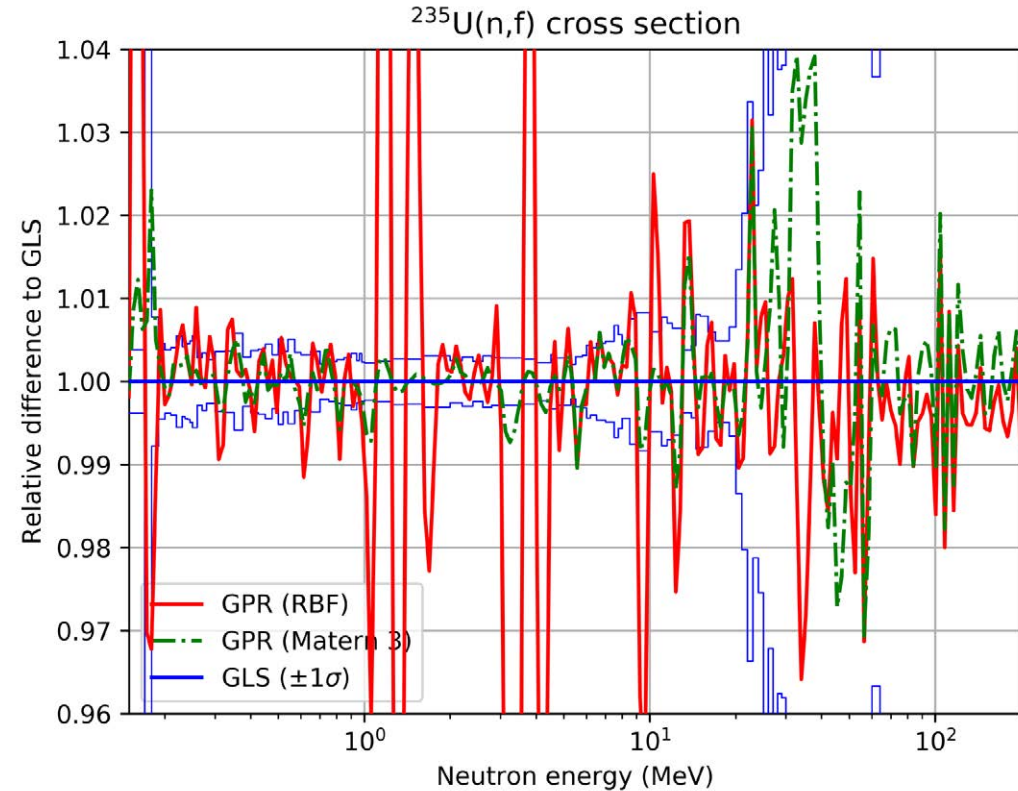


# Comparison with GLS results

## ● Cross section



## ● Relative difference

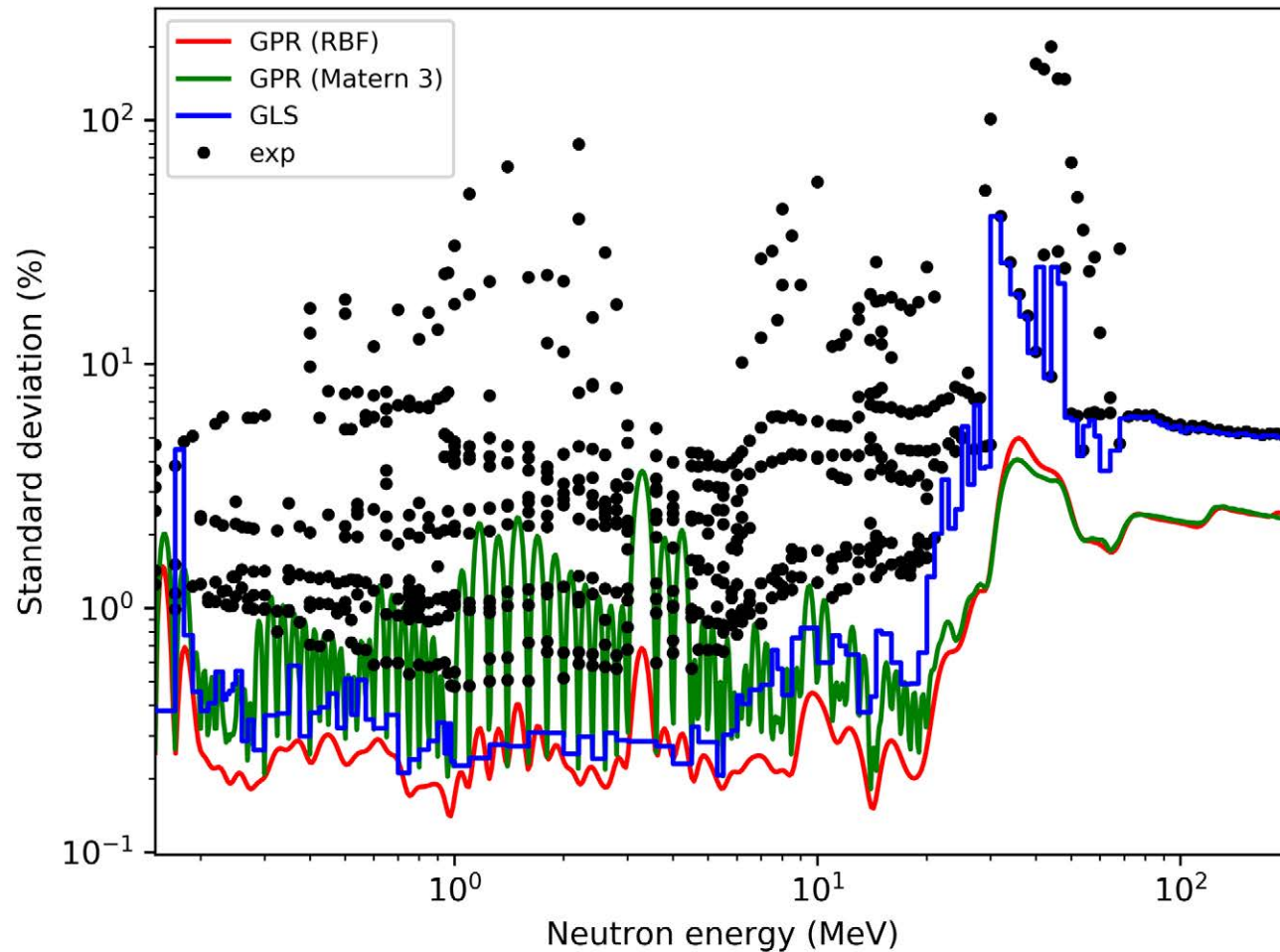



- GPR with the Matérn 3 kernel gives more consistent results with GLS. Differences are almost within GLS  $1\sigma$  uncertainty.



# Comparison with GLS results

- Standard deviation (diagonal components of covariance matrix)

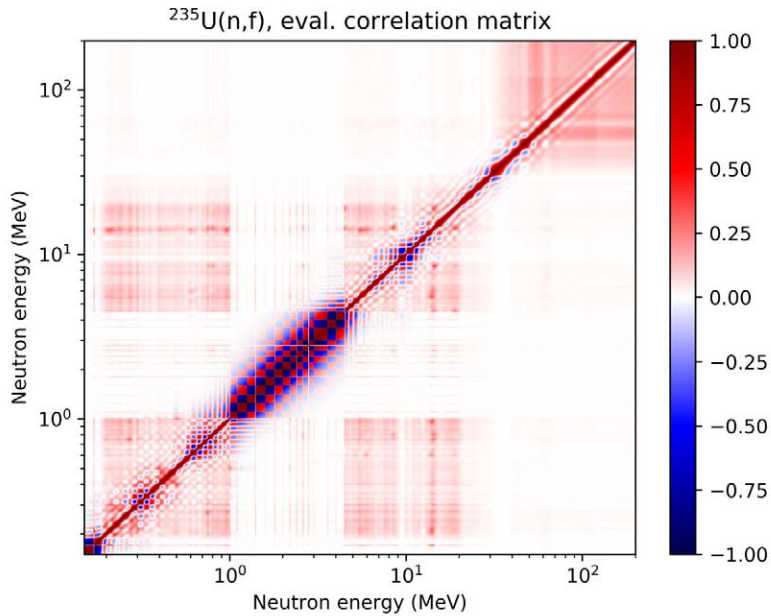


- GPR tends to give large standard deviations between experimental data points.
- Above 20 MeV, GPR gives smaller standard deviations than GLS.
- Instead, correlations are larger than GLS (next slide )

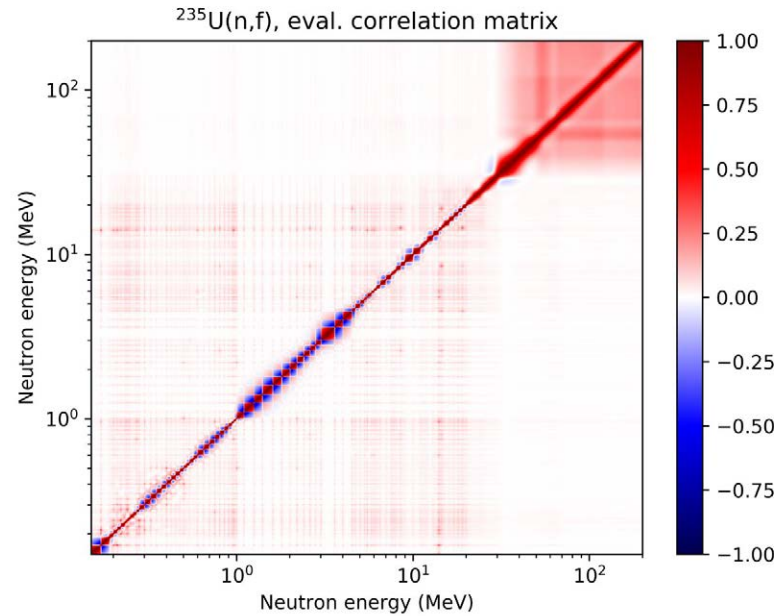
# Comparison with GLS results

## ● Correlation matrix

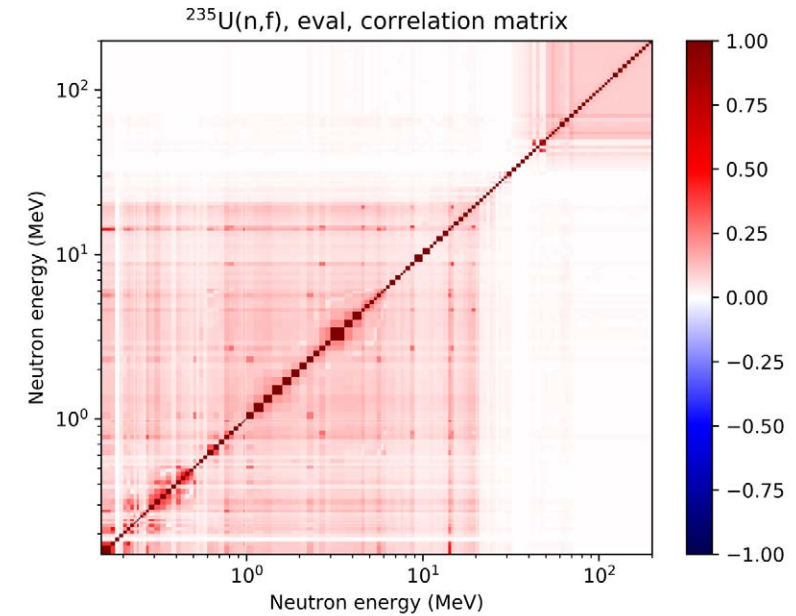
### ✓ GPR (RBF kernel)



### ✓ GPR (Matérn 3 kernel)



### ✓ GLS



- Broadly speaking, GPR results are similar to GLS results, but the strength of correlation differs from each other.
- Positive and negative correlations can be seen in GPR near the diagonal components.

# Summary and suggestion

## Summary

- GPR is a flexible tool to evaluate nuclear data, whose results could vary depending on the kernel function (and hyperparameters) adopted.
  - ➔ For  $^{235}\text{U}(n,f)$  case, the Matérn 3 kernel gave better results, but the covariance was somewhat different from the GLS results.

## Suggestion

- GPR is a promising option for evaluating nuclear data.
- The covariance data evaluated by GPR may help covariance users, for example, in uncertainty quantification of reactor physics parameters.