

Design of a soft X-ray imaging system and tomography analysis based on Bayesian principle

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Outline

Background

Bayesian experimental design

Bayesian tomography analysis

♦Summary



Soft X-ray tomography



◆ SXR tomography is widely used in fusion device

- SXR tomography can get the 2d image quickly
- SXR tomography has non-invasive character



Keda Torus eXperiment (KTX)

Keda Torus eXperiment





Reversed field pinch

parameters	КТХ
Major radius R (m)	1.40
Minor radius a(m)	0.40
R/a	3.5
Thickness of conductive shell (mm)	1.5
Poloidal magnetic flux	3~5Wb
Loop voltage V _{loop} (V)	10~50
Plasma density (10 ¹⁹ m ⁻³)	2
Electronic temperature T _e (eV)	300 (Phase I)
Maximum toroidal field Bt (T)	0.35 (Phase I)



Purpose of SXR design

Quasi-single-helical states is an important way to improve the confinement of RFP and it will be studied on KTX in the future

Requirement

- Get enough information of changed QSH states
- Get the 2d image of QSH states
- ◆ Use less resources (camera location, sight line)

Meet requirements with as few resources as possible!

flux surface of QSH state







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Bayesian experimental design

$$p(X|Y,I) = \frac{p(Y|X,I) \cdot p(Y|I)}{p(X|I)}$$

$$P(\boldsymbol{\alpha}|\boldsymbol{\eta}) = \frac{1}{\alpha_{max} - \alpha_{min}}$$

$$P(D|\boldsymbol{\alpha},\boldsymbol{\eta}) = \frac{1}{\sigma\sqrt{2\pi}}\exp(-\frac{(D-f(\boldsymbol{\alpha}))^2}{2\sigma^2})$$

Bayesian theory

 α : interest parameters –plasma edge η : design parameters – sightline D: experimental data

$$p(\boldsymbol{\alpha}|\boldsymbol{D},\boldsymbol{\eta}) = \frac{p(\boldsymbol{D}|\boldsymbol{\alpha},\boldsymbol{\eta}) \cdot p(\boldsymbol{\alpha}|\boldsymbol{\eta})}{p(\boldsymbol{D}|\boldsymbol{\eta})}$$

The probability for interest parameters



Bayesian experimental design



The information gain of η

α: interest parameters –plasma edge
η: design parameters – sightline
D: experimental data – SXR emissivity



The BED approach allows us to quantitatively evaluate the performance of the design, and to estimate the design robustness



SXR sightline design





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SXR sightline design

Camera location: $\varphi = 0^{\circ}, \varphi = 180^{\circ}$ Camera opening angle: $\Delta\beta = 100^{\circ}$





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Tomography Reconstruction

$$p(\alpha|D,\eta) = \frac{p(D|\alpha,\eta) \cdot p(\alpha|\eta)}{p(D|\eta)}$$

$$p(\boldsymbol{g}|f,\boldsymbol{\theta}) = \frac{p(f|\boldsymbol{g}) \times p(\boldsymbol{g}|\boldsymbol{\theta})}{p(f|\boldsymbol{\theta})}$$

g: interest parameters – emissivity distribution
θ: design parameters – reconstruction method
f: experimental data – brightness

Get *g* from *f*

Cormark-Bessel method

$$f(p,\varphi) = \int_{L(p,\varphi)} \frac{g(r,\theta)}{dl} dl$$





Tomography Reconstruction

$$g(r,\theta) = \sum_{m=0}^{\infty} \sum_{l=0}^{\infty} [a_m^{(c)l} \cos(m\theta) + a_m^{(s)l} \sin(m\theta)] g_m^l(r)$$

Expend in Fourier series
$$f(p,\varphi) = \sum_{m=0}^{\infty} \sum_{l=0}^{\infty} [a_m^{(c)l} f_m^{(c)l}(p,\varphi) + a_m^{(s)l} f_m^{(s)l}(p,\varphi)]$$

$$f_m^{(c,s)l}(p,\varphi) = \int_L (\cos(m\theta), \sin(m\theta)) g_m^l(r) ds$$

$$g_m^l(r) = J_m(\lambda_m^{l+1}r)$$

$$\lambda_m^l \text{ is the lth zero of mth Bessel function}$$



Parameters of method

$$f_m^{(c,s)l}(p,\varphi) = \int_L (\cos(m\theta), \sin(m\theta)) g_m^l(r) ds$$
$$p(g|f,\theta) = \frac{p(f|g) \times p(g|\theta)}{p(f|\theta)}$$





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Tomography analysis

The reconstruction of QSH states need at least 2 SXR cameras

 $\Delta \phi$ is the angle between 2 camera









Tomography analysis

♦ It can be divided into two parts with Δφ = 130°
♦ Part 1 has a peak at Δφ = 60°
♦ Part 2 has a peak at Δφ = 180°





2D image of SXR





Summary

- The experimental design is accomplished with two windows and open angle 100°
- The BED approach allows us to quantitatively evaluate the performance of the design, and to estimate the design robustness.
- The Bayesian theory can be used to analyse the tomography reconstruction and we use it to modify the reconstruction method and do two camera design.





Thank you!



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