

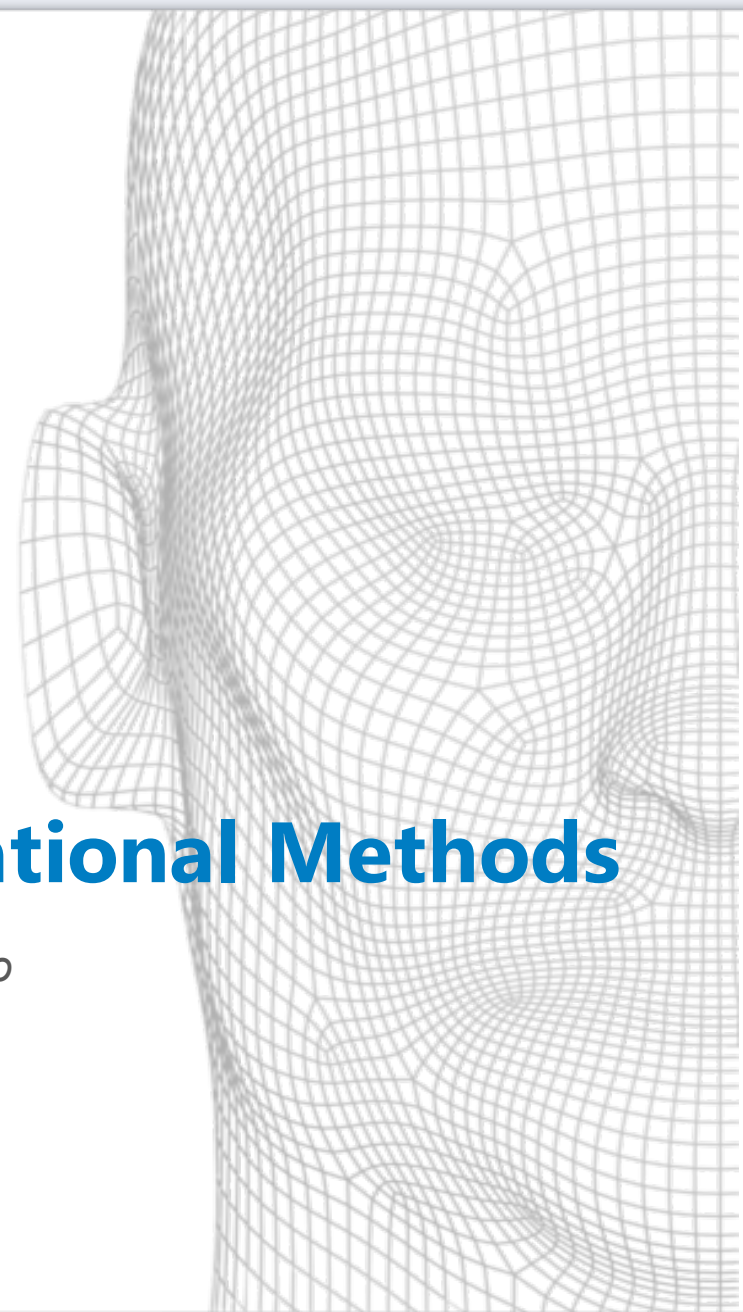
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STUDIECENTRUM VOOR KERNENERGIE
CENTRE D'ETUDE DE L'ENERGIE NUCLEAIRE

Personal Online Dosimetry Using CoMputational Methods

Filip Vanhavere, Mahmoud Abdelrahman, Pasquale Lombardo



Framework for individual monitoring: why is dosimetry needed

Individual monitoring of workers



Control occupational exposure



Dose limits and ALARA principle



Inform workers of their exposure



Avoidance



Behaviour



Control

Dose	Annual Limit
Effective Dose	20 mSv
Eye Lens	20 mSv
Extremities	500 mSv/year

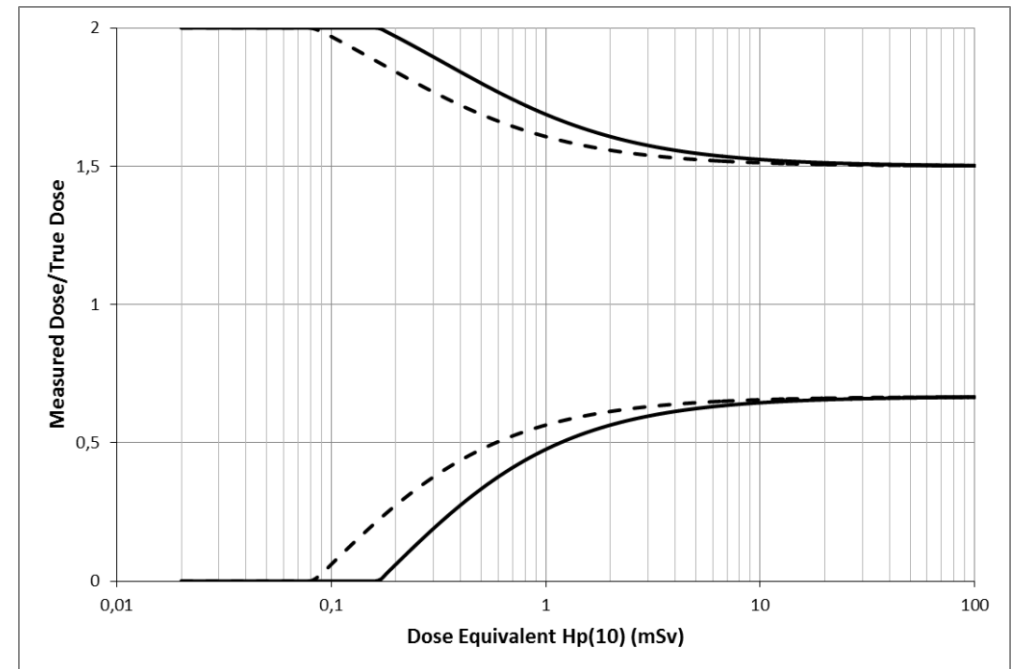
Problems with individual dosimetry

- Workers don't like to wear dosimeter
- Workers especially don't like to wear more than one dosimeter
- Still not all parts of body covered
 - What if other parts of body need dosimetry in future (brain, heart,...)?
- Not always strict use of dosimeters:
 - Forgetting
 - Not correct place



Uncertainties in personal dosimetry

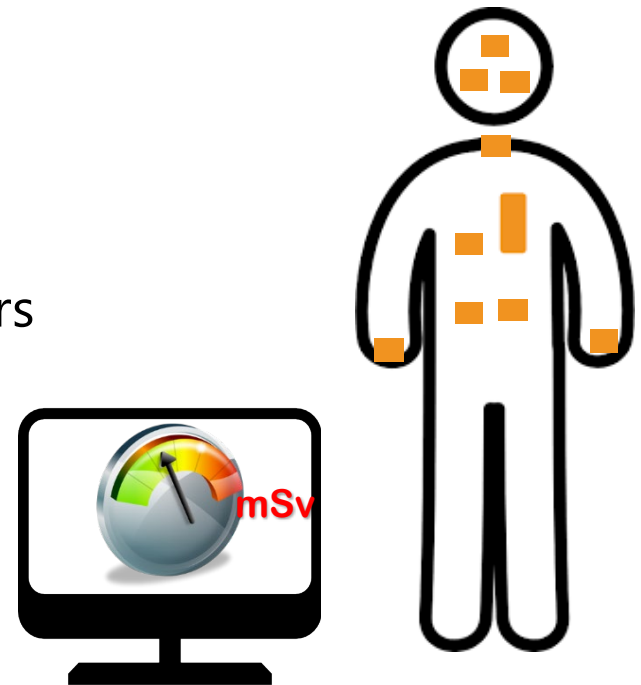
- Risk is given by effective dose
 - Complicated system of operational quantities to estimate effective dose
 - $H_p(10)$ is only estimation of E
- No dosimeter is perfect for $H_p(10)$
 - Non-linearity, fading, ...
 - Energy and angular dependence....
- Loosing dosimeter: all data lost...
- Not wearing correctly
 - Dependent on homogeneity of the field



Factor 1.5 in either direction for doses near the limit
Factor 2.0 for lower doses (ICRP 75)

Personal Dosimetry: what brings the future?

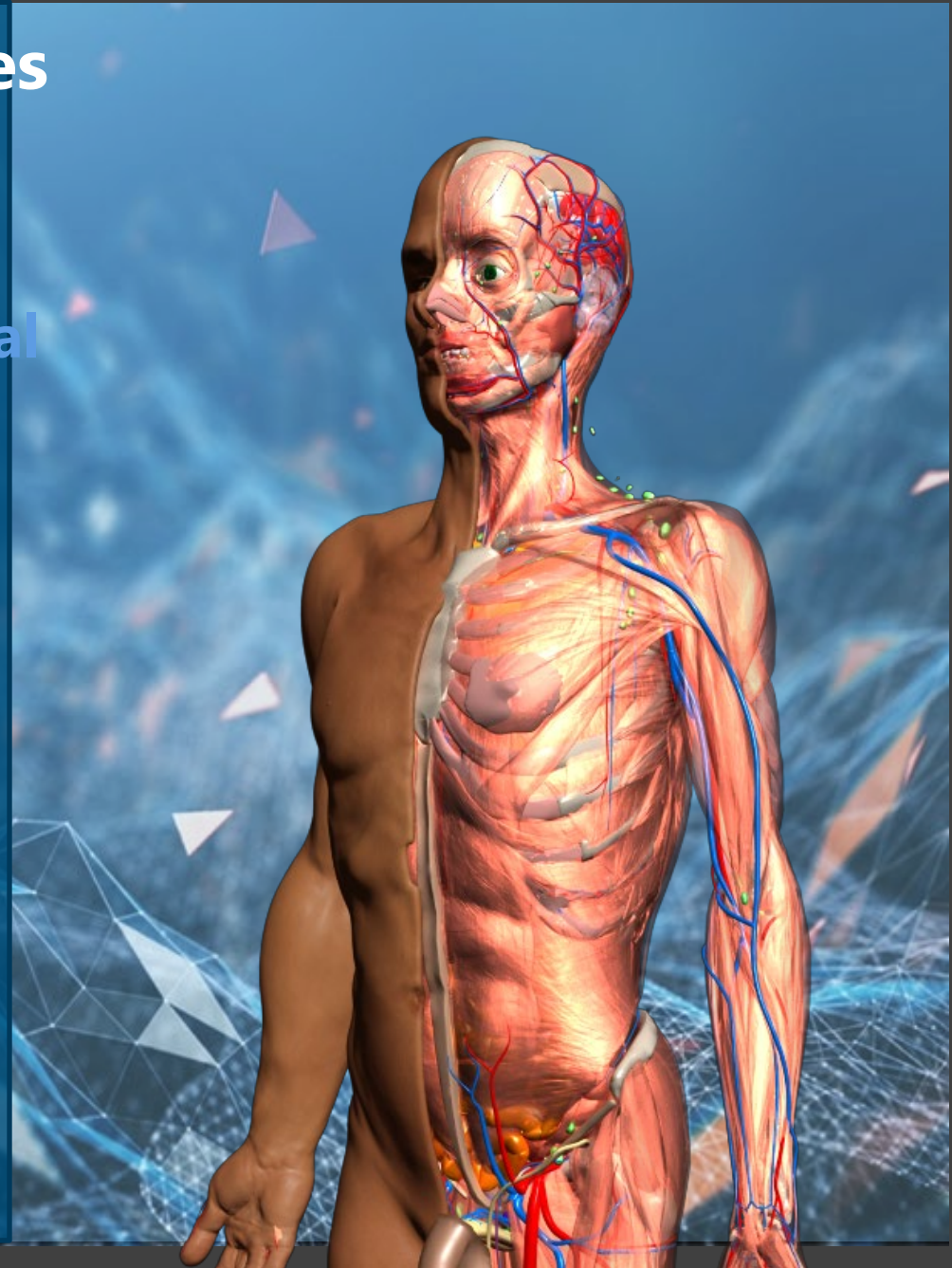
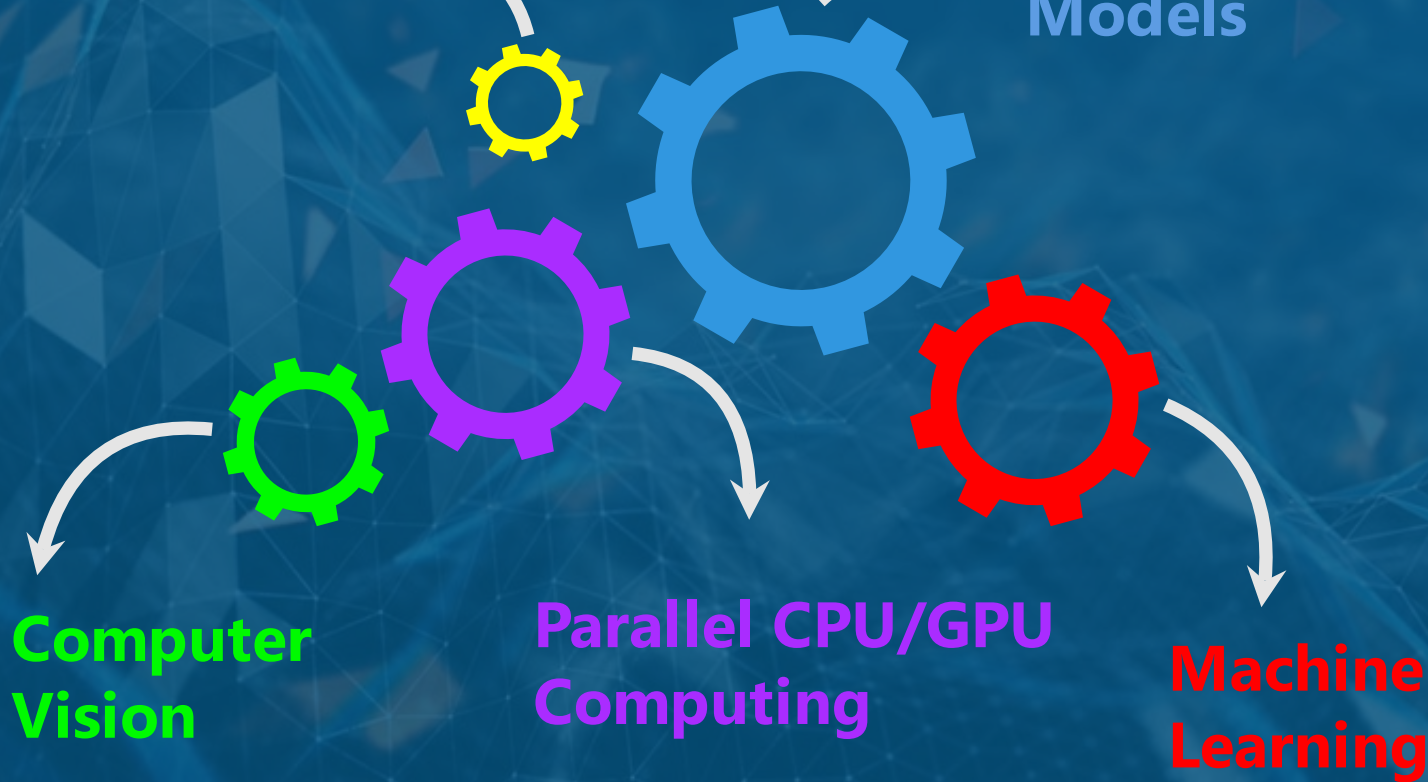
- More use of active personal dosimeter: direct feedback
- May be no need for physical dosimeters?
- Suppose we can use [Monte-Carlo simulations](#) to calculate on-line all doses
- Advantages:
 - No more need for physical dosimeter
 - No more losing dosimeters
 - No more need for operational quantities
 - No more worries for changing quantities/weighting factors
 - Doses to all organs can be known
 - Personalized dosimetry possible
 - Better accuracy possible
 - Faster feedback to workers
 -



Exploiting most advanced technologies

Monte Carlo Simulations

Human Computational Models



- CONCERT 2nd Call
- EC project

- 24 months, start January 2018

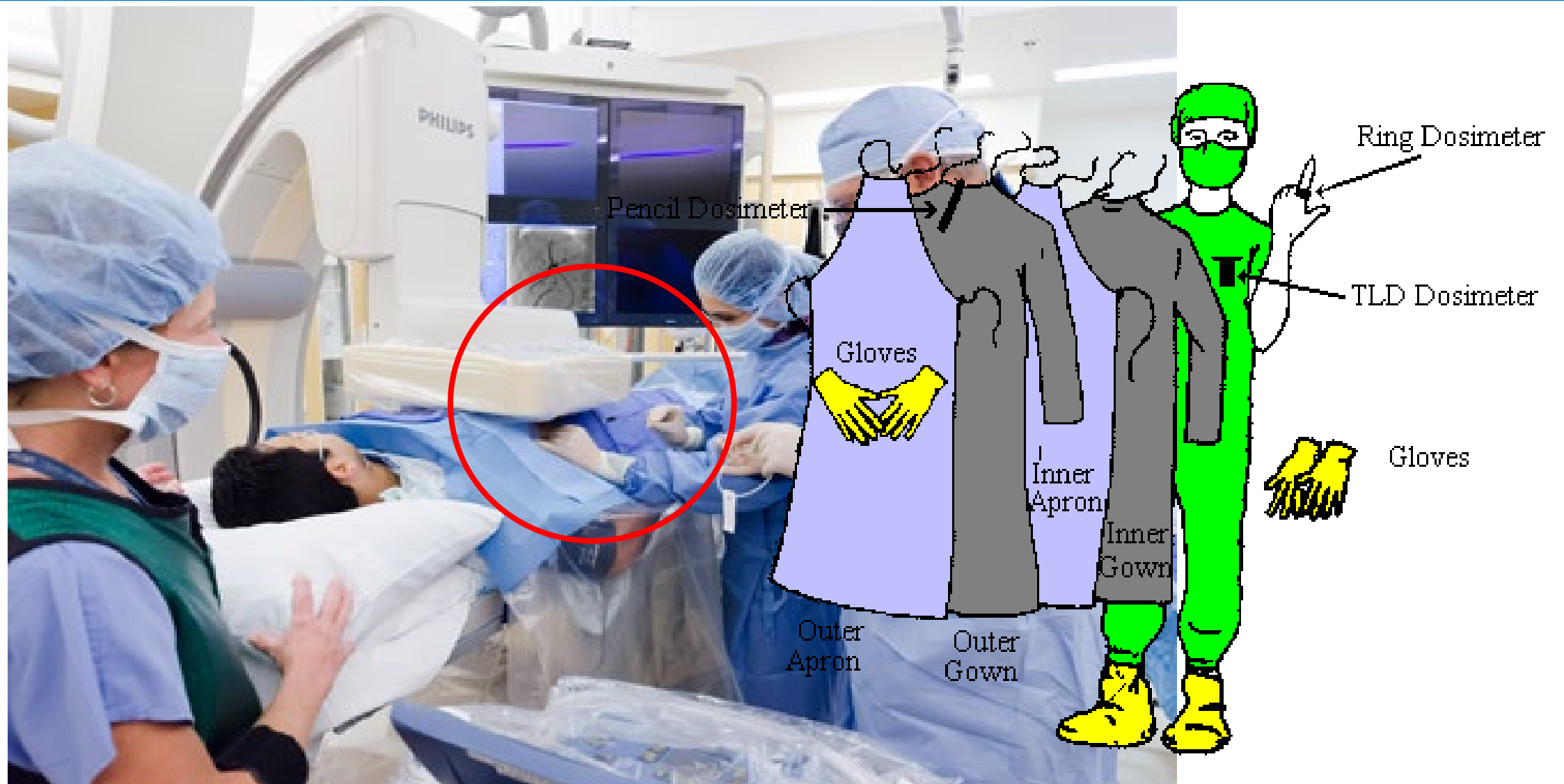
- 7 partners: SCK•CEN (Belgium), UPC (Spain/Catalunya), HMGU (Germany), LU (Sweden), PHE (UK), EEAE (Greece), SJH (Ireland)

- **Improve occupational dosimetry** via an online dosimetry application using computer simulations: without the use of physical dosimeters
- **Develop an online application** in which we will calculate individual occupational doses
- **Apply and validate** the methodology for two situations where improvements in dosimetry are urgently needed: **neutron workplaces** and **interventional radiology**
- The **legal aspects** to introduce this or similar techniques as an official dosimetry method will also be established

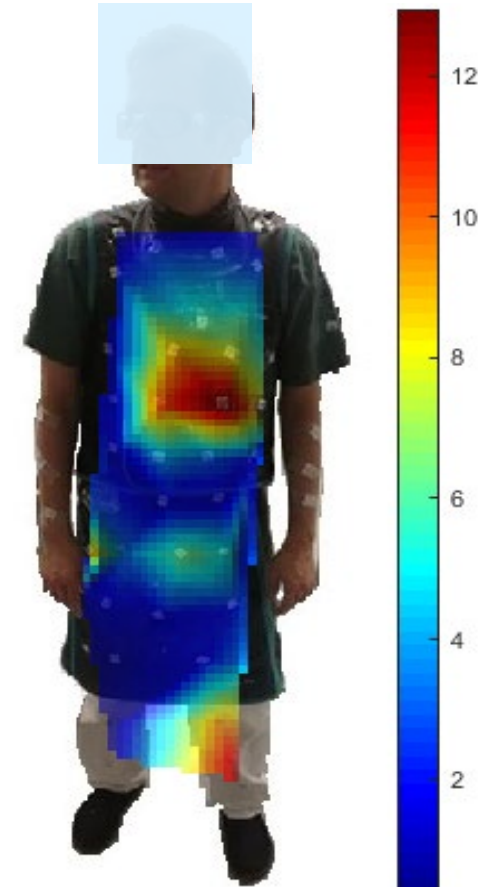
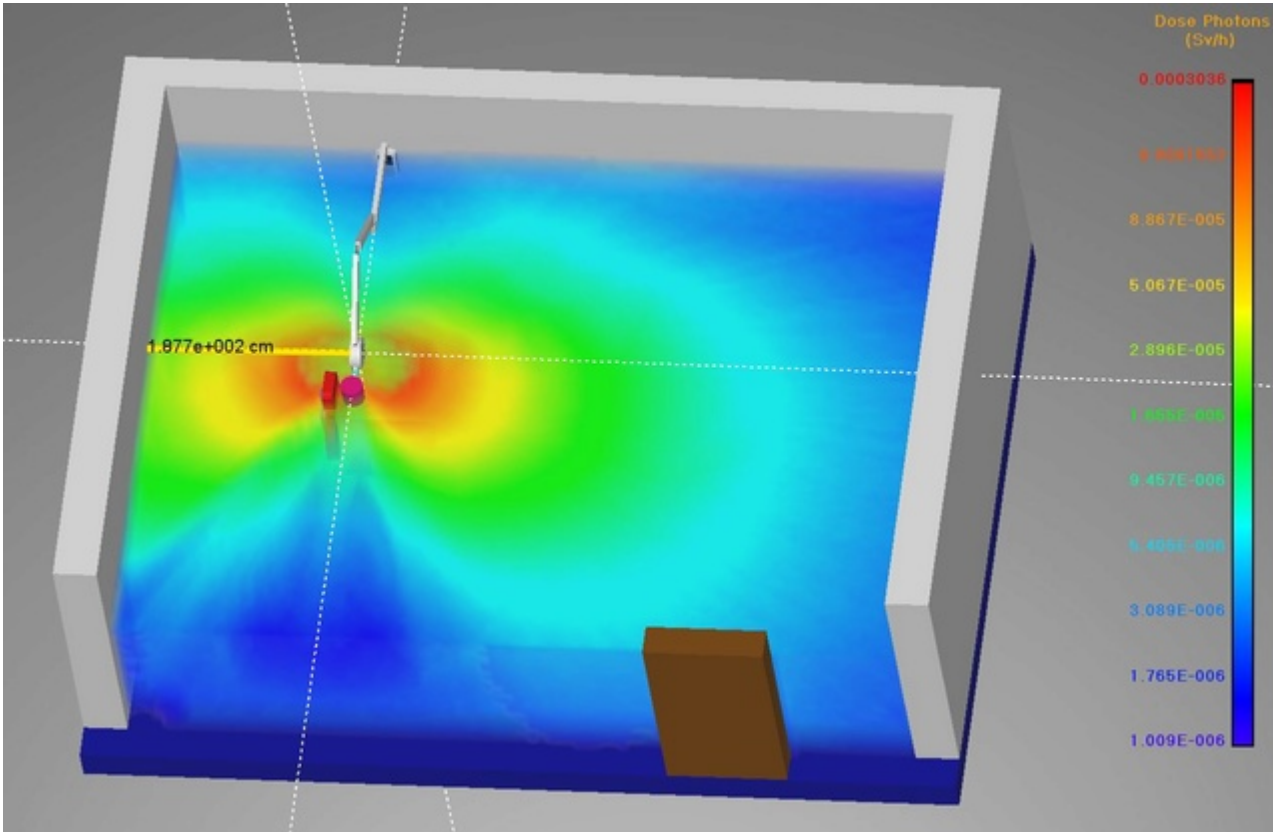


FEASIBILITY STUDY

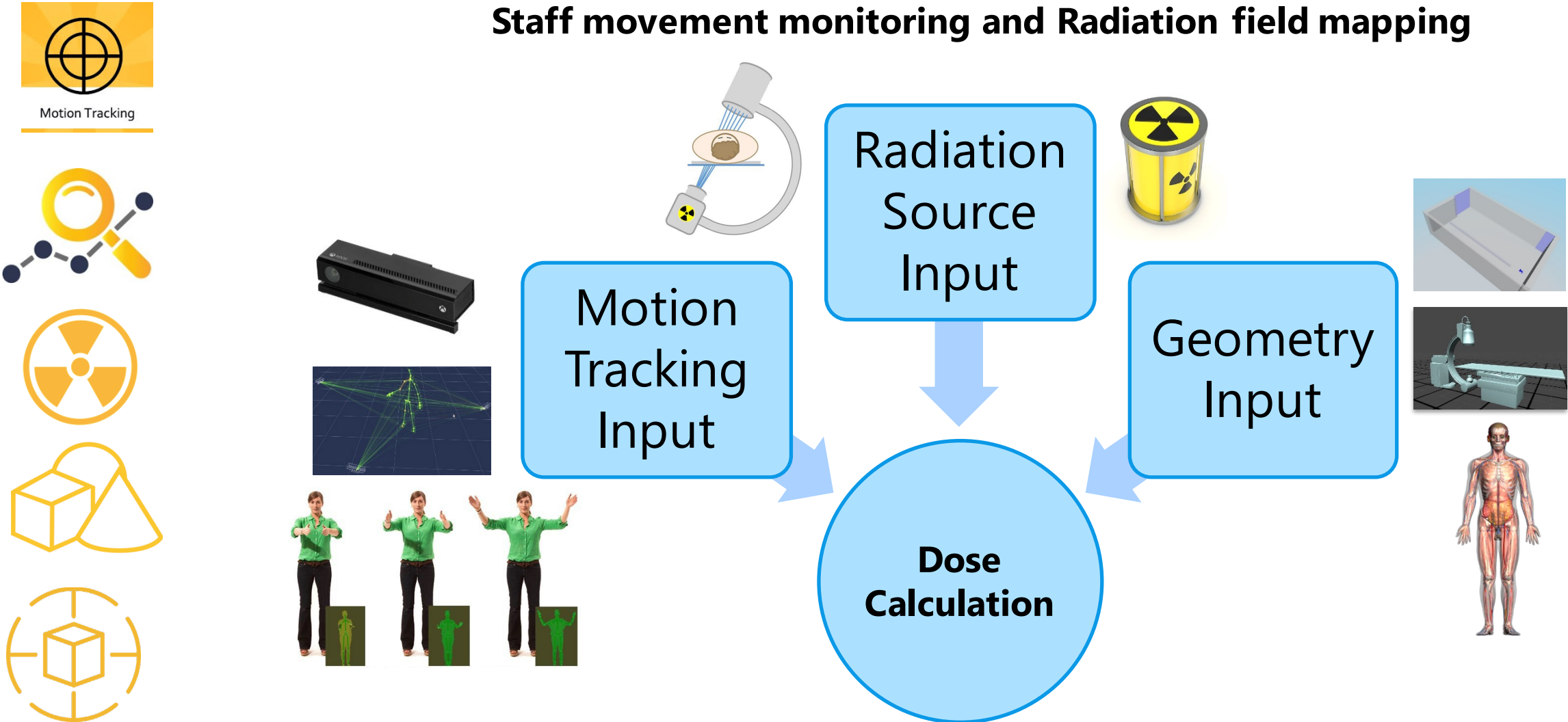
Personal Dosimetry: Interventional Radiology



Personal Dosimetry: Inhomogeneous fields



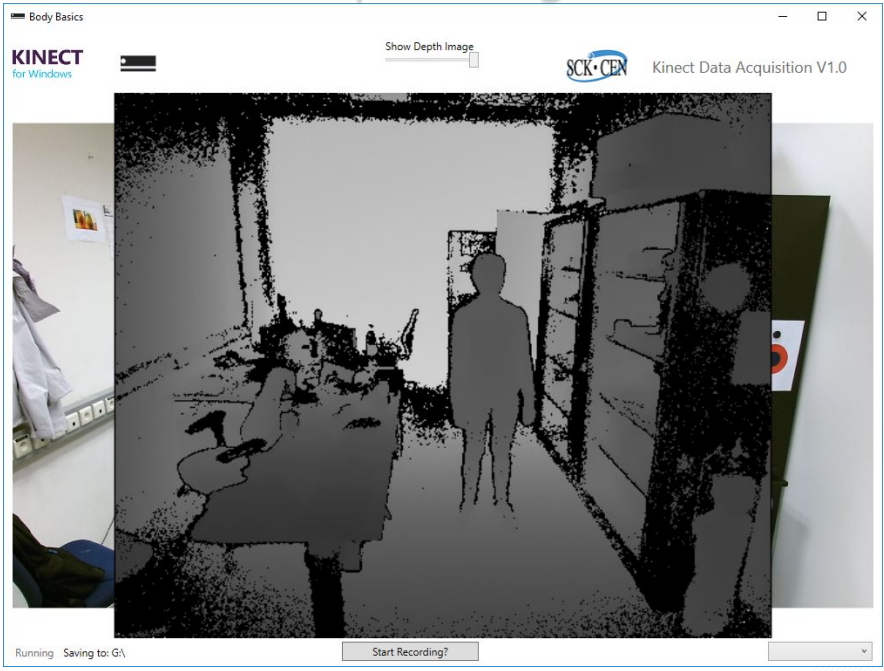
Staff movement monitoring and Radiation field mapping



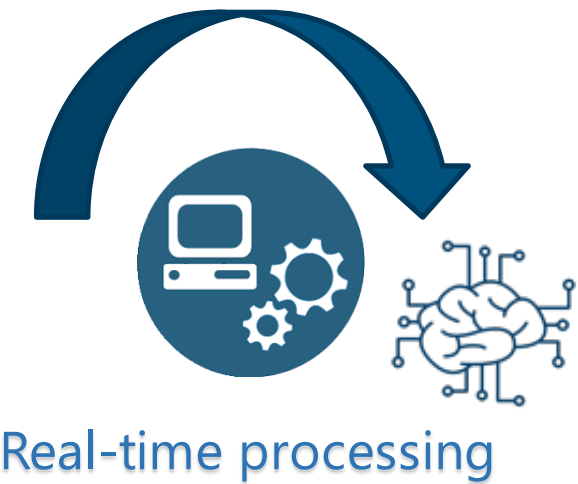
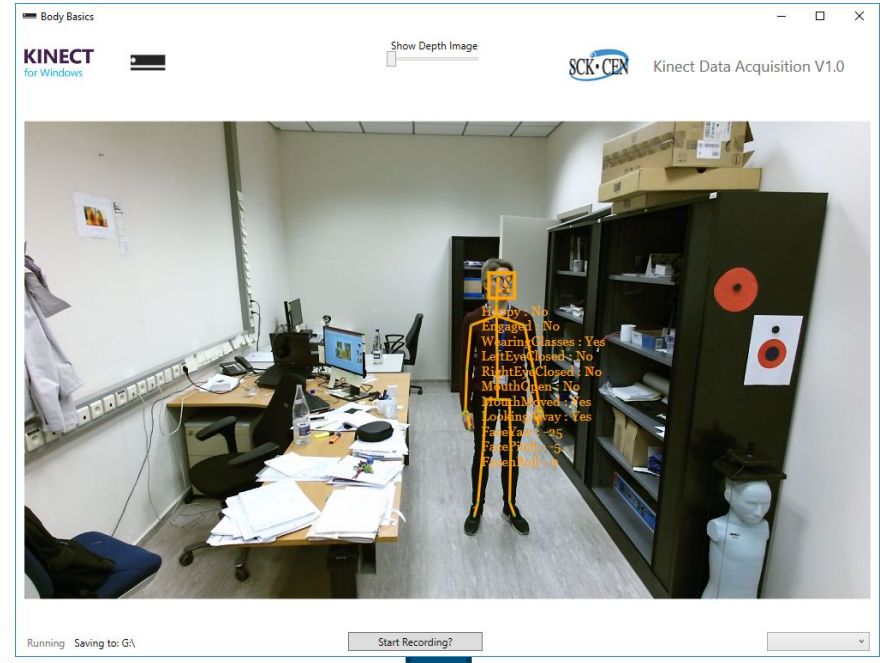


Tracking system based on single depth camera

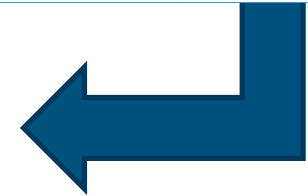
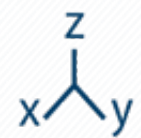
Depth Image



Skeleton Tracking



Real-time processing



Storing XYZ coordinates or send to a cloud

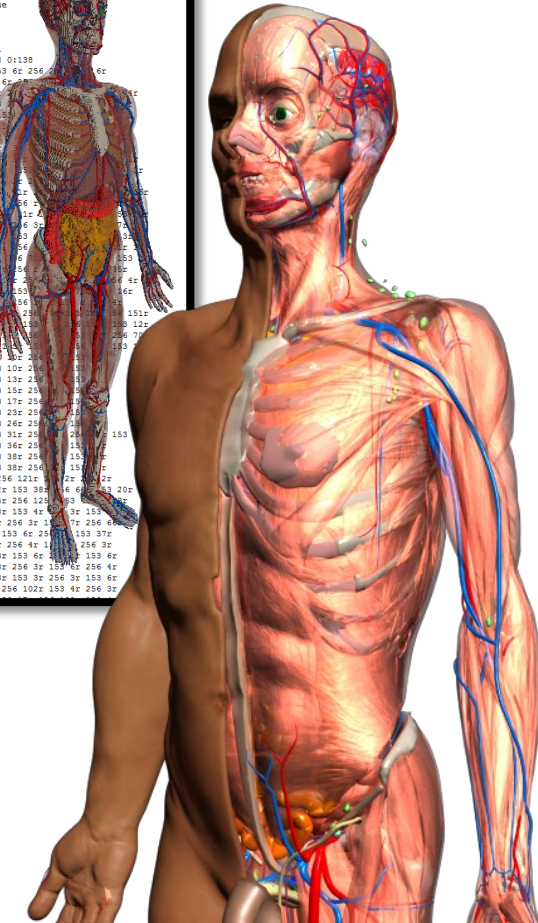
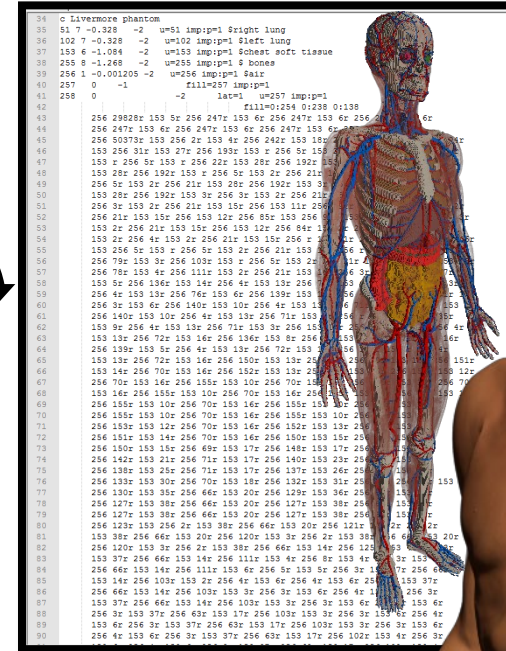
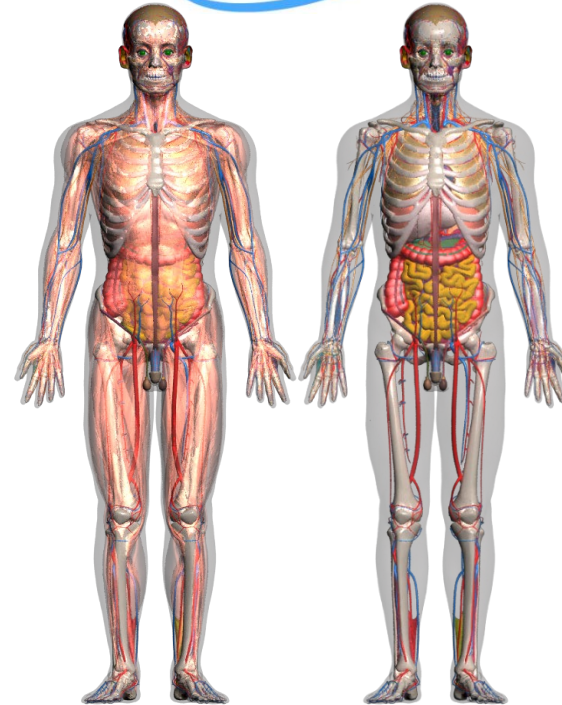
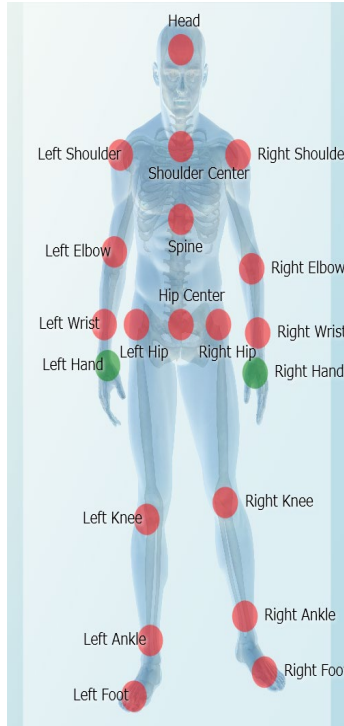
RAF: Realistic Anthropomorphic Flexible Phantom

- Polygonal Mesh Boundary Representation
- Organ and tissue masses adjusted according to ICRP 89
- Computational model with 2900 tissues segmented
- Dosimetric validation in comparison with ICRP 116



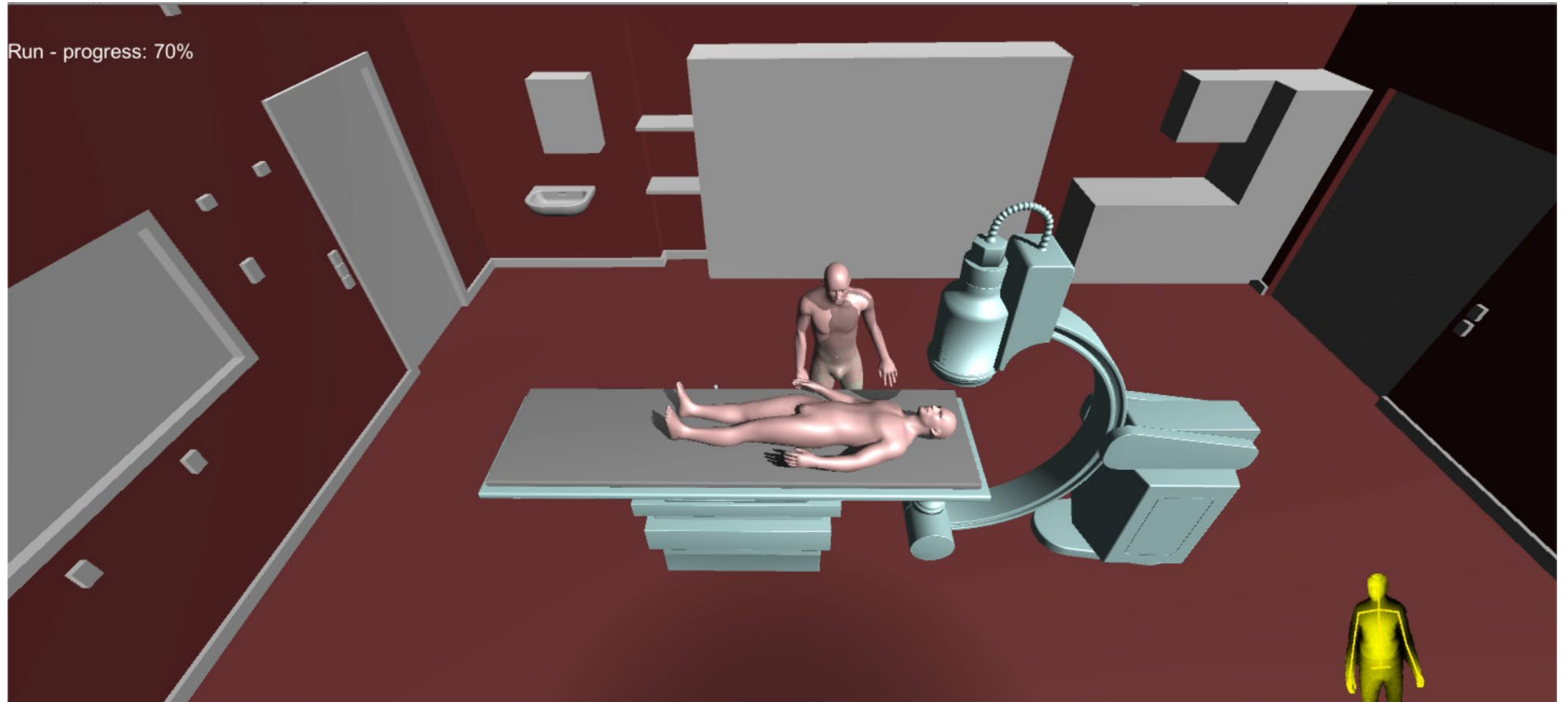
Development and Validation of the Realistic Anthropomorphic Flexible (RAF) Phantom

Lombardo, Pasquale A.; Vanhavere, Filip; Lebacqz, Anne L.; Struelens, Lara; Bogaerts, Ria
Health Physics, Volume 114 (5) – Jan 1, 2018



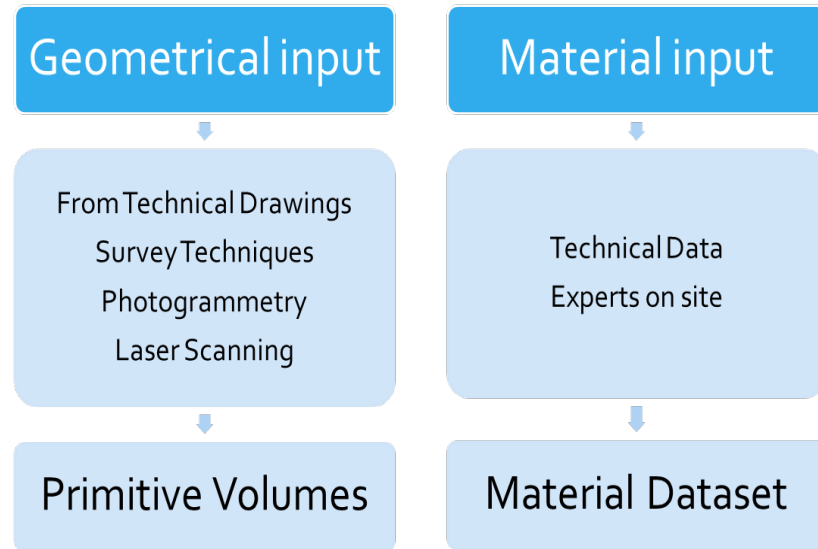
Realistic Anthropomorphic Flexible Phantom (RAF)

Animation of RAF phantom





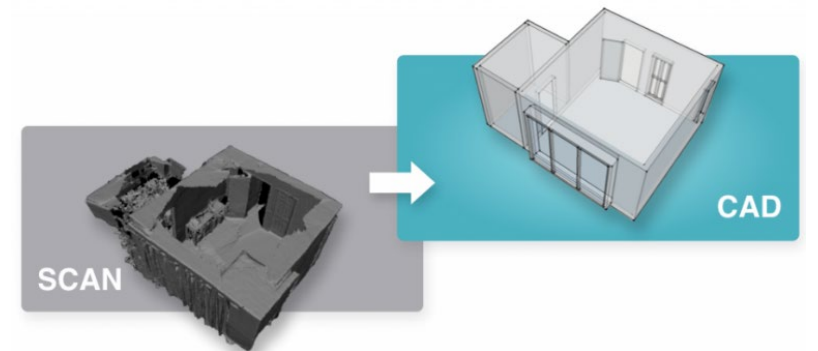
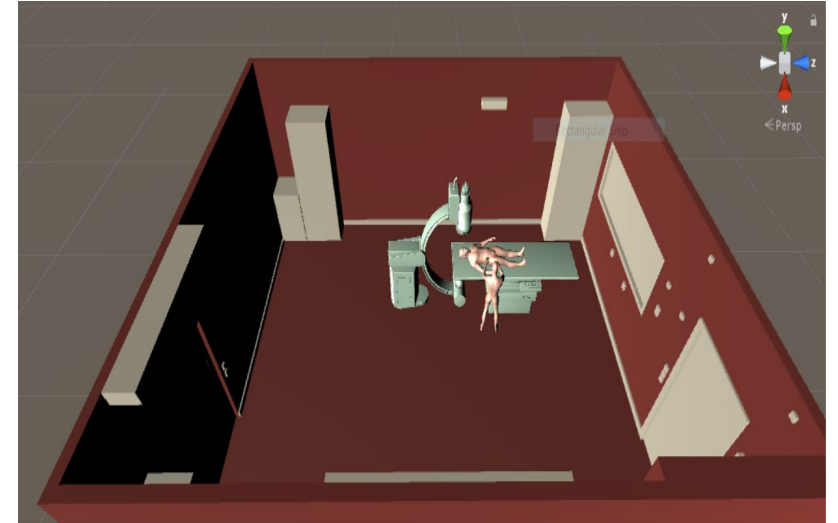
- Define of the workplace geometry for the calculations



- Complex geometries can be prepared by:

- Scanning of the workplace
- Converting CAD files to different formats

- Modeling and tracking of important moving objects (**shielding**) is also needed

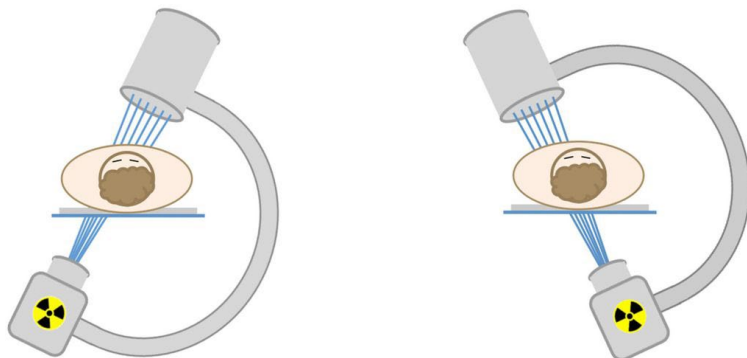


X-Ray spectrum

- Tube potential (kVp value)
- Tube current
- Added filtration
- Target material
- Voltage waveform

Tube Angulation

- C-arm projections



Interventional Radiology and Cardiology Parameters

Parameter	Range
High Voltage	60-120 kVp
Intensity	5-1000 mA
Inherent filtration	3-6 mm Al _{eq}
Additional filtration	0.2-0.9 mm Cu
Energy range of scattered spectra	20 keV – 100 keV



Input

- Radiation dose structured report (RDSR) extracted from the X-ray machine
- **Time synchronization with tracking**
- DAP meter for normalization

SCK·CEN

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Standard position

No room

Selected EndEffector

Head

Inverse Kinematic

KINECT

- zoom Face
- zoom Chest
- rescale RAF
- move RAF
- scatter Sphere
- Hp(10) dosimeter
- 25 tissues
- 122 tissues
- Lead Apron
- Collar
- Cap
- Activate elbow and knees
- Faster End Effector movement
- Slower End Effector movement
- Faster Camera
- UP Camera

C-Arm rotation

- rotation of projection 29 LAO
- arm angulation 37 CAU
- position along bed -43.0705
- position perpend bed 53.51411

IPP - RAF phantom

IR Room definition

- IR room
- Rotate C-Arm
- Move bed

effective dose [Sv/(Gy DAP)] * (voxel volume)

0.000112357150692318

Calculate Bounding Box

Res x	Res y	Res z
256	512	256

load MCNP PTRAC

Batch mode (seconds) 30

KINECT angle (deg) -10

PNG stack for VoxelVis VoxelVis

Patient and C-Arm Read MCNP output

Visualise skin regions

High Res? cut legs! PP graphics

OBJ ASCII STL BINARY STL

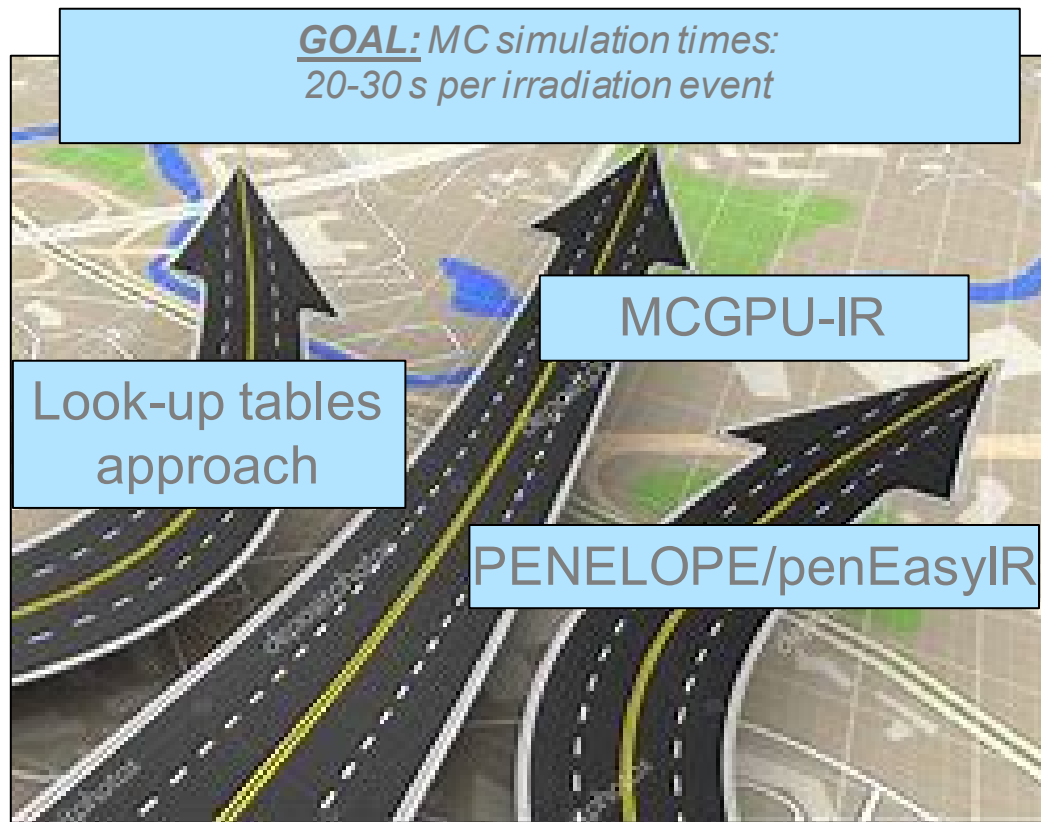
Export Mesh for Geant4

Voxelize on GPU launch MCNP sim



Computational dosimetry ... the solution?

Challenge: Make Monte Carlo calculations fast enough



Fast Monte Carlo methods for interventional procedures

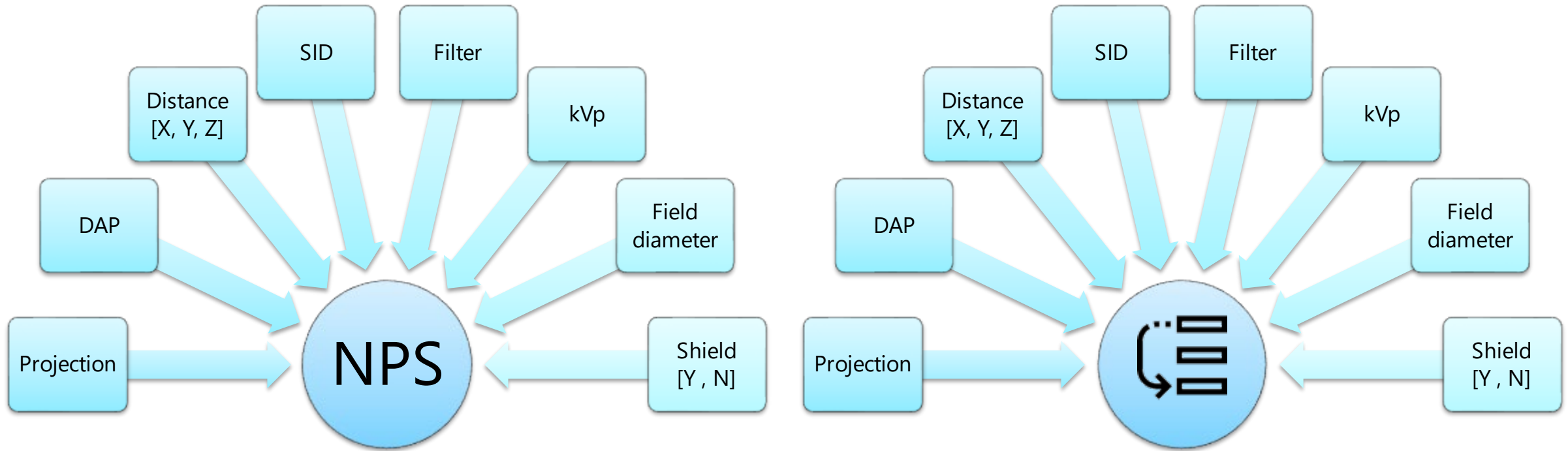
MCGPU-IR

Based on MC-GPU (2009) a MC code for the simulation of photon transport in restricted geometrical set-up's

PENELOPE/penEasyIR

Based on PENELOPE v2014, a standard multi-purpose MC code

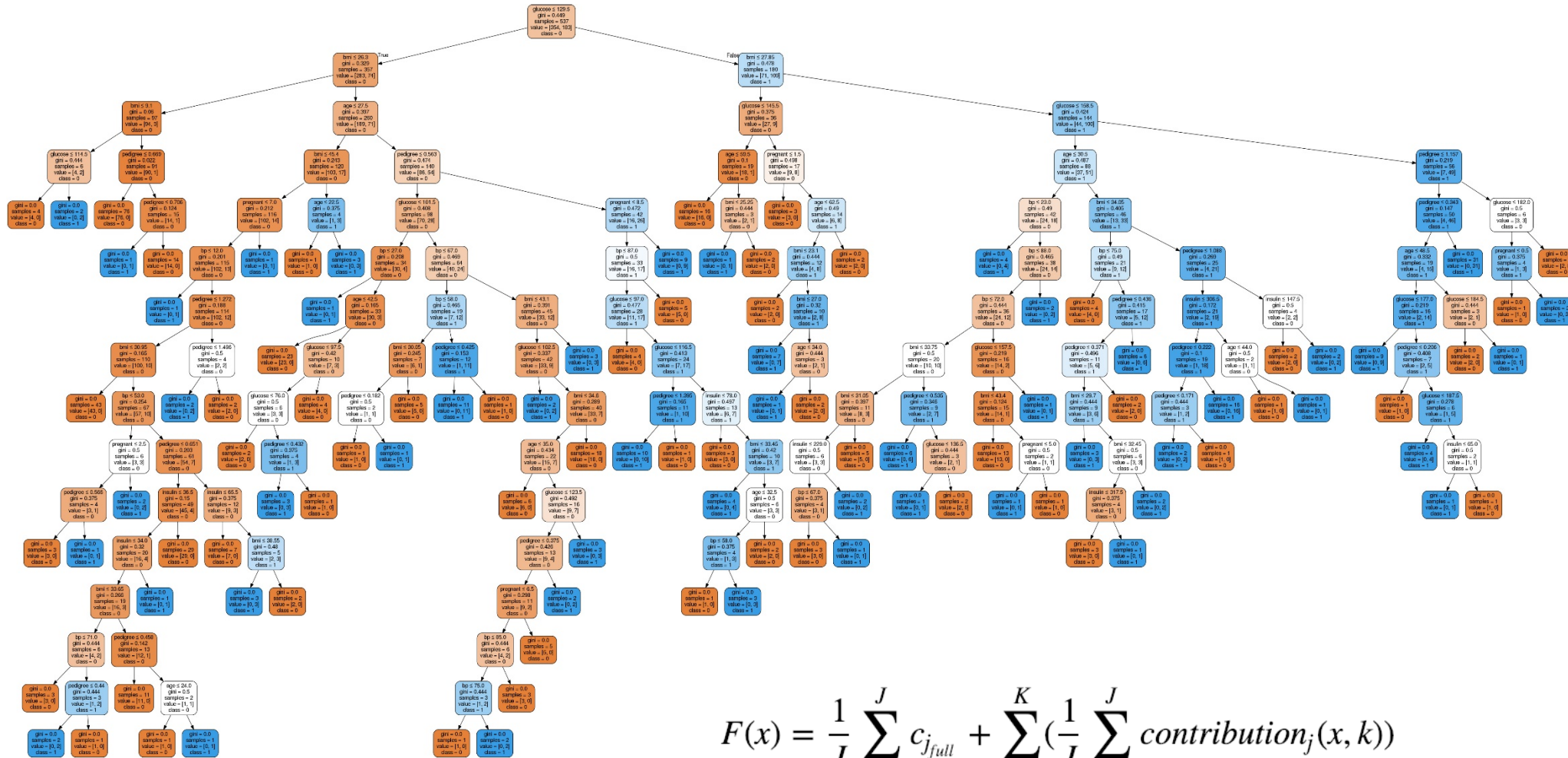
Optimization Algorithm



Optimized simulation time
NPS: number of simulated particles

Prioritization of simulations
Irradiation event with high dose

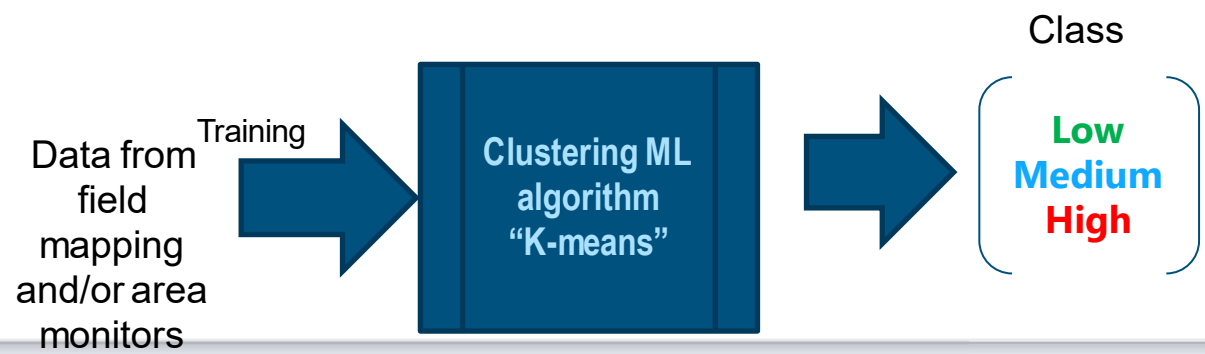
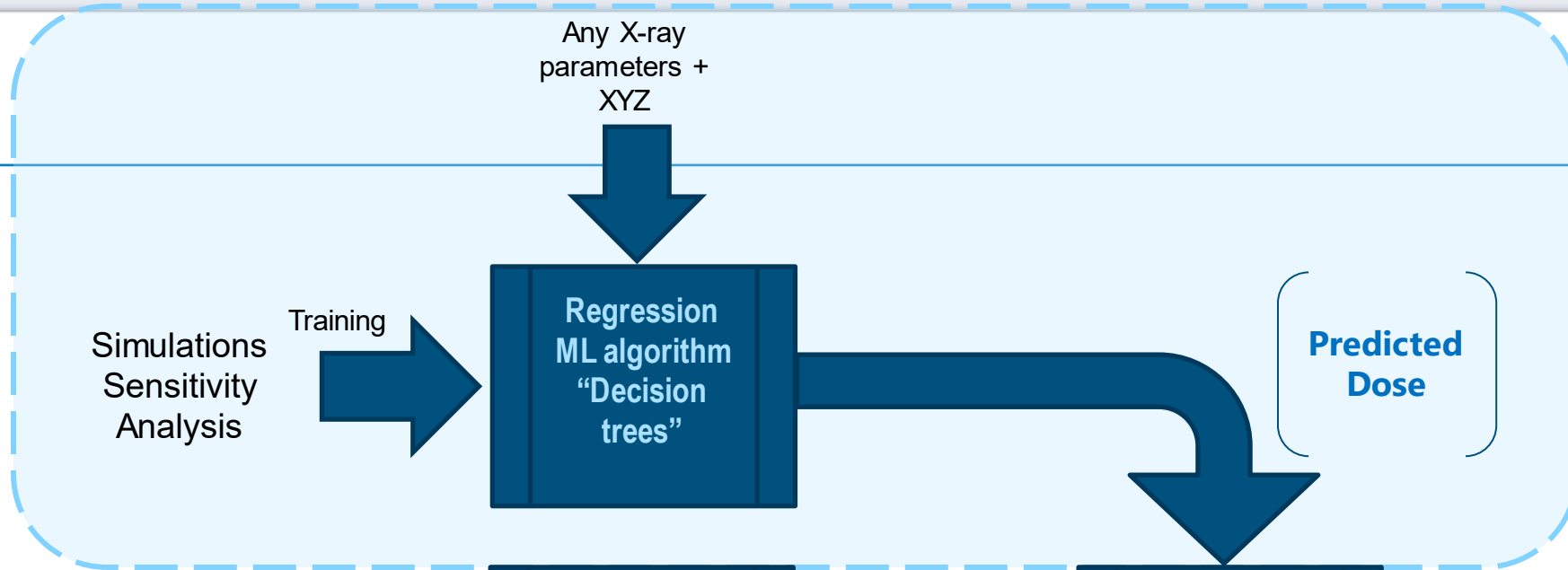
Data analysis: Random forest regressor

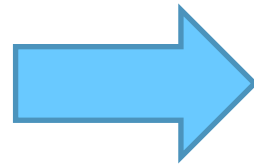
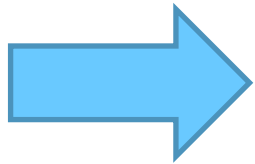


$$F(x) = \frac{1}{J} \sum_{j=1}^J c_{j,full} + \sum_{k=1}^K \left(\frac{1}{J} \sum_{j=1}^J \text{contribution}_j(x, k) \right)$$

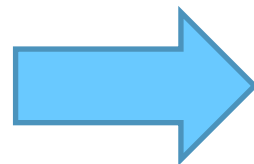
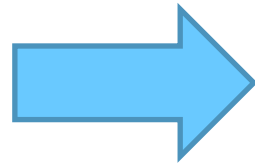
Predictive model

Classification model





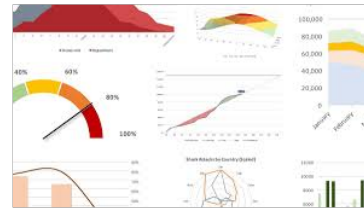
Model Training



Scoring

Dosimetry integration

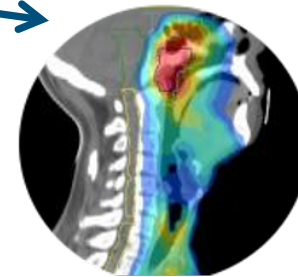
ID	State de desenvolupament	Class de tractament	Data	Tipus	Estat
1001_01	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_02	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_03	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_04	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_05	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_06	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_07	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_08	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_09	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat
1001_10	0000-01-01	0000-01-01	0000-01-01	CA	Finalitzat



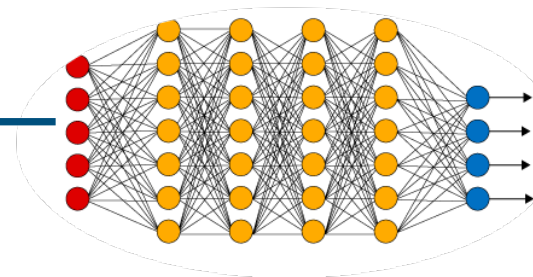
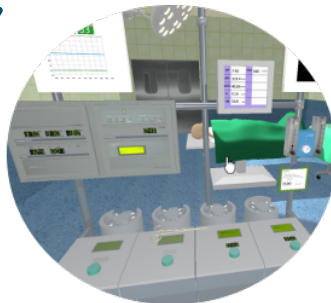
2D, 3D
Visualization

On-line dose
calculation

Tracking



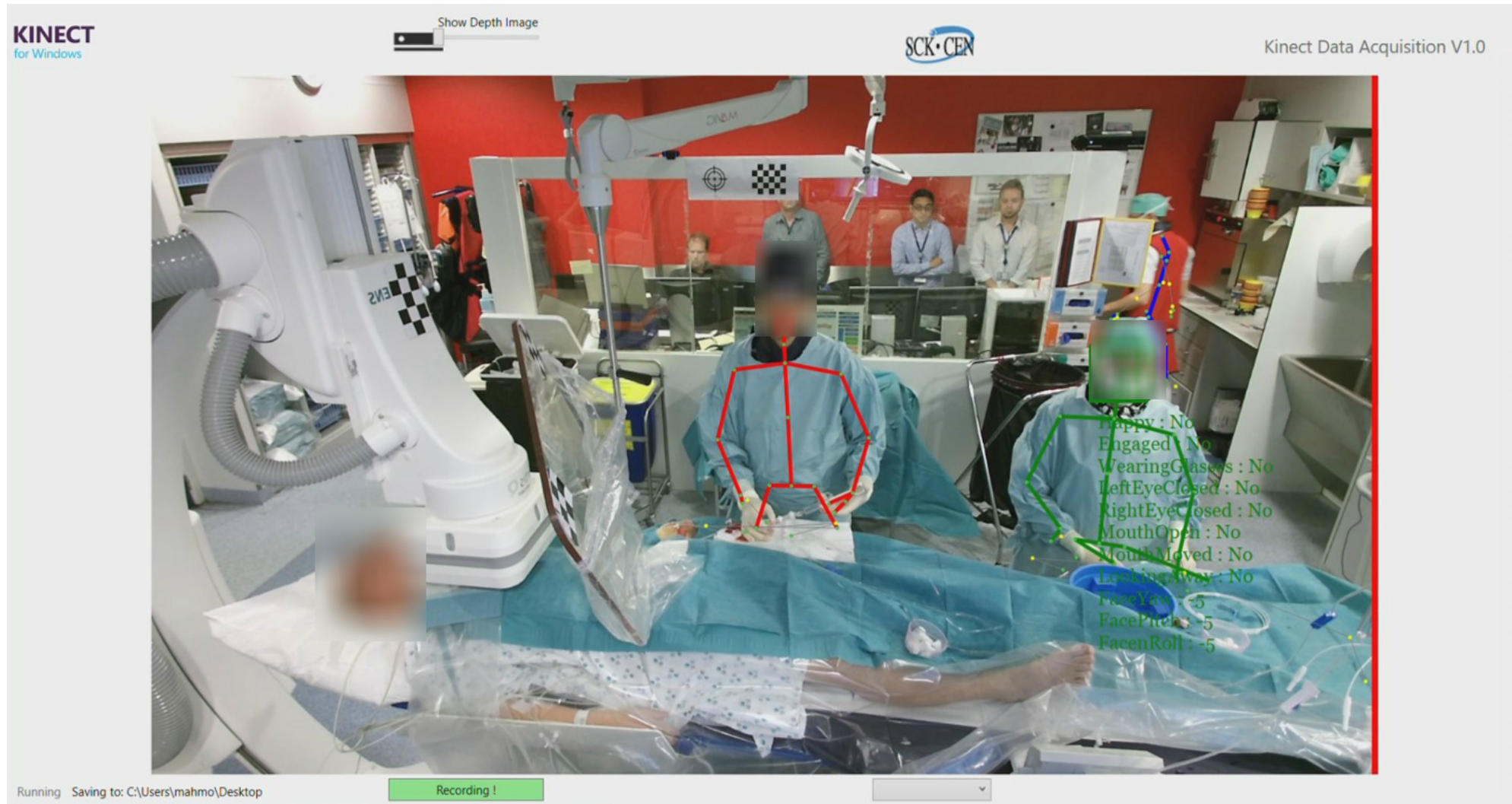
Gaming,
Traning,
data



Deep learning

Validation





KINECT
for Windows

Show Depth Image

SCK•CEN

Kinect Data Acquisition V1.0

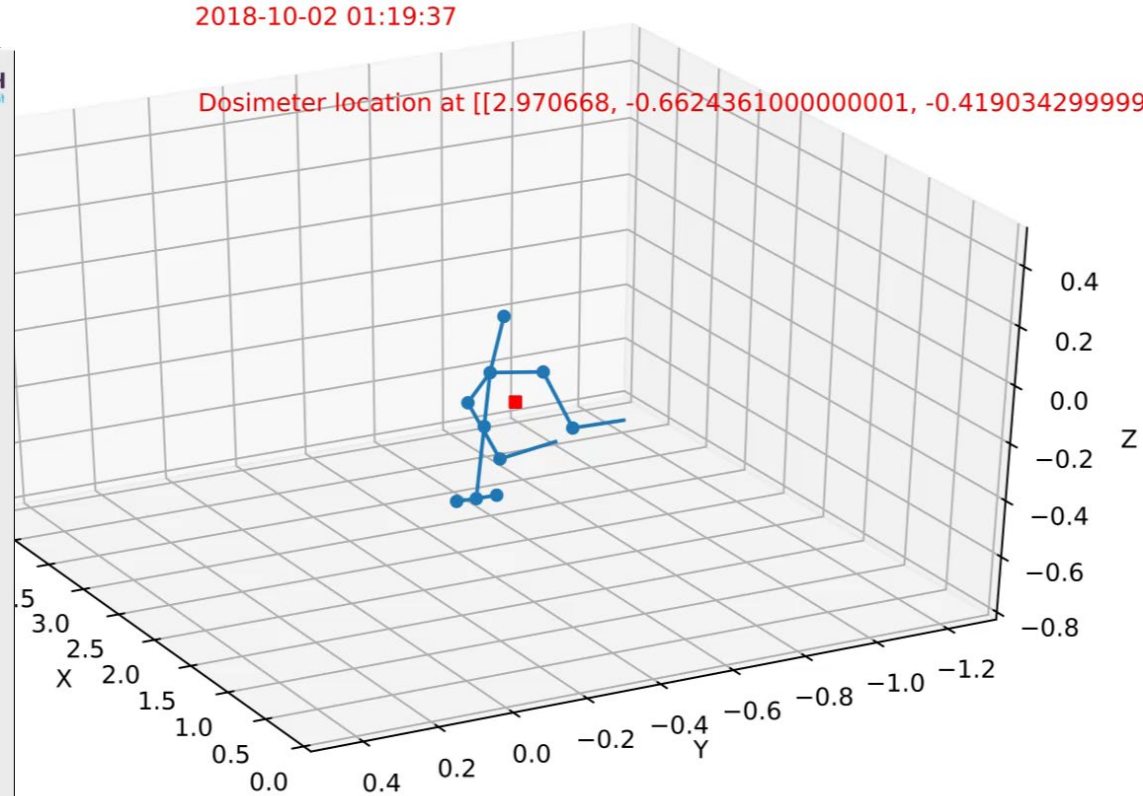
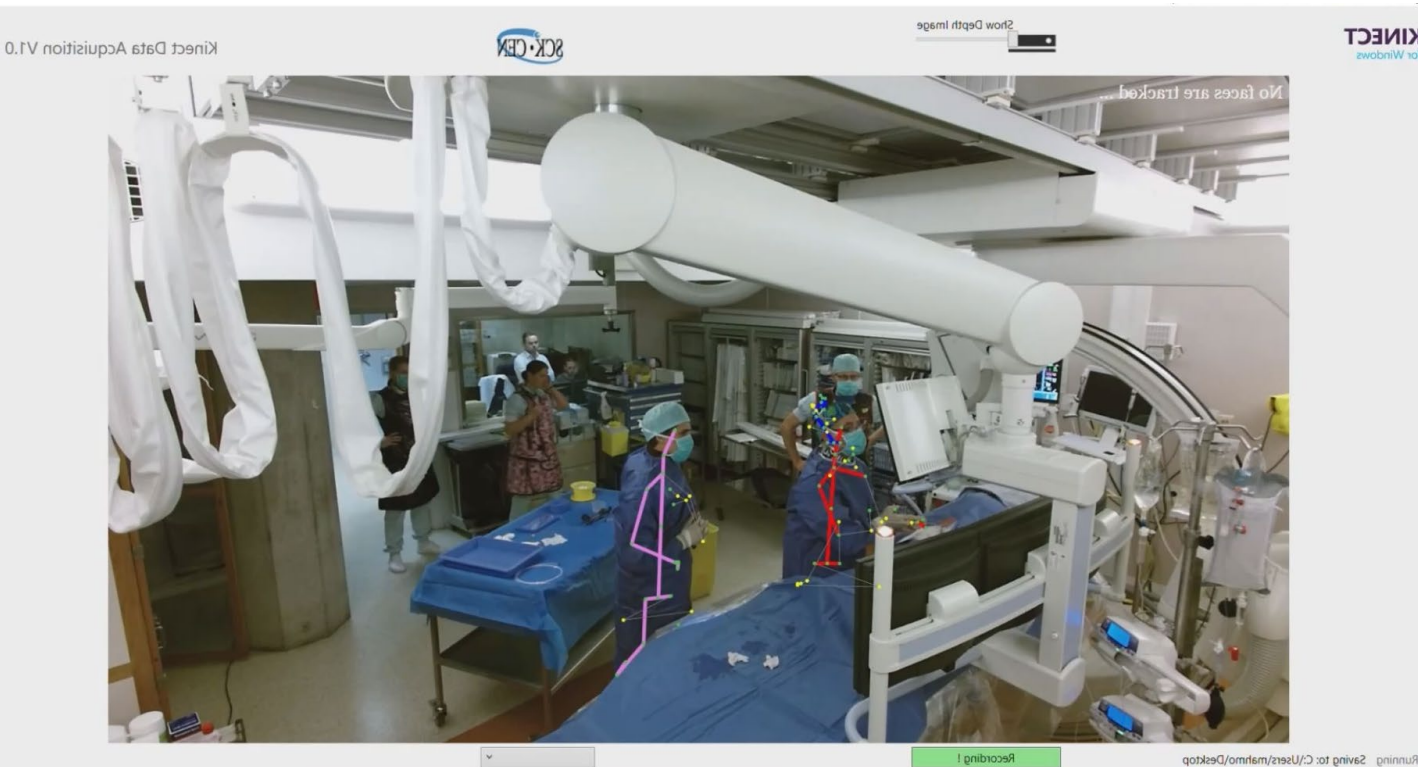


Running Saving to: C:\Users\mahmo\Desktop

Recording !

Validation Case: Angioplasty Procedure

- Measurement of accumulated dose $H_p(10)$ of operators with Thermo EPD Mk2.3
- Estimation of dosimeter location by the tracking system

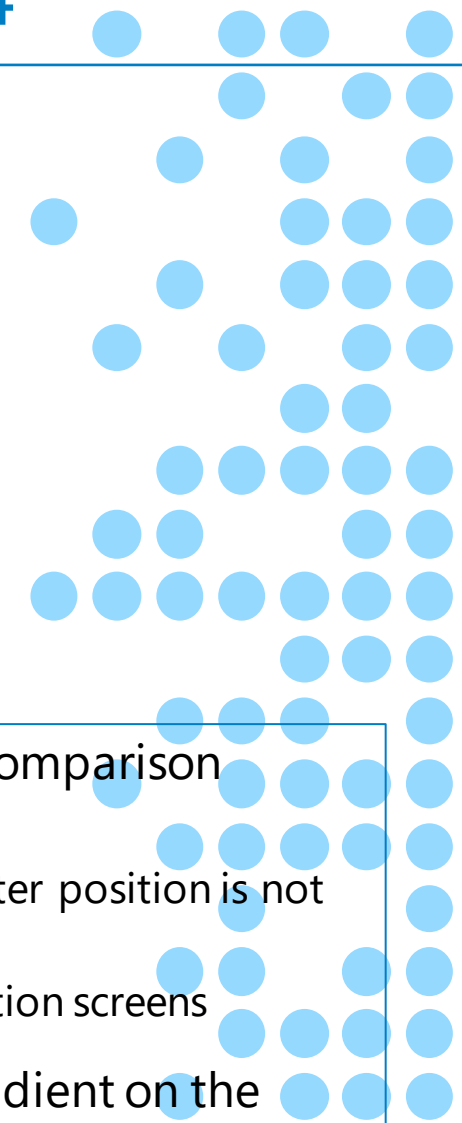


Results from CHU-Liège case 4

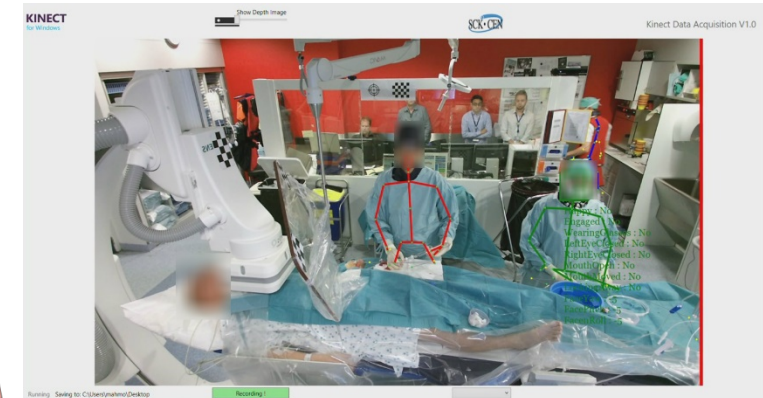
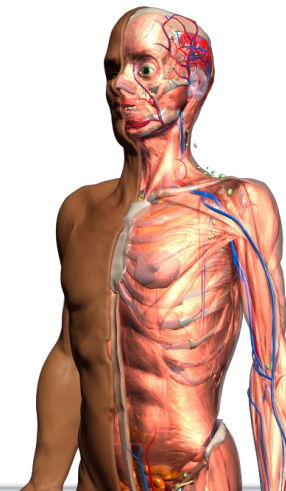
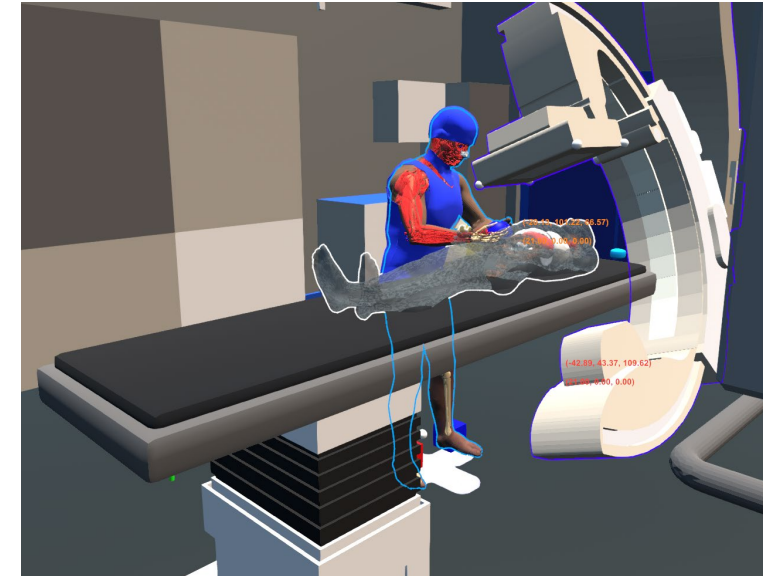
Validation Case	Simulations Accumulated $H_p(10)$	Measured EPD Accumulated $H_p(10)$
EndoVasc CHU-Liège Case 4 (PCI)	39 μSv	23 μSv

Event	FL1	FL2	FL3	FL4	FL5
Time (s)	7	6	6	5	6
RDSR DAP ($\mu\text{Gy}\cdot\text{m}^2$)	536.5	1655.2	1647.7	1347	1646.9
mGy	47.6	217	216	177	216
F6-REF (MeV/g/#)	6.55E-05	4.85E-05	4.85E-05	4.85E-05	4.85E-05
F6-DOS (MeV/g/#)	3.25E-09	9.27E-10	9.27E-10	9.27E-10	9.27E-10
$H_p(10)$ (μSv)	2.36	4.84	4.81	4.73	4.81
Event	FL6	FL7	FL8	FL9	Total
Time (s)	6	6	5	5	
RDSR DAP ($\mu\text{Gy}\cdot\text{m}^2$)	1647.1	1646.7	1496.8	1090.2	
mGy	216	216	196	143	
F6-REF (MeV/g/#)	4.85E-05	4.85E-05	4.85E-05	9.13E-05	
F6-DOS (MeV/g/#)	9.27E-10	9.27E-10	9.27E-10	1.35E-09	
$H_p(10)$ (μSv)	4.81	4.81	5.24	2.46	39

- Difficulties for comparison
 - Low doses
 - Exact dosimeter position is not known
 - Use of protection screens
- Strong dose gradient on the body



- Part of the future will be dosimetry without physical doseimeters
 - Although dosimeters still will exist for many applications
- Results show the validity of the method in interventional radiology and some neutron workplaces
- Still some challenges to be solved
 - Shielding tracking, worker identification
- Increasing contribution from AI and ML
 - “prediction” of doses instead of simulating....
- Important aspect of visualisation of radiation
 - ALARA and training tool
- Expanding to other applications

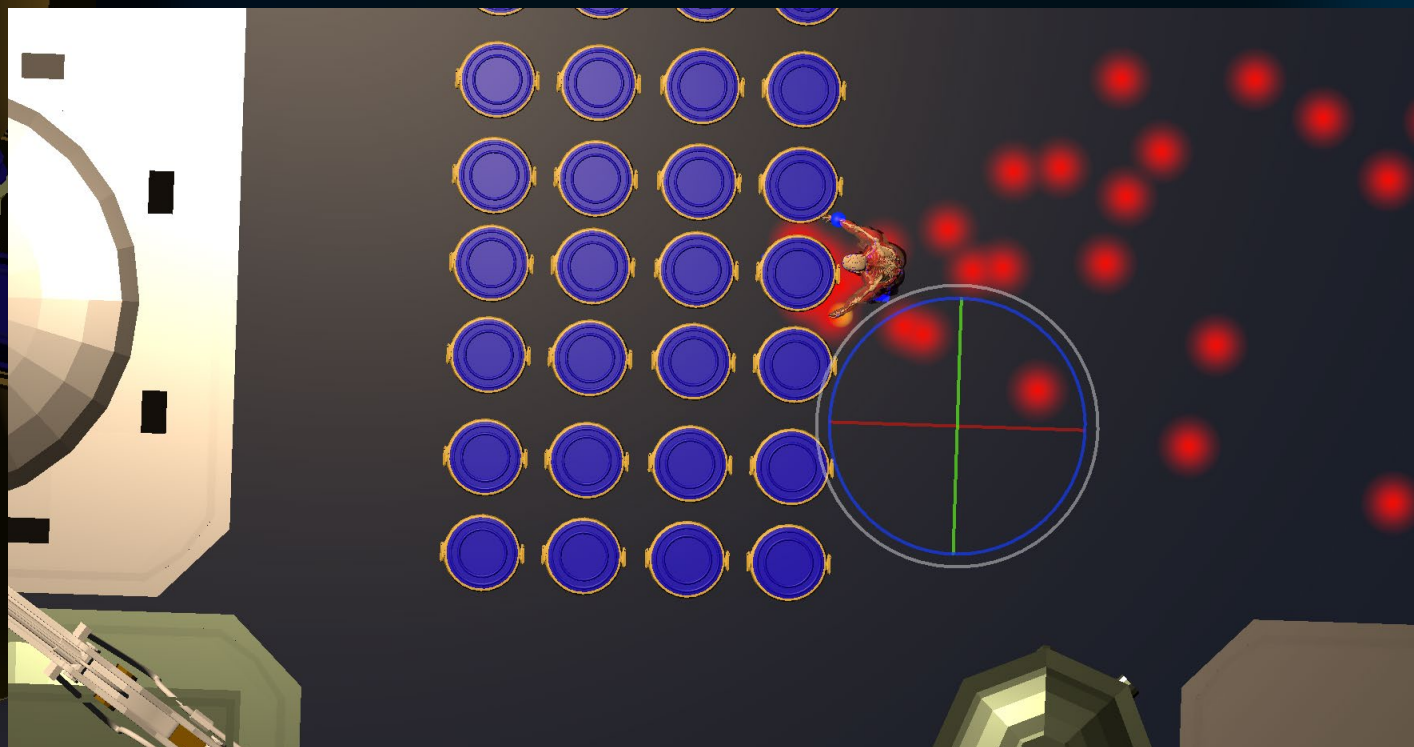
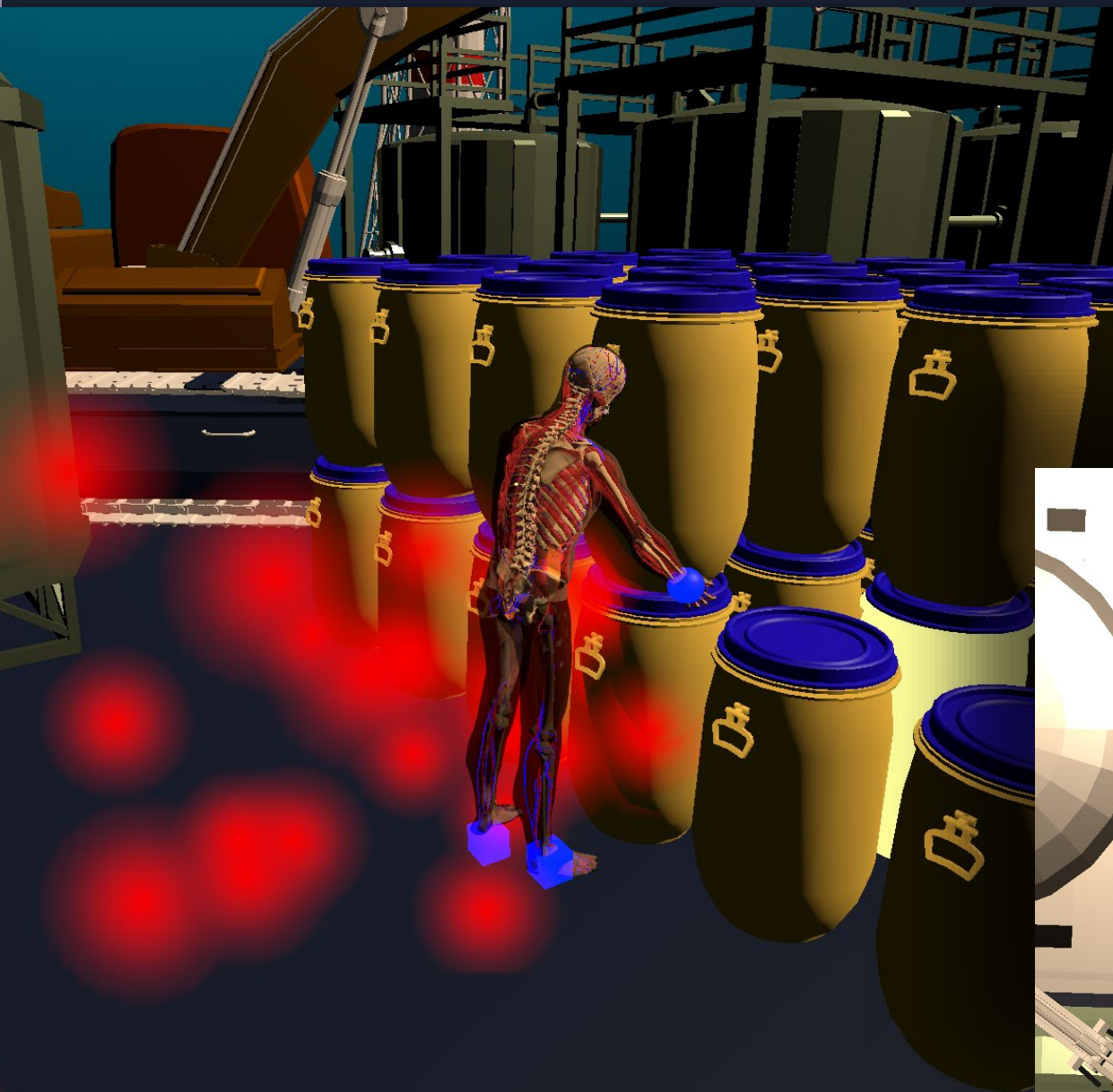


Other applications with RAF Phantom



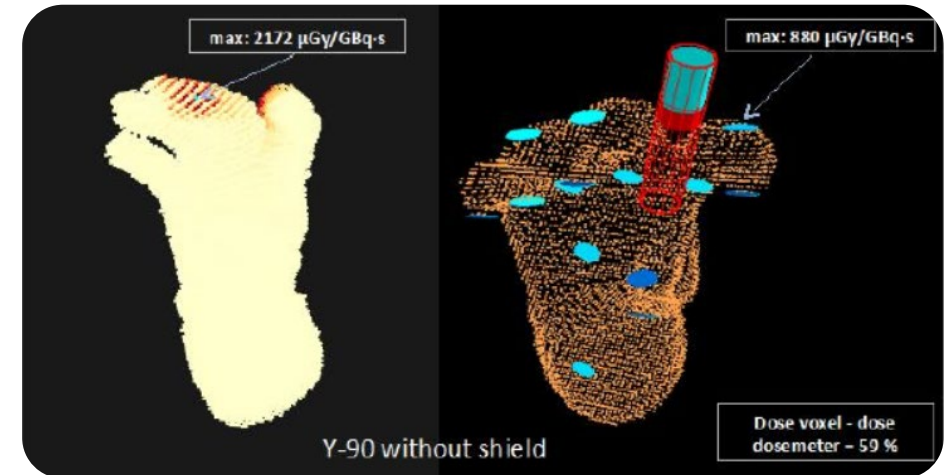
ALARA planning and training tool

- **Accurate** MC simulations using flexible phantoms
- **Planning and analysis** dosimetry tool visualizing data in Virtual Reality environment
- **Neural Network** based framework for optimizing dose calculations



Why improve dosimetry service for nuclear medicine staff?

- **High risk** of exceeding legal doses of radiation in the extremities
- Accurate dosimetry is very **hard** for the hands
 - Higher exposures zones varies from one person to another
 - A single ring dosimeter is not enough to measure the whole hands dose
 - Wearing many ring dosimeters is uncomfortable
 - Multiple dosimeters will make dosimetry service more complex and expensive



Local data acquisition – object tracking

Tailor PODIUM data acquisition solution to fit NM requirements by **developing specialized** ML-based person, fingers and object tracking.

- We cannot rely on already available tracking algorithms especially for **tracking the radioactive source -> vials, syringes**



Train our own Convolutional Neural Network (CNN) using **Tensorflow**

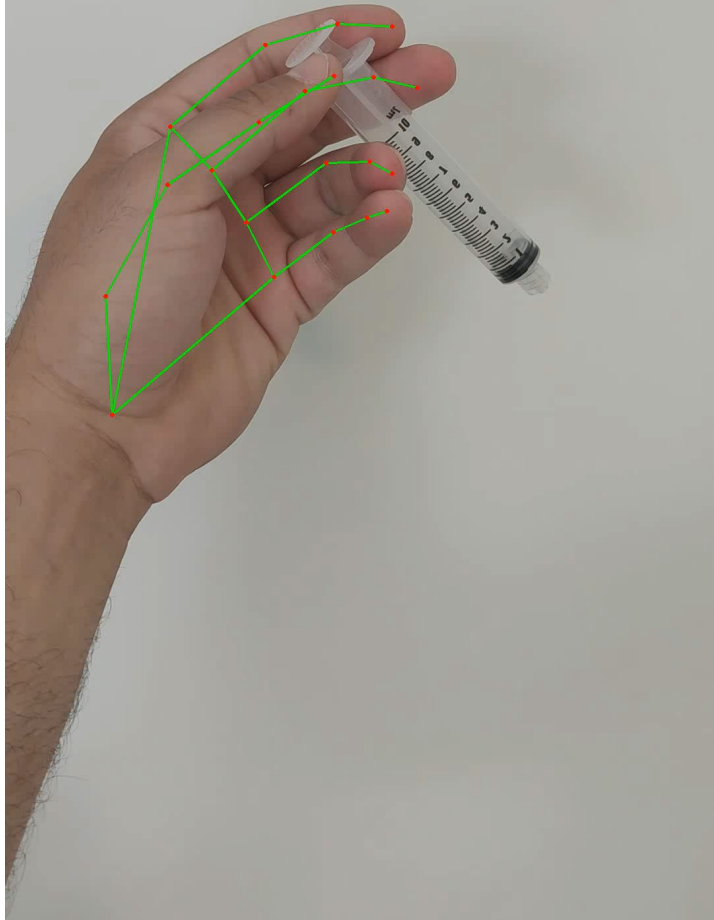


Caffe



Hand acquisition – next steps

acquisition solution to fit NM requirements by using ML-based methods, NM requirements, and data collection methods and solutions and



Mediaripe



Thank you!

We are looking for projects and partners to apply this methodology for different applications!

Filip.vanhavere@sckcen.be



PODIUM Team



HelmholtzZentrum münchen
Deutsches Forschungszentrum für Gesundheit und Umwelt



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EEAE ΕΛΛΗΝΙΚΗ ΕΠΙΤΡΟΠΗ ΑΤΟΜΙΚΗΣ ΕΝΕΡΓΕΙΑΣ
GREEK ATOMIC ENERGY COMMISSION



**Public Health
England**



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