

## Lessons learned from upgrades to the JET RF real-time control system.

#### Alex Goodyear 2021-07-05

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#### **JET Plasma Control System**



#### JET Plasma Control System

- The PCS is distributed, loosely coupled and heterogeneous.
- 80+ real-time subsystems: diagnostics, support functions, controllers, protection, actuators.
- Experimental objectives, with limits to protect plant.
- Actuators receive target references and control within local operator specified constraints.
- 500Hz overall cycle time.
- References can be feedforward or feedback, computed in a number of places.

### **JET Plasma Control System / ICRH**

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#### **RFLM : Radio Frequency Local Manager (controller) Match scientific demand to engineering**

**Experiment Definitions Parameters & Control Technical Systems Global Feedback Jocal Feedback** Real-Time Central Controller Heating (RTCC) (Local Managers) Ion Cyclotron Resonant Heating Group **Positio** Vertical Stabilisation) lasma Shape Density Controller - t = 61.17s - t = 62.20s **Plant Actuators** Magnetics Toroidal & Poloidal Fields) PLASMA Magnetics Heating Density (Ion Cyclotron Radio Electron Temp Frequency, Neutral Beams & Neutron Lowe X-ray Ceramic support Spectroscopy now inside etc. Double vacuum antenna feed through (Ga J1 Heating wing Aux supplies Pellet In cooling codes Figure 1. Overview of Feedback Control Remote handling 4x2MW ICRH transmission JET Control Room Generators EUROfusion 0 line Physics Summary Task Force: C **IVCD** supplies Torus Scientific Coordinator: Unknown 33kV Session Leader: Damian King / Unknown Interspace Diagnostic Coordinator: Ashwin Patel circuits pumping system Engineer in Charge: Adrian Whitehead Date: Friday 18/06/21 (getter) Session Aims: Continuation of NBI conditioning/power demonstration Shift: Early Week: n/a Ip pulse/total ne dl Te PNBIA PNBIA fractio Pre & Post Pulse Pulse Time Bt (bar-L) (x10<sup>19</sup>) (keV) (MW) (MW) (KT5P) JG99.119-3c Repeat, higher NBI 99106 14:15 2.5 2.2 3.59/19.24 10 3.5 6.5 9.5 37 power OK Test load Repeat OK 99105 13:48 2.5 2.2 1.33/15.66 9.5 2.4 5.5 1.6 35 Repeat OK 9104 13:18 2.5 2.2 1.41/14.34 9 2.7 5 1.6 34 Switches Trombone liner trimmer Schematic of ICRH plant for one antenna array (motorised)

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#### **Roles and Responsibilities**

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Plant & RF Engineering





Integrated Control Embedded/Real-Time



Performance Constraints Resilience/Lifetime Optimise Effective Delivery

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#### **RFLM Upgrades: Requirements/Constraints**

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- Upgrades are to
  - To support new RF plant equipment i.e integration of the ITER-like antenna (ILA)
  - To improve plasma control schemes i.e modification to protect the ITER-like wall (ILW).
- Challenges
  - Trade off between improving performance and minimising risk
  - Retrofit behaviour into existing code
  - ITER "actuator sharing"
  - No option of redesigning the system from scratch because of
    - Cost in time and money
    - Risk to the program given the existing maturity
    - Level of confidence based on experience
- => Growth in complexity is inevitable <=</li>

#### **RFLM Evolution : 1996**







#### Designers leverage symmetries

- Elegant
- Comprehensible
- Efficient



### **RFLM Evolution I : Symmetry breaking**

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## **RFLM Evolution I : Symmetry breaking**

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#### Project Requirements.

**"Just"** adapt the existing software – mostly the functionality is the same.





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# **The JET PCS evolution**



- Re-engineered in 2009 to protect ITER like wall (ILW).
- Infra-red camera systems were installed to detect hotspots.
- Real-time protection sequencer (RTPS) was introduced.
- Actuators modified to accept RTPS override instructions.
- Maintain control both for experiment goal AND machine protection.



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#### PLASMA PROTECTION SYSTEM

KY3-FAIL	0.000
SC-SOFT	76.902
SC-FAST	0.000
HIGH-FAIL	0.000

FAST>RF	0.000
SLOW>RF	0.000
STOP>PEL	0.000
SLOW>LH	0.000
TRIG>DM2	0.000
STOP>DM2	65.001

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**Basic protection: pulse termination PTN** Time window / Power window : PEWS Scenario Dependent Variation : RTPS Avoid Thermal Limits : VTM PCS **RF** Actuator





11		Local					JET puise #80455	780
- V (	essel Thermal Map (VTM)	Alarm	Action Time A	ct InOvr	RTPS Output	StopType	1000	760 VTM hot-spot
	• • •	RF A ramp	RTPS 0		Local Response does not vary with Phase	RF_A_rp	A A A A A A A A A A A A A A A A A A A	2 720 A
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		RF D ramp	RTPS 0		Local Response does not vary with Phase	RF_D_rp		620 Heasured temperature 620 DRS temp. thresh.
		RF A stop	RTPS 0		Local Response does not vary with Phase	RF_A_st		60.6 0.8 61 61.2 61.4 61.6 61.8 62 8 Time (s)
		RF B stop	RTPS 0		Local Response does not vary with Phase	RF_B_st		Plasma current wertical position Plasma clearance from top of vesse
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		P 42 inh	RTPS 0		Local Response does not vary with Phase	P42_inh		0.22- Market Mith
		P 43 inh	RTPS 0		Local Response does not vary with Phase	P43_inh	t = 61.17	0.2
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	L. Real-time temperature map display—https/jac based politing @ 4 Hz without compromising real-time performance.	ste <sub>P 45 inh</sub>	RTPS 0		Local Response does not vary with Phase	P45_inh		
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KY3-FAII

0.000

Slow East

RTSP DMV Plant Enable Window System (PEWS)

Mhd2 Mhd MCHS DHS Both Mhdf

Basic protection: pulse termination PTN Time window / Power window : PEWS Scenario Dependent Variation : RTPS Avoid Thermal Limits : VTM Mitigate Disruption : DMV



Basic protection: pulse termination PTN Time window / Power window : PEWS Scenario Dependent Variation : RTPS Avoid Thermal Limits : VTM Mitigate Disruption : DMV

Optimise Performance Continue Mission with Remaining Resources













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#### **RFLM Evolution II : Debrief**

Did all the systems act :

- as expected,
- in all of the modes,
- given all of the observed events?

This turns out to be non-trivial and needs tool support. Correctly identifying edge cases is difficult but important.







# Failure is the chance to do it better next time.

– Henry Ford —

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#### **Software Engineering / System Engineering**

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waterfall is always agile in the long run requirements are always incomplete balance short/long term



extreme rigour : every line of code ⊆equirement extreme agile : rapid code/run cycles

> software costs usually underestimated software volume(t) generally increasing feature creep leads to combinatorial growth

quality software costs are ~ 5x normal

Best modern practice is to measure software quality to manage it better...

### **Growth in Complexity**

- Considerable increases in the McCabe cyclomatic complexity are due to algorithm enhancements or physical plant changes.
- Software release 8131 included the move from a dual 68K CPU setup to a quintuple 68K system.
- Software release 12872 added 3DB calculations.
- Software release 16527 added control of the new ILA Antenna.
- Software release 16776 added RTPS local protection.
  - Software release
     19989 added the
     new Advanced
     Power Control
     Algorithm, but kept
     the ability to select
     the old control
     mechanism.



## **Growth in complexity**

- The new Advanced Power Control Algorithm created 3 new functions
- Complexity greater than 20.



• The drivers of this complexity come mostly from project level decision processes and constraints (backwards compatibility, not all the plant upgraded).

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#### **Root causes of complexity.**



progressing with leaps of faith is risky we prefer safe, incremental change



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stakeholders don't like to throw things away they may need them again in future

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Change nothing quite a lot



Preserve identical behaviour using copy/paste techniques.

> Intentional QA rule breaking. Accept the complexity as the cost of the compromise.

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### **System Testing**

- Challenges
  - Highly complex
    - Internal logic / many interfaces
    - Large parameter space
  - Backwards compatibility non-negotiable
    - Number of features always growing
    - Prove the new ; maintain the old
  - Multi-disciplinary
    - Embedded expert must understand enough RF + POG
  - Law of unintended consequences
    - Must re-examine previous design assumptions
    - Just doing the same as before may not be enough



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- Methodology and supporting infrastructure
  - Simulations running on workstations
  - Offline test rigs that support hardware in the loop testing
  - Toolkit to simulate external inputs, replaying JET data from archive pulses.

Trust/

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#### **Integrated Commissioning**

- Challenges
  - Demonstrate end to end (real world)
  - Minimize machine time required (£\$€₽ ¥¥₩)
  - Don't break anything (high confidence in advance)
  - Avoid test bias with independent test/make teams
- Methodology
  - Use low risk conditions/reduced limits
  - Pulse schedules written by plasma operations team
    - method and pass criteria specified
    - reviewed independently by interface ROs
  - Compress many tests within one pulse
    - Different behaviours in different time windows
    - Can run in the tail of broader commissioning activities
    - Shortens critical path to full science operations
  - Accept risk/time balance
    - Enough variation to cover main behaviours
    - Not feasible to be exhaustive
    - Ultimately ; FOAK ; Experiment





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Procedure
Commissioning of JET Tokamak Systems
Author: M Cleverly Reviewer: D Ciric

#### **Case Study**

- Protection system multi-function combined test within a single pulse
- Units under test:
  - Two "global" stops
    - jump to termination event.
    - total power ramp down (cascades to modules)
  - Four Hotspot warning limits by local module ramp (impacts total power capacity)
    - Ramp down each module (need to check all modules go through path as expected)
    - Local ramp parameters chosen symmetrically : reduce to 50% in 0.5s (each test needs two checks)
  - Four Hotspot alarms by local module stop (impacts total capacity)
- Overall then
  - 10 functional tests, in a short period of the pulse
  - Local ramps run in between the global stops (must still have power to demonstrate)
  - Local ramps staggered at 50ms intervals to enable traces to be identified
  - Local stop sequencing also tuned to be identifiable



Verification of complex hardware designs with timing and logic is supported by specific tools.



Verification of complex systems in PCS would benefit from an equivalent.

#### **Case Study: Lessons learned in test data.**



Cutting back eventually costs more than you save.







Invest in careful test design.

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Allocate sufficient time.

Consider tooling to help check complex traces.



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#### **Summary : regarding RFLM**

- RFLM software has adapted over 25 years to cope with a lot.
  - Maximum freedom to achieve a clean design came at the start. *it was the time of maximum symmetry it was the time of least operational knowledge*
  - Tested and trusted features became essential tools for operations ops team proposed improvements progressively as we learned
  - Each feature change considered alone seems relatively small complexity is multiplicative, not additive.
  - Major engineering changes were encountered (ECT, ILA, ILW, ...) Most physical updates replace predecessors (self contained) BUT – the impact on software requirements can be hard to assess.

The integrated increase in measured complexity is significant and would be a concern but for our thorough understanding of the cause.

#### **Conclusions : more broadly.**

Operations software should be expected to change through the life of a tokamak: this gives resilience and ability to optimise.

Supporting the systems, tools, knowledge and people to achieve this effectively needs significant resource and recognition.

Managing software change can be counter-intuitive

- Keeping old features to reduce risk often increases it.
- Changing operations software regularly is much easier than only touching it during major maintenance outages.
- Some best practices and software quality metrics if strictly followed can compete with operational requirements.
- The output of the software team is invisible and the value may be discounted when it is working well. But it is an essential link in running any machine and if invested in adequately, the ROI will be high.



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