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Overview of the TCV digital real time plasma control system and its applications IAEA 13th Technical Meeting on Plasma Control Systems, Data

Management and Remote Experiments in Fusion Research

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EPFL The TCV tokamak



>390 signals at 10-250 kHz and >10 cameras at 1kHz to be interfaced

- Multi actuators experiment:16 PF coils, 2 Ohmic coils, 8 launchers, >3 gas valves, 6 gyrotrons, 2 NBHs
- Demanding constraint on main plasma control cycle time (<100 us, 10kHz)
- Plant-wide real-time distributed system
- Control research experiment: control system flexible and quick to implement new ideas but rigorous enough to maintain the good ones.

+Flexible digital control system (100% Simulink-programmable)

Swiss Plasma $B_t = 1.5T$, $I_p < 1MA$, a = 0.25m R=0.88m $\kappa < 2.8$ Center

EPFL The digital real-time control system

- > 10 years continuous development -> mature system
- Control code mainly written and maintained in Simulink and autogenerated for MARTe2 capable systems, all data stored in MDSplus
- New: introspective generated code, fully and automatically interfaceable to MDS+ for its run-time configuration
- Various types of interconnected control subsystems:
 - Low latency systems for hard real time control at fastest rate
 - Oversampling systems for fast diagnostics acquisition followed by complex realtime analysis algorithms
 - Multi-core computational systems for CPU hungry codes
 - Real-time vision nodes for vision in the loop systems
- EtherCAT for fast, flexible, distributed and cost effective I/O interconnection



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EPFL Hardware highlights



- Twin multi-core computer main machine control system
- The two computers can run real-time code in parallel on the same discharge (only 1 controlling it though)
- 10 kHz control rate on 192 inputs – 64 outputs system
- Articulated EtherCAT network for agile low bandwidth – low I/O systems interconnection

EPFL Control code handling



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EPFL MATLAB/Simulink MDS+ loader classes



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EPFL MARTe2 based control architecture

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EPFL Supervisory actuator manager and off normal event handling #62441 be in H-mode be in L-mode



 Complete configurable plasma supervisory, actuator manager and off normal events handler to deal with multiple tasks and few actuators



Beta real-time control togther with confinement status (L/H) control via NBH 1

T. Vu et al. IEEE TNS 2021 Plasma Center

Swiss

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EPFL Vision in the loop detachment control

Center



EPFL Conclusions and outlook

- TCV has a state of the art, powerful and flexible digital control system
- Together with the extreme flexibility of the machine, this promotes TCV as a cutting edge facility for plasma control experiments
- A number of domestic and international control activities have been done and are ongoing on this topic
- Its software architecture is very general yet robust, it has allowed the seamless cohexistence of several control modules (e.g. basic plasma control together with advanced actuator manager)
- The system will be expanded in the future by adding additional diagnostics nodes (e.g. real-time Thomson scattering) alongside pure processing nodes



Thank you cristian.galperti@epfl.ch

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