

Scenario optimization and instability monitoring to reach the Q=10 ITER mission without disruptions

by

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with

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and their mitigation**
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Where do disruptions occur? (not where you think)

- Reactor relevant scenarios for steady-state power production are operated at $q_{95} \geq 5$

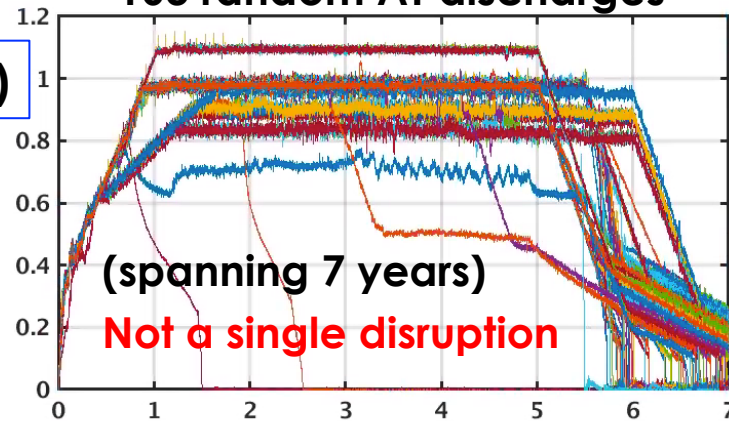
NO disruptions at $q_{95} \geq 5$

- At any β
- With any instability
- With any radiated fraction

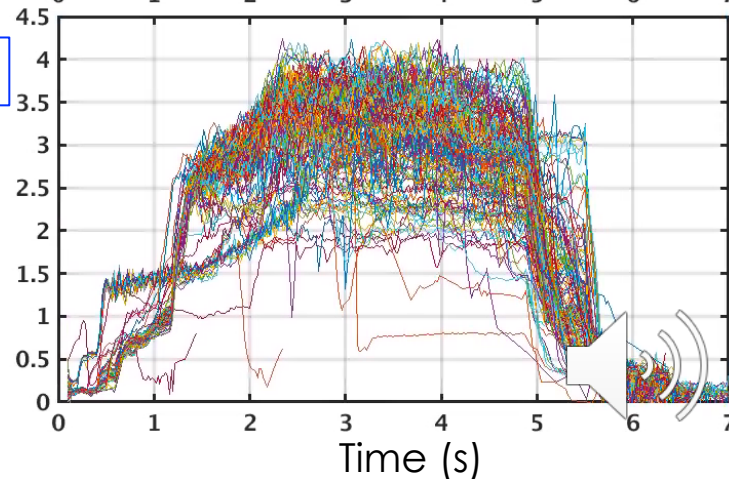
- Physics caused disruptions only occur at $q_{95} < \sim 3.8$**
- Inductive scenario for high gain, pulsed, operation
- **Low β_N , very low J_{NI} , low input power**

163 random AT discharges

I_p (MA)



β_N



I will focus on the low q_{95} ITER Baseline Scenario, where disruptions occur

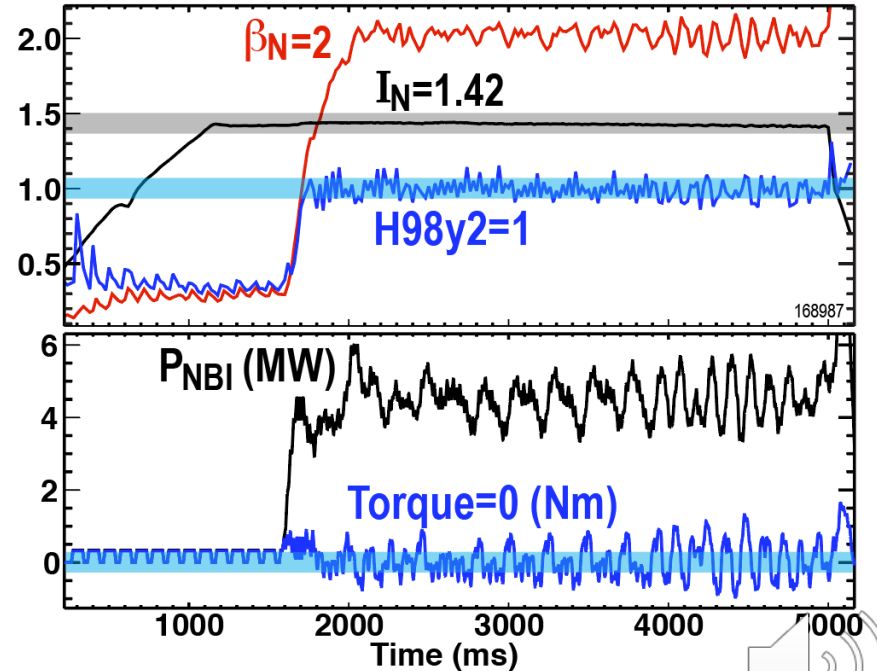
ITER Baseline Scenario demonstrated in DIII-D matching most parameters

Mission:

- 500 MW for 400 s, $Q = 10$ ($G=0.42$)
- Full Bt, $I_p=15$ MA, $I_N=1.415 \rightarrow q_{95}=3$
- Expected $T < 0.7$ Nm, low rotation

DIII-D demonstration discharges:

- ITER shape+ ϵ , $q_{95}=2.9-3.3$
- $H_{98}=1$, $\beta_N=1.7-2.25 \rightarrow G=0.38-0.43$
- $T=-0.5-5$ Nm



Contents

- **Finding the cause of the disruptive tearing modes in the IBS**
- **Modify the scenario to operate in a passively stable state**
- **Why the need for passive stability: negative aspects of off-axis ECCD**
- **A way to measure the approach to instability: Active MHD Spectroscopy**



- **Finding the cause of the disruptive tearing modes in the IBS**
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IBS: Tension Between Stability and Confinement

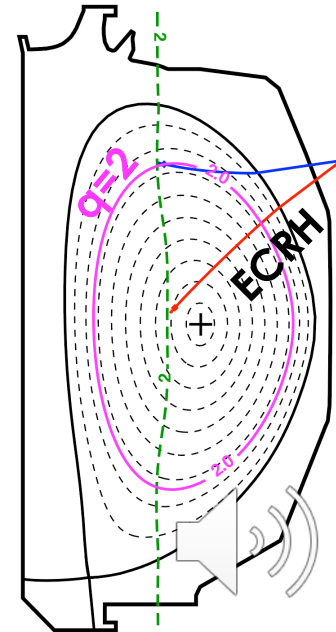
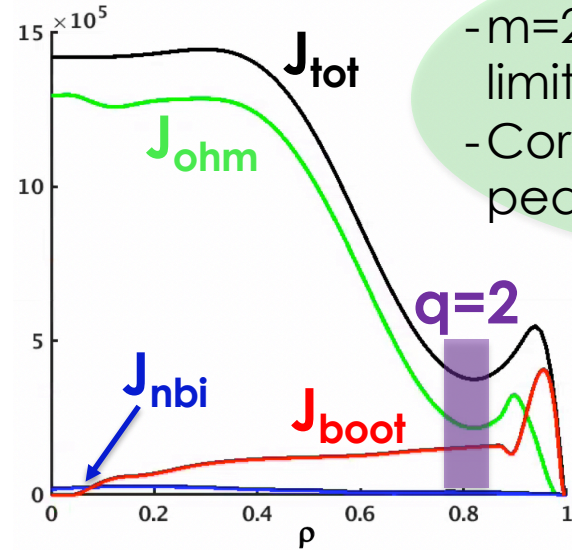
- ITER Q=10 mission: $P_{fus}=500$ MW, high gain \rightarrow **high I/B, low input power**
- $q_{95}=3$ + sawteeth \rightarrow **q=2 near the edge**
- >2017: Passively stable **zero torque** IBS plasmas with NBI+ECH power

STABILITY

- $m=2/n=1$ rotating TMs can limit flattop duration
- Core stability determined by pedestal region

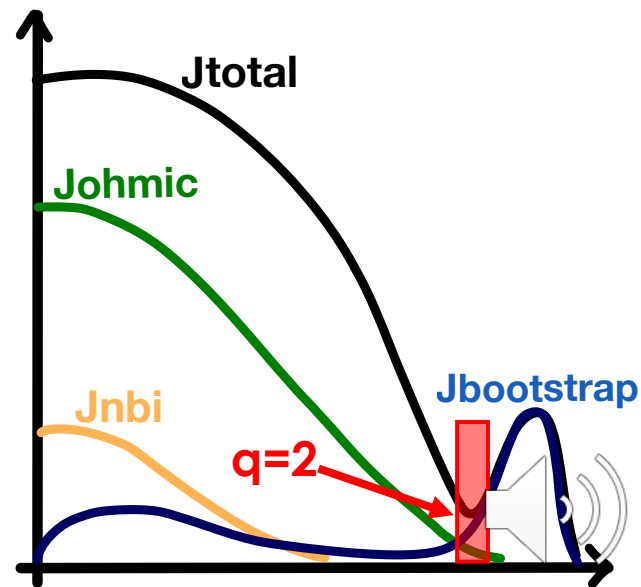
CONFINEMENT

- Direct ECCD stabilization requires far off-axis deposition
- Issue for fusion power and gain



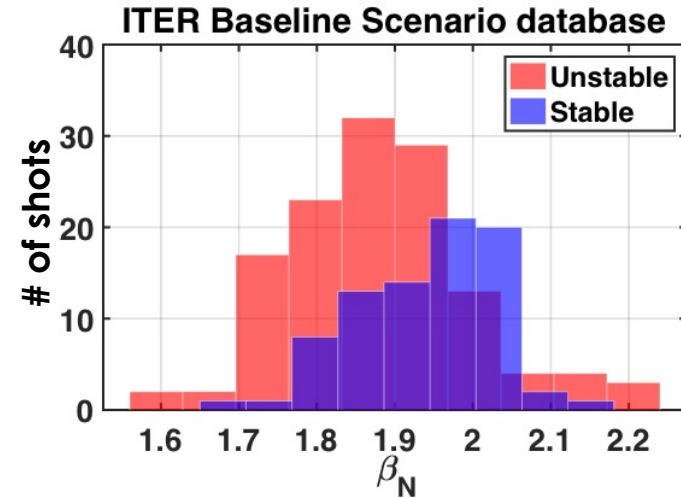
"Unstable" Shots Are Terminated By an $m=2/n=1$ Tearing Mode

- The plasma current is mostly **inductive** \rightarrow J profile tailoring by NI sources is ineffective (CD is not a viable actuator)
- J_{boot} dominates the pedestal, **$q=2$ at $\rho \sim 0.8$** \rightarrow Strong correlation with pedestal/edge due to fixed I_p
- Many **shots are terminated by a 2/1 tearing mode**
 - At high and low torque
 - It locks and disrupts within 50-150 ms
 - ECCD stabilization isn't effective (low T_e , j_{CD} ; fast growth, lock)



The IBS Instabilities Are **Not** Due to a β_N Limit

- The modes appear after $>10 \tau_E$ at **constant pressure**
- **Well below the no-wall MHD limit**
- **Lower β_N** does not lead to better stability



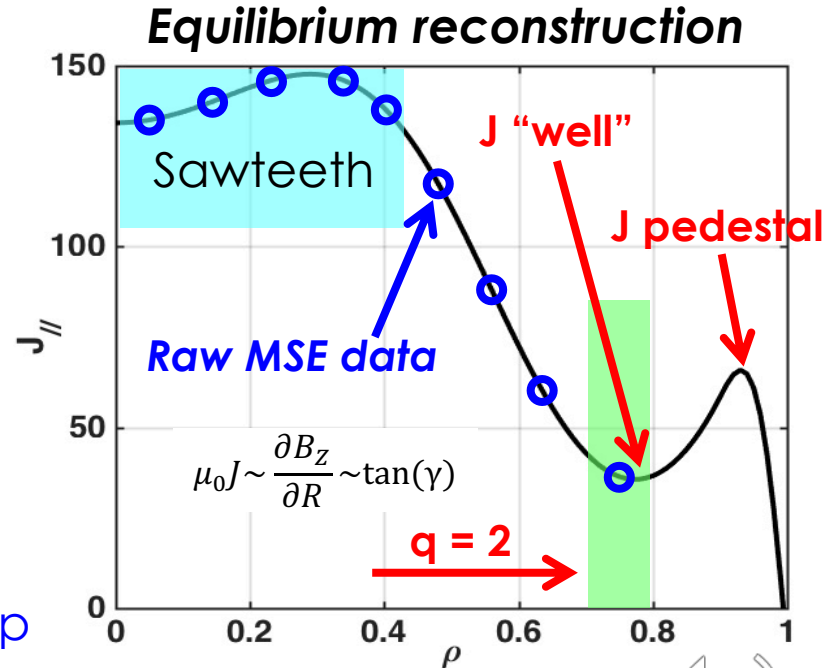
These are very likely classically unstable TMs,
not NTMs:

- Onset after 10s sawteeth, ELMs, 100s τ_{tear} at fixed pressure \rightarrow on τ_R scale
- J_{boot} is very small everywhere, and minimum at $q=2$ (inductive!)
- $J_{\text{eccd}}/J_{\text{boot}} > 1-2$ does not stabilize (Δ' is the drive, not J_{boot})



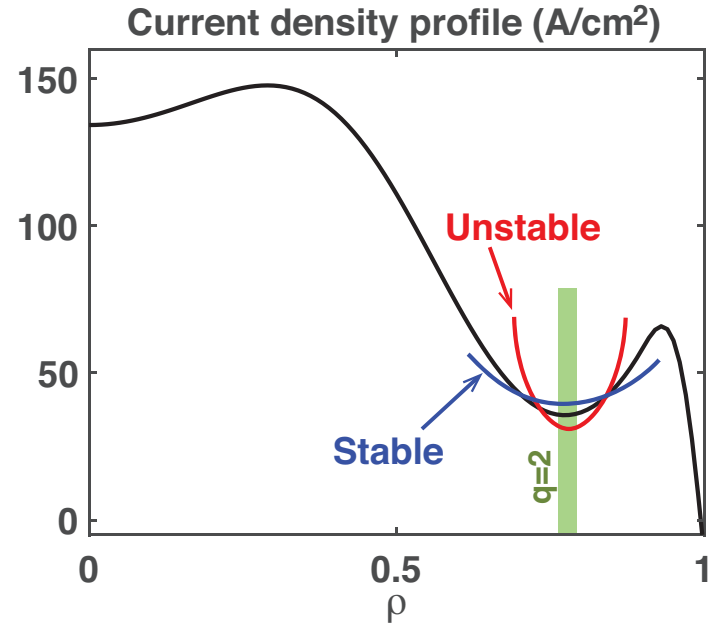
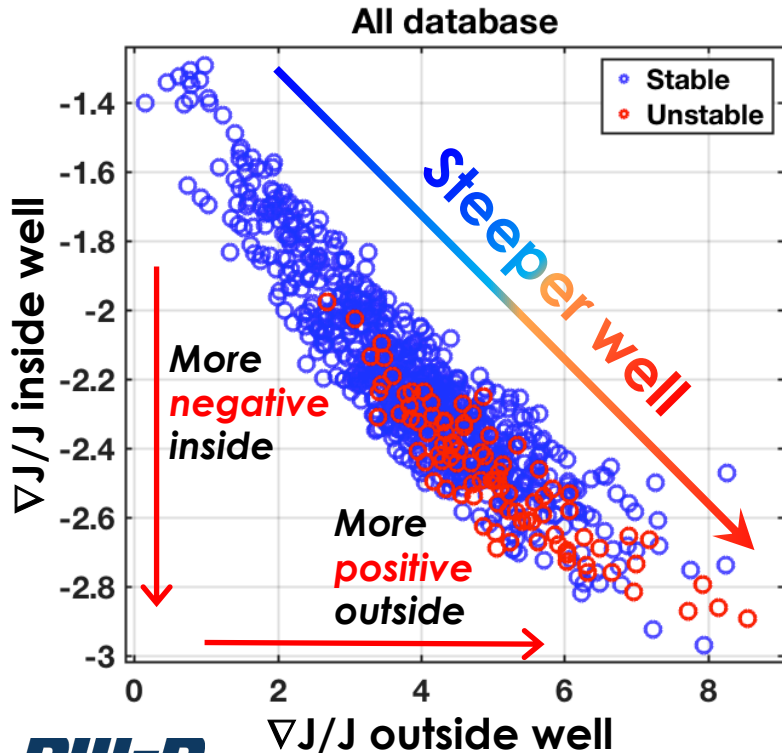
Database of ~240 IBS Plasmas Analysed for Global and Local Quantities

- Local current density measured by raw MSE data
- “Enhanced” efits for q and J, with MSE+magnetics and a pedestal
 - Magnetics + edge constraints describe the pedestal (similar to kinetic efit)
 - MSE constrains the core up to $\rho \sim 0.8$
- Unstable = at time of 2/1 mode onset
- Stable = stable time slices on the β_N flattop



Changes in the Current Profile Are Correlated with Tearing Instability

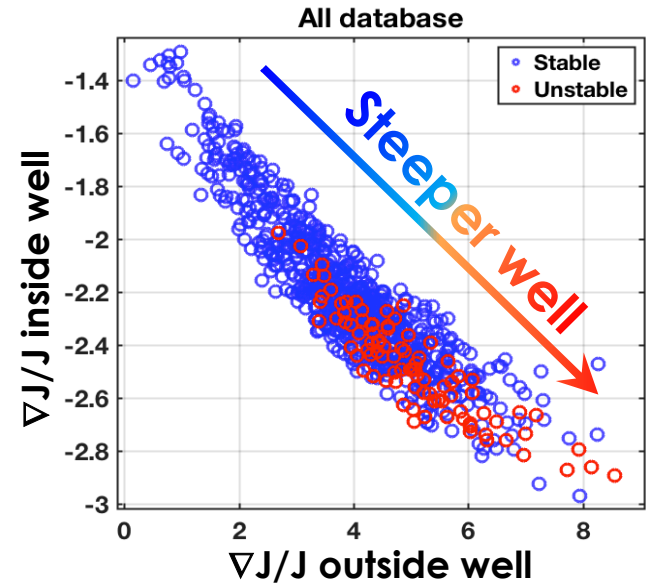
- **Unstable points** fall predominantly in the lower right region (larger gradients)



Unstable points have **steeper** "current well" around the q=2 surface

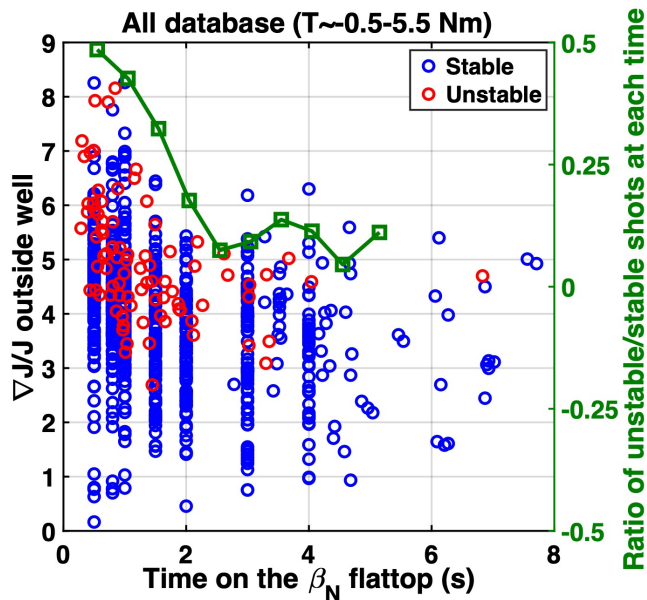
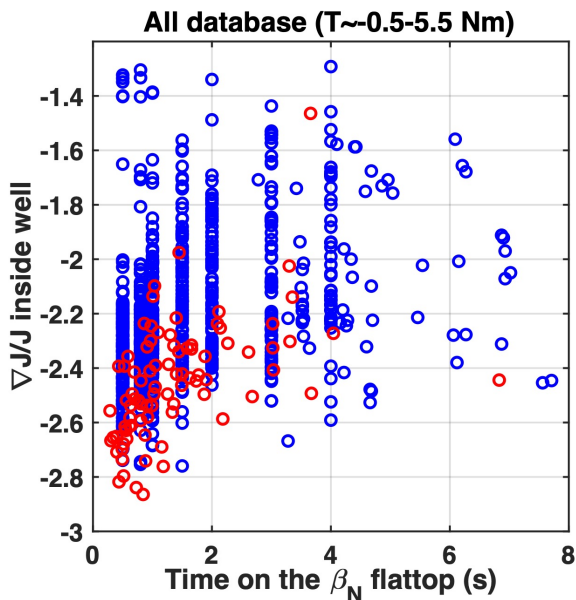
Changes in the Current Profile Affect the Classical Tearing Index Δ'

- Long term dependence on J suggests stable and unstable times have different Δ' : classical drive
- Δ' is a GLOBAL parameter, determined by all the current profile
- $\Delta' > 0$ is necessary, not sufficient for instability:
 - Δ' trends determine if more/less stable
 - For instability, $\Delta' > \Delta'_{crit}$ (inner layer physics)



67% of the Instabilities Occur Before 1.3 s on the β_N Flattop (1-1.5 τ_R in DIII-D)

- More stable current profile late, **fewer unstable shots after ~1 s**
→ if we **solve the access problem**, high probability of remaining stable



∇J separation is independent from torque, sawteeth, ELMs, higher m/n modes



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Database study indicates that the early current evolution is crucial for stability → created new β_N ramp up recipe

Changes l_i , current penetration



Changes ELM frequency, pedestal (not density)

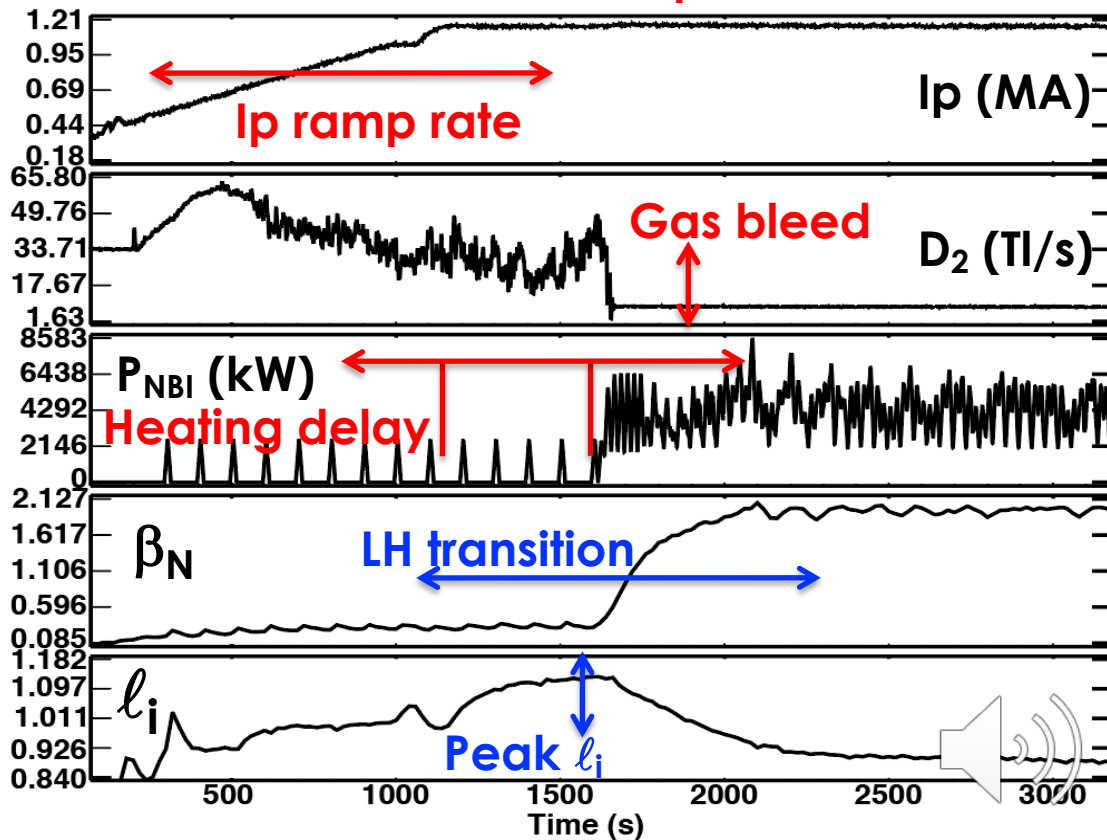


Changes l_i , current penetration



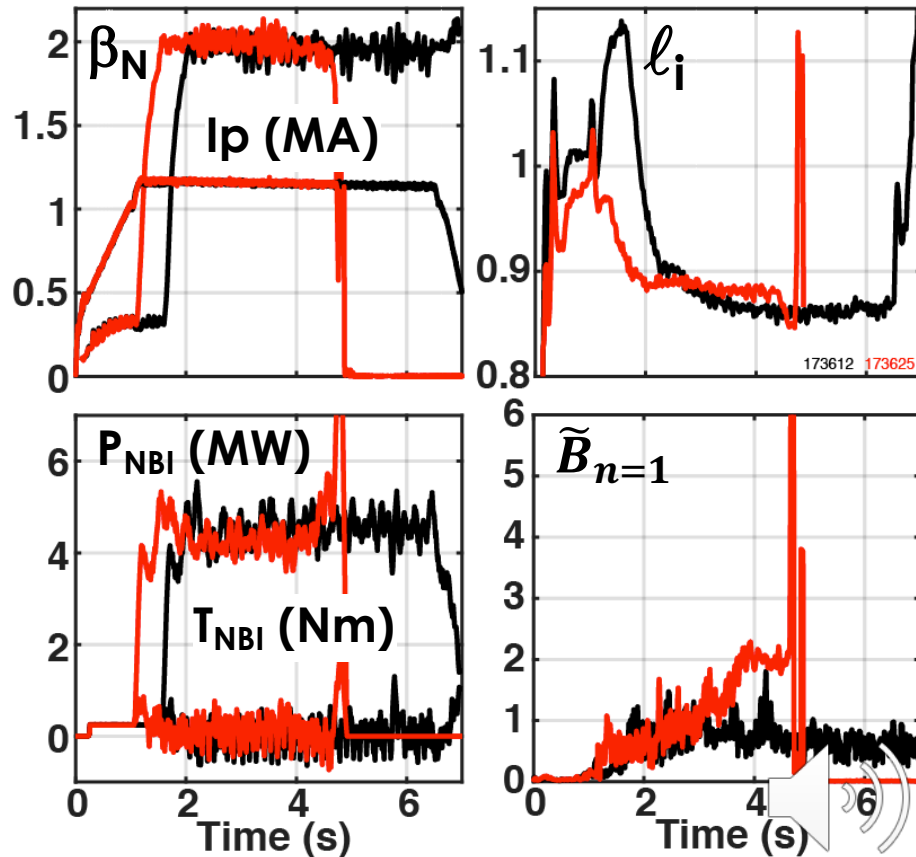
No time to scan the L-mode density/gas

Fixed zero torque



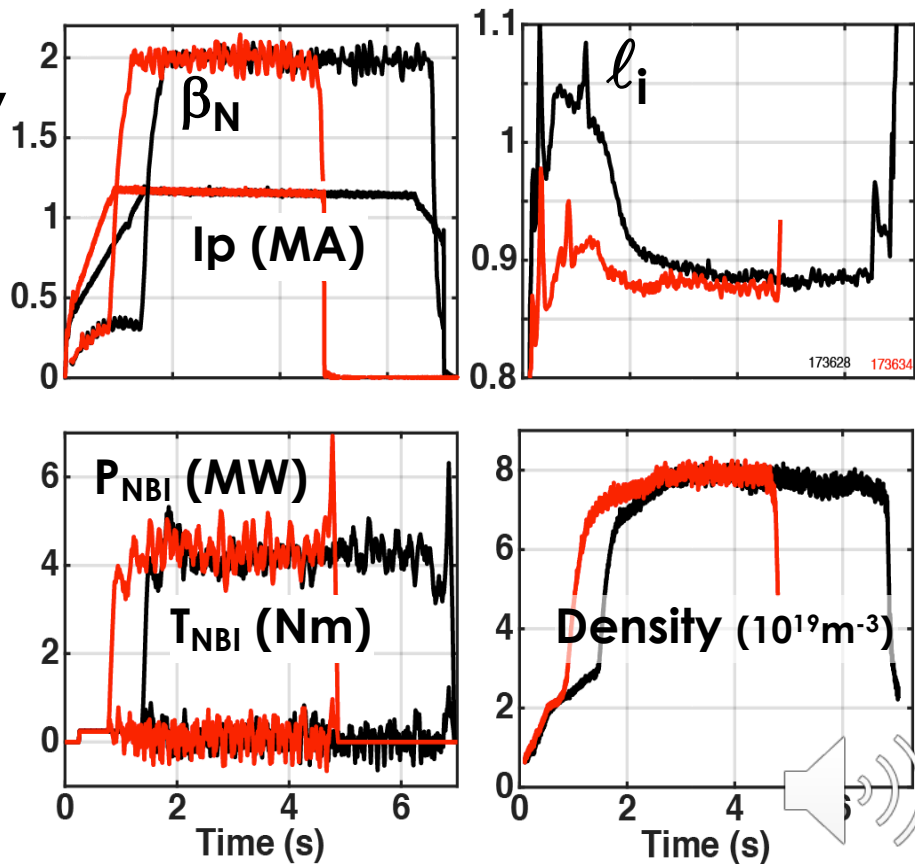
Applied modifications to show causality. (1) Heating delay

- Database of pulses with only change to the H-mode transition time shows the late timing is robustly stable
- Trajectory of l_i shows current profile evolution is different
 - l_i is not sufficient to predict stability



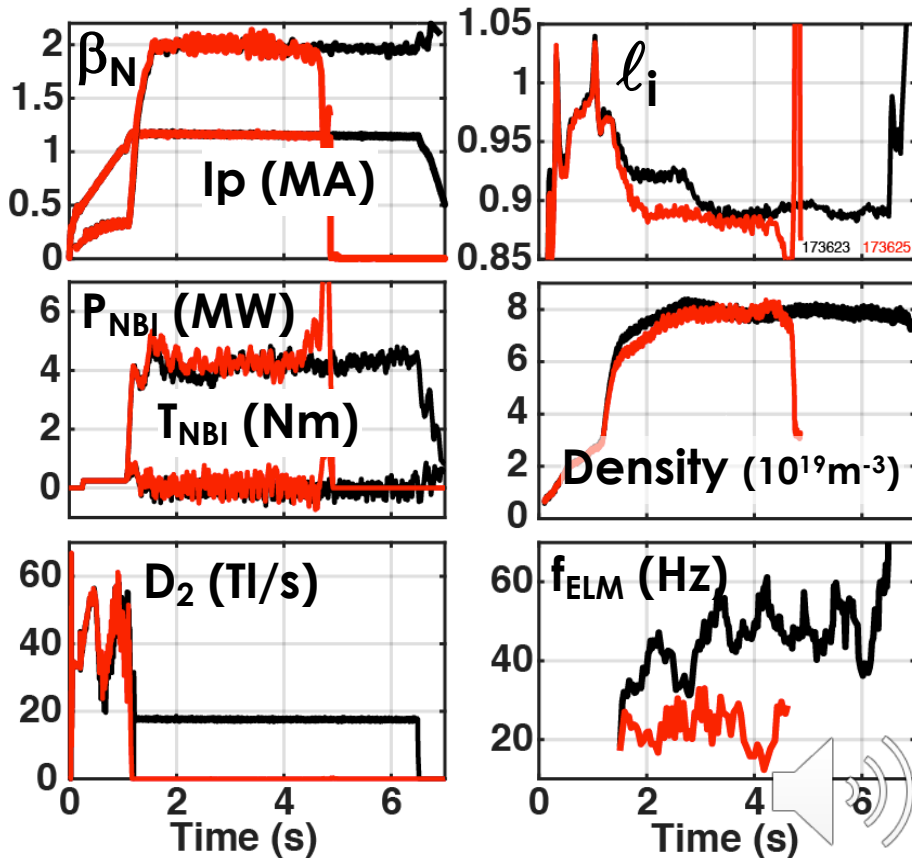
Applied modifications to show causality. (2) I_p ramp rate

- Slower I_p ramp rates are robustly stable – similar effect as heating delay
- Combination of I_p ramp and heating time changes can tailor the stability to the hardware requirements



Applied modifications to show causality. (3) D₂ gas "bleed"

- Modest gas "bleed" eliminates LATE modes
- Results in more regular and more frequent ELMs
- Little difference in density
- No difference in energy confinement

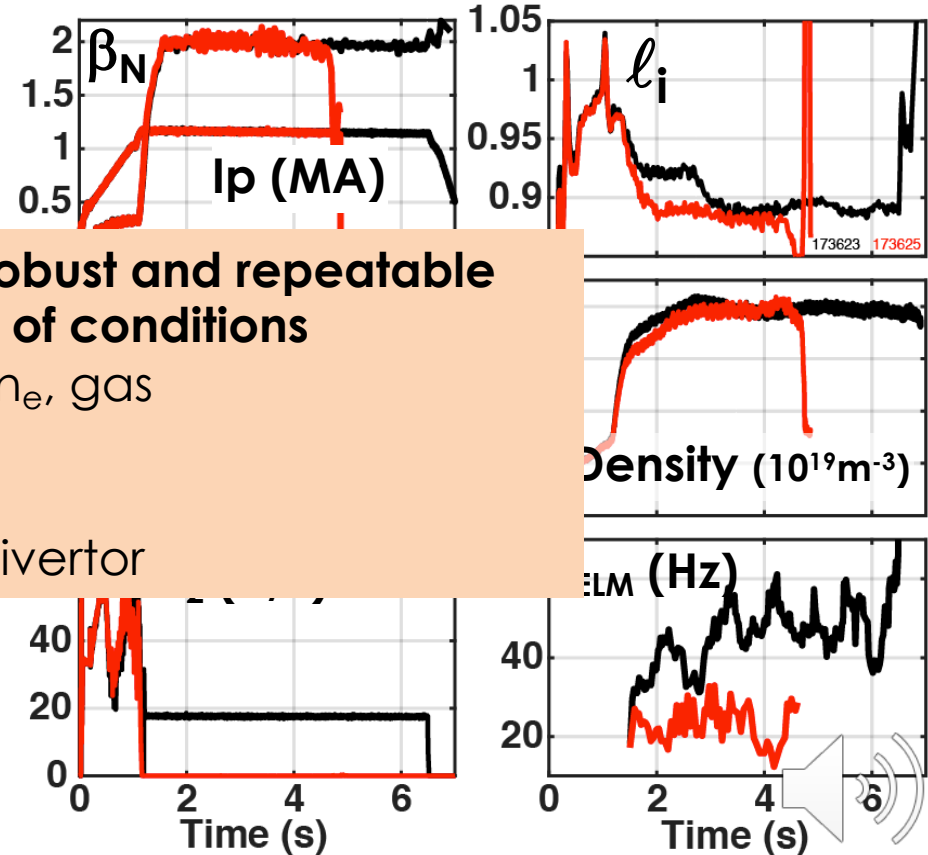


Applied modifications to show causality. (3) D₂ gas "bleed"

- Modest gas "bleed" eliminates LATE modes
- Results in more frequent ELMs
- Little difference in confinement
- No difference in confinement

The passive stability is robust and repeatable under a variety of conditions

- Different I_p , B_T , n_e , gas
- Wall conditions
- Heating mix
- Open/closed divertor



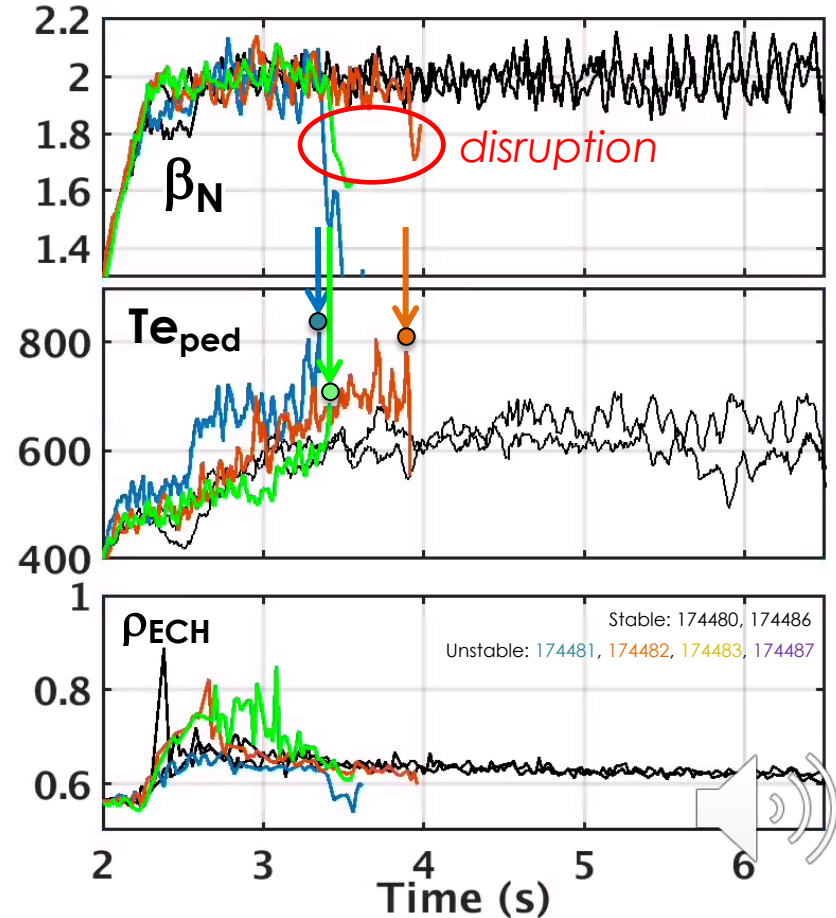
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Effect of e- Heating: Early ECH Deposition Location Can Negatively Affect the TM Stability

- Rising $T_{e_{ped}}$ \rightarrow 2/1 mode
- Sometimes correlated with $\rho_{ECH} > 0.85$, but other factors apply
- Some cases are at the marginal point: small perturbations can cross the threshold

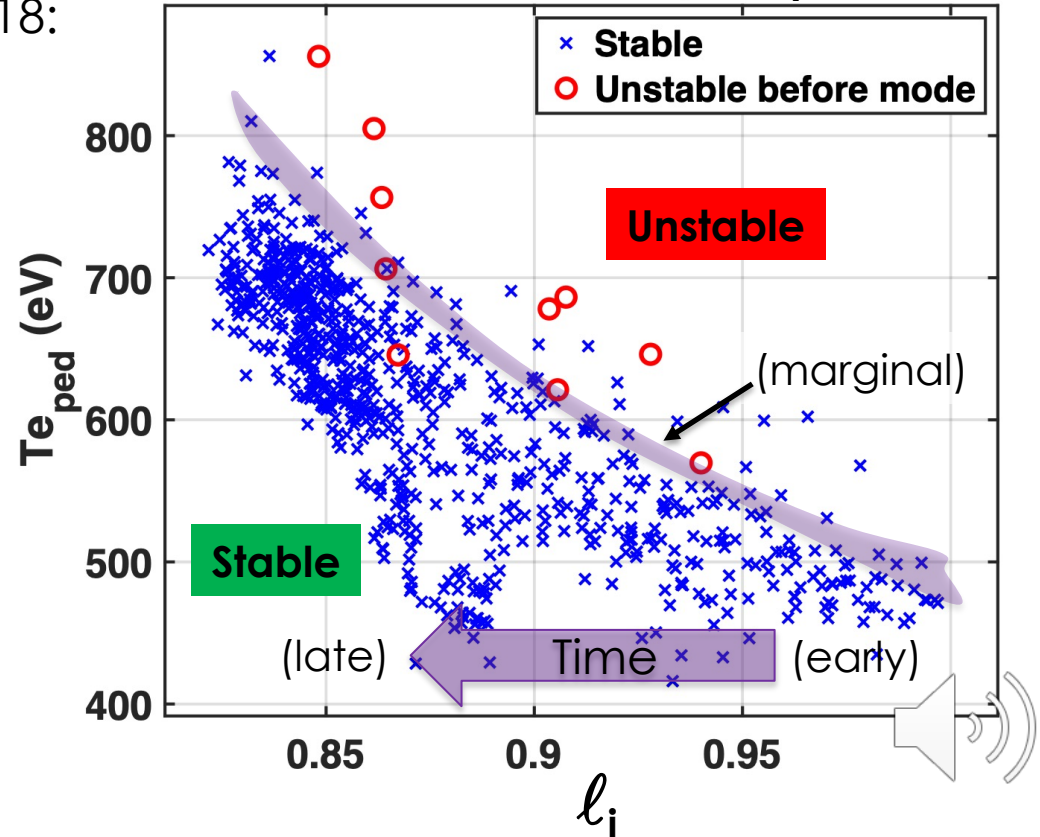


l_i Sets the $T_{e,ped}$ Threshold: Global Classical Δ' Effect

Expanded database of all 2017-2018:

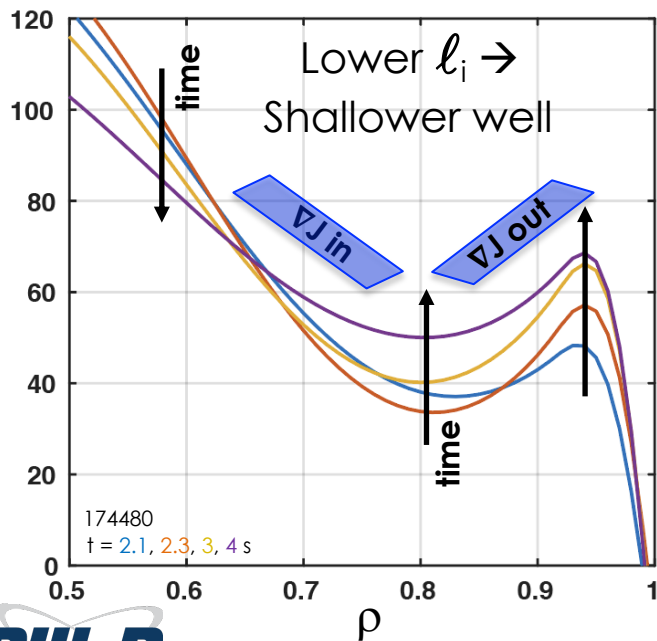
- Timing matters: **higher $T_{e,ped}$ late can be stable**
- l_i decreases \rightarrow the well is shallower \rightarrow **equilibrium can survive a higher pedestal**
- **Effect of T_e on $J_{pedestal}$ is the limiting factor** (not absolute T_e !)

IBS database with ECH and Torque = 0 Nm

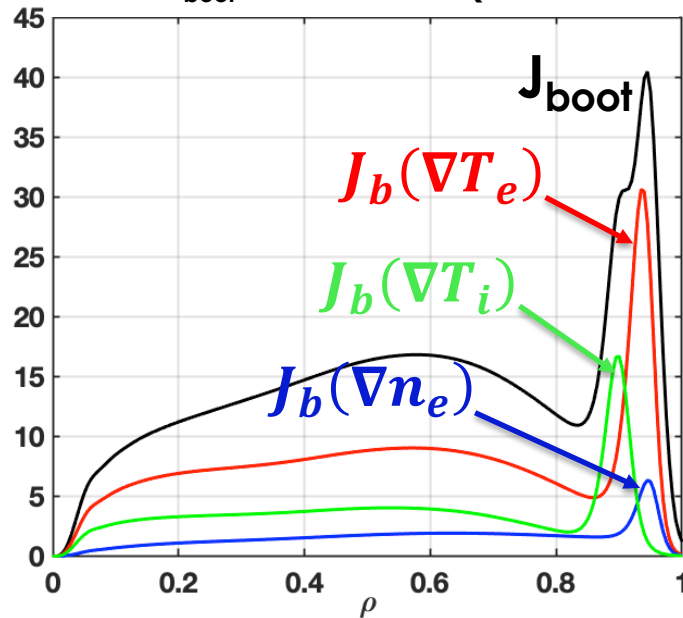


T_e Has a Much Larger Impact on J_{boot} than n_e, T_i in These Plasmas

- J profile responds to local J_{boot} changes due to fixed total plasma current
- Classical tearing index Δ' changes as a function of global J profile



Calculated J_{boot} contributions (Sauter model)



ECH Power Near $q=2$ is Significantly Detrimental to Performance

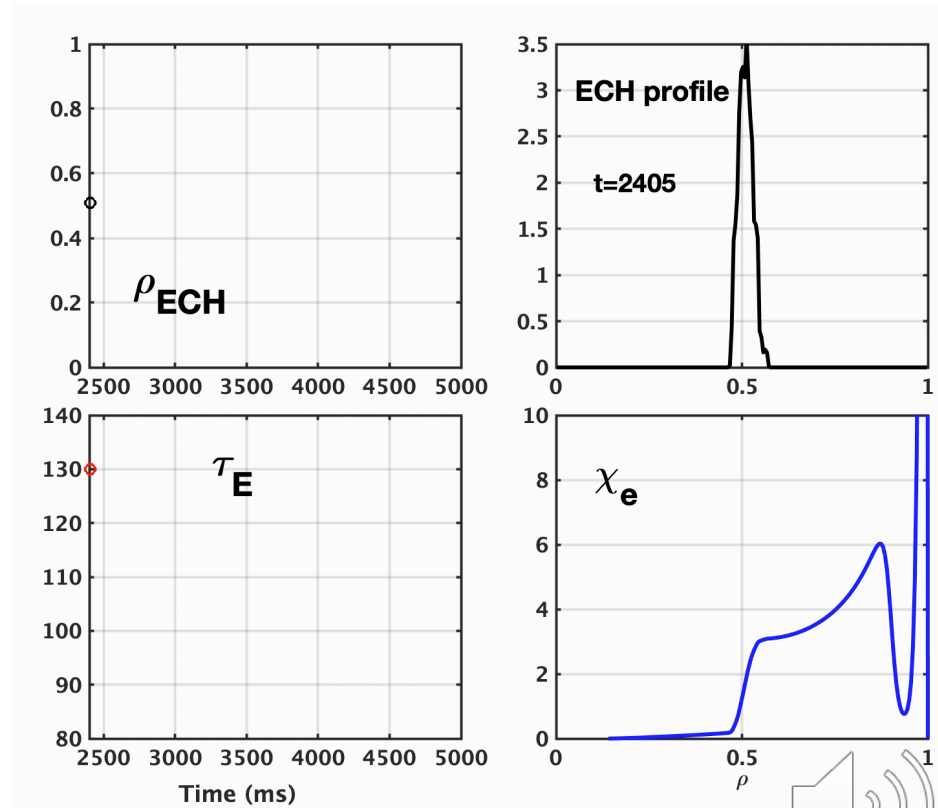
- Moving 3 MW of ECH from $\rho=0.5$ to $\rho=0.8$ decreases τ_E by 25-30%, H_{98y2} by 15-18%

$$\eta_{\text{heating}} \approx 1 - \rho_{\text{ECH}}^2$$

Expect 50% drop in τ_E , observe 25%



Loss of heating efficiency
compensated by transport
improvement



This is also observed clearly in the full database (220 shots)

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MHD Spectroscopy Measurements Shows the Approach to a Stability Limit

- Reduced IBS database at $T=0-1$ Nm
 - $n=1$ external field rotating at 20 Hz
 - Magnetic probes measure the plasma response of the external kink
-
- **Signals: response amplitude & phase vs external field**
 - **Phase shows a "jump" when approaching a limit**

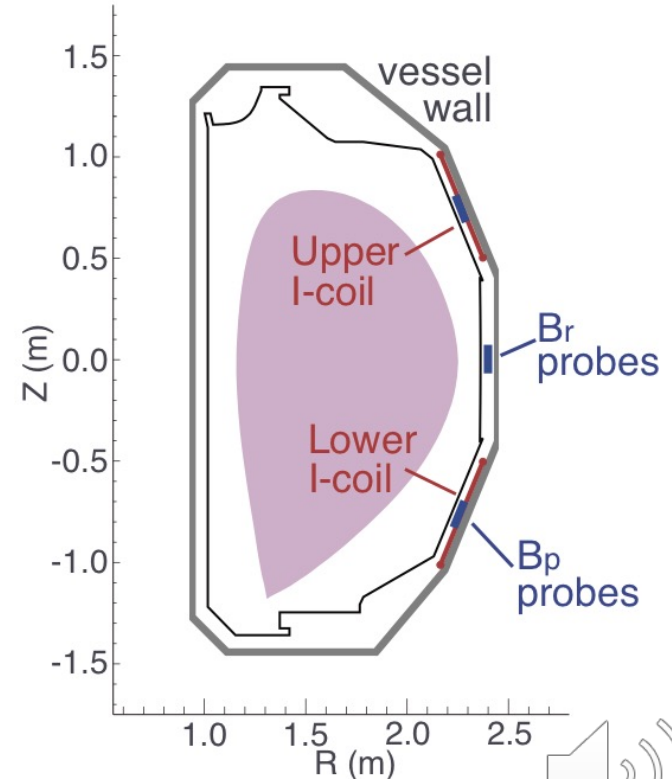
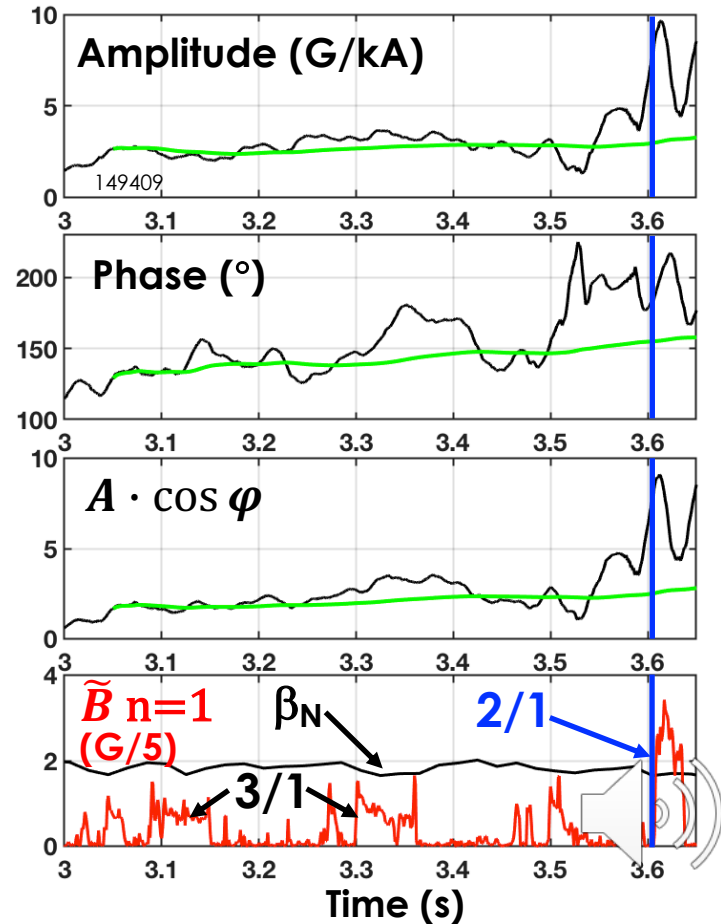


Figure courtesy of J. Hanson

Realtime AMS Signals May Become a Stability Sensor

- IBS plasmas have intermittent 3/1 bursts and 1/1 sawtooth precursors
- Spectroscopy amplitude and phase changes are largest with large 2/1 component
- Relative measures help discard false positives – intrinsic dependence on β_N , ℓ_i

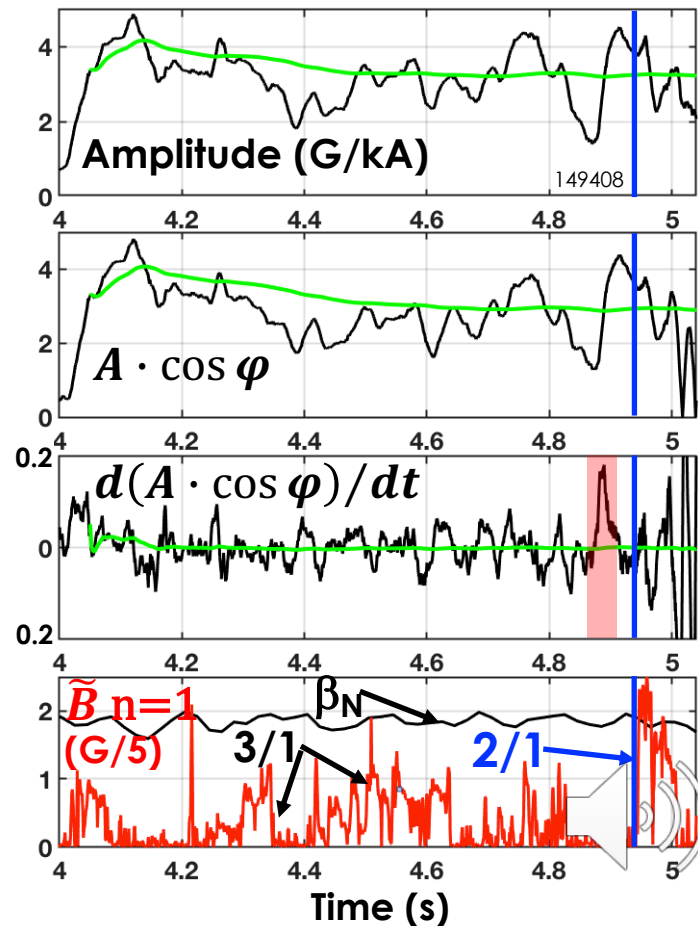
Use A , φ , $A \cdot \cos \varphi$ – shot average



Realtime AMS Signals May Become a Stability Sensor

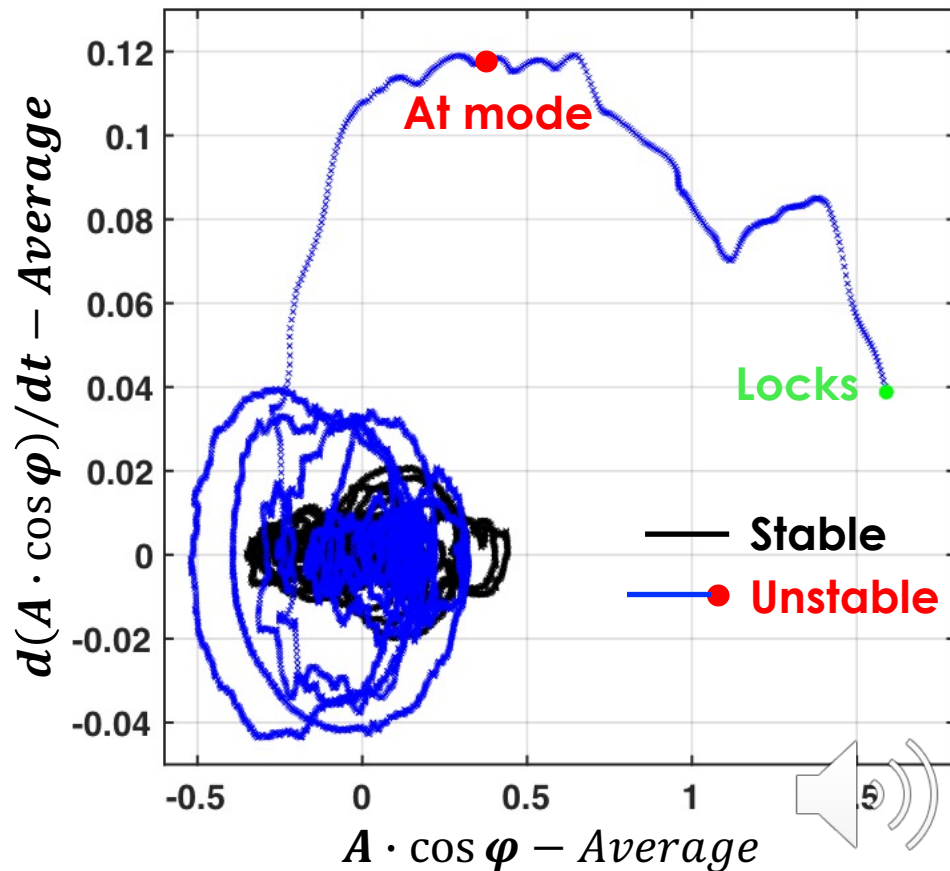
- When the 3/1 activity is stronger and continuous, **the derivative of the signals is a good indicator of the 2/1 mode**
- Slowly growing 2/1 modes are harder to detect, but in that case **spectroscopy picks up imminent locking**

→ Deploy disruption mitigation systems



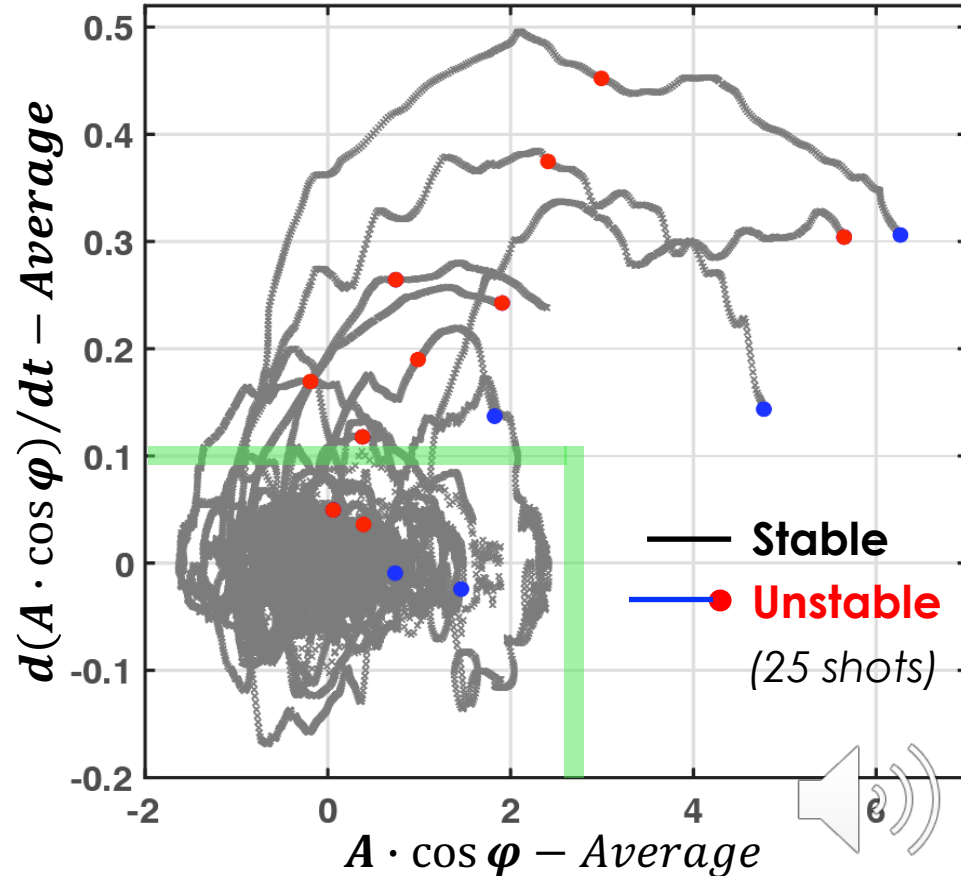
In Stable Shots, A and φ Show Little Excursion from Average

- To generalise and quantify, chose evolution of
$$A \cdot \cos \varphi, d(A \cdot \cos \varphi)/dt$$
- Compare to shot average (plasma response typical of that shot $\leftarrow \beta_N, \ell_i$ dependent)
- **Unstable shots** shoot out of stable envelope at **time of mode**



Careful Choice of Limits can Lead to a Real-Time Sensor

- Limits of stable envelope can be used to define **sensor trigger values**
- Other choices of signals are possible, depending on the scenario parameters



Conclusions

- “Physics driven” disruptions are only relevant to low q_{95} (pulsed) inductive scenarios
- In the IBS there are no good actuators to rein in the instabilities (no JNI, JECDD fails to stabilize the modes, off-axis power prevents to reach the goals)
- Passive stability is the best option, and it has been demonstrated
- Indirect actuators may be an option if the conditions evolve on the flat-top: squareness and triangularity changes

Preview on effect of shape on current density and stability

Small shape changes can change the pedestal during the flattop

