



Prevention of the H-mode density limit by various heating schemes through control of the plasma state space

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IAEA Technical Meeting on Plasma Disruptions and their Mitigation, 20-23 July, 2020 (Virtual Meeting)

EPFL



This work has been carried out within the framework of the EUROfusion Consortium and has received funding from the Euratom research and training programme 2014-2018 and 2019-2020 under grant agreement No 633053. The views and opinions expressed herein do not necessarily reflect those of the European Commission.



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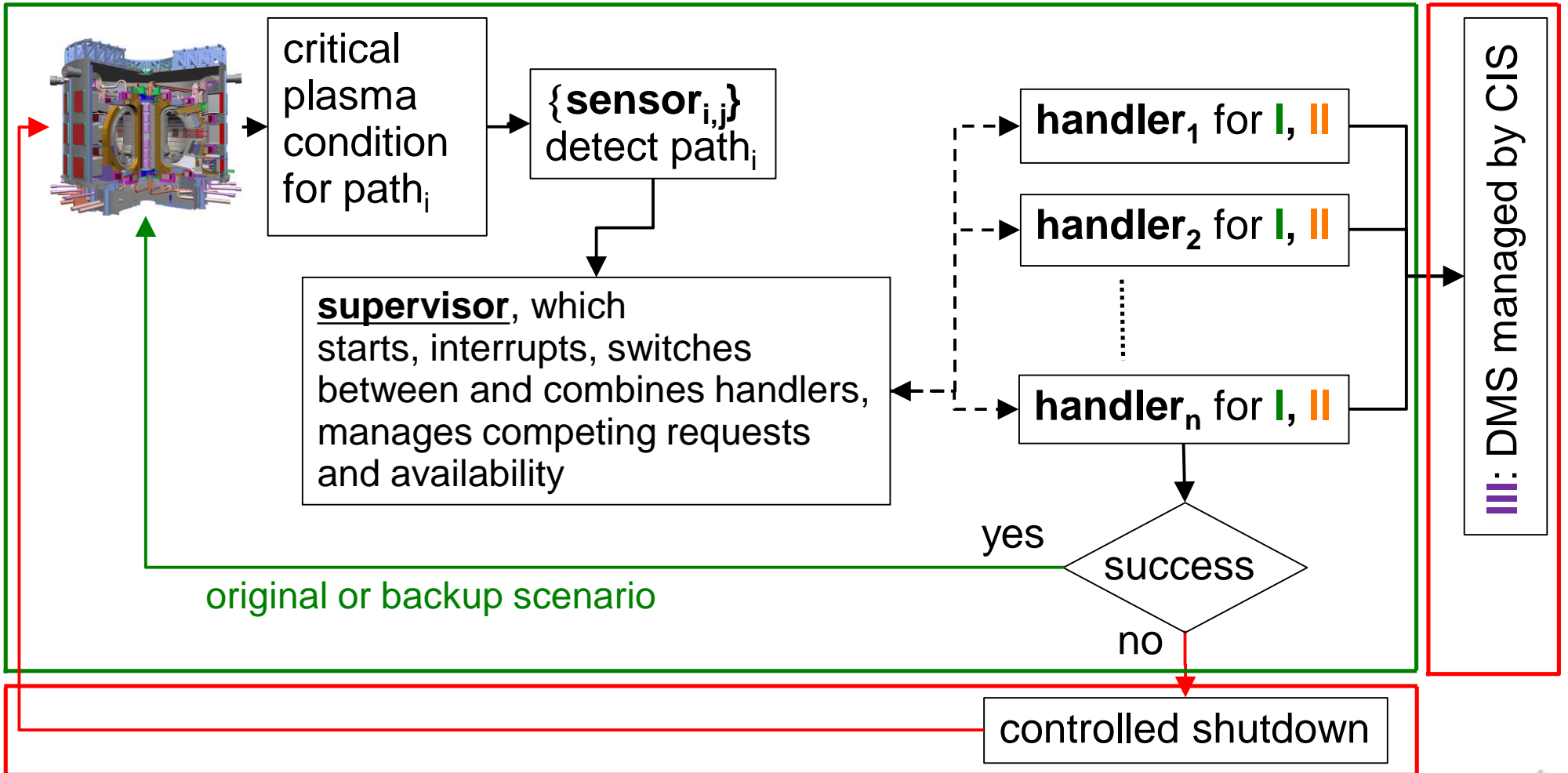
M.Maraschek, A.Gude, A.Pau, O.Sauter, B.Sieglin, C.Sozzi, T.Vu, E.Alessi, M.Bernert, V.Bobkov, T.Eich, E.Fable, F.Felici, C.Galperti, F.Janky, O.Kudlacek, R.Ochoukov, G.Pautasso, N.Rispoli, J.Stober, M.Wischmeier, H.Zohm, ASDEX Upgrade team, TCV team, MST1 team

- Integrated disruption prevention scheme
- State space description of HDL in D_2 at ASDEX Upgrade and TCV
- State space based controller at ASDEX Upgrade and TCV
- Influence of $N_2 \Rightarrow$ alternative sensor and controller setup
- Summary and outlook

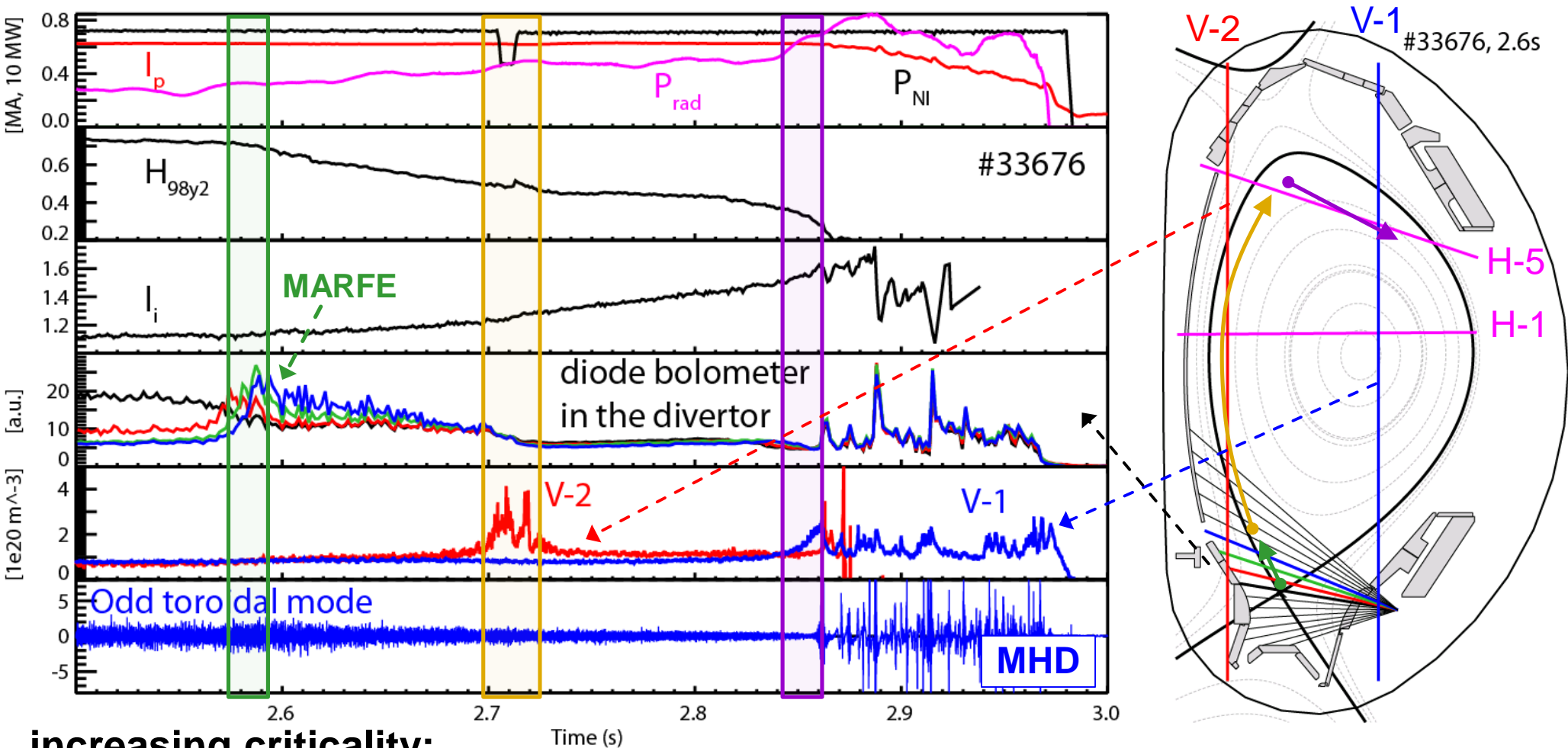


Outer flow diagram for all disruption path_i's, controlling handler_i

hierarchy of actions: **I: recovery** **II: avoidance** **III: mitigation**



ASDEX Upgrade and TCV : H-mode density limit



increasing criticality:

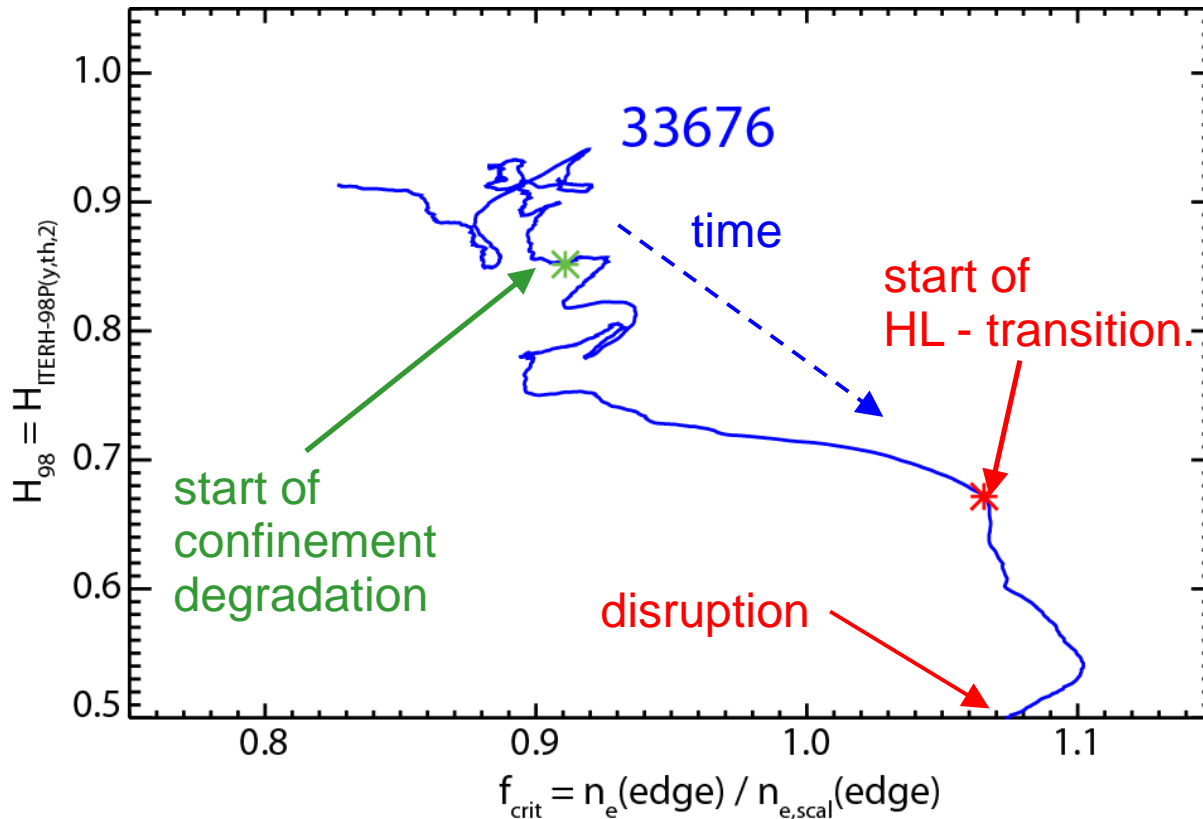
- MARFE enters confined plasma (seen on div. bolometer, with / after HL-transition)
- migration from X-point to top on HFS (bolometer, HFS interferometer)
- movement towards plasma LFS (bolometer, HFS interferometer)



- Strong W_{mhd} and H_{98y2} drop with MARFE formation before MHD:
 - In present devices early MARFE can be recovered with heating
 - In future devices $P_{\text{fus}} \sim \beta_N^2$ loss makes plasma unrecoverable
 \Rightarrow action required significantly before MARFE
- With lower q_{95} the time between MARFE and disruption might shrink
- Scaling for **start of H to L – transition**:
$$n_{e,\text{scal}}(\text{edge}) = 0.506 P_{\text{heat}}^{0.396} I_p^{0.265} q_{95}^{-0.323}$$

determined from **state space**: $W_{\text{mhd}} - n_e(\text{edge})$

Normalized state space: $H_{\text{ITER-98P}}(y, \text{th}, 2) - n_e/n_{e, \text{scal}}$



start of "HL-transition" :
 (shortly) before MARFE
 moving into confined
 plasma region

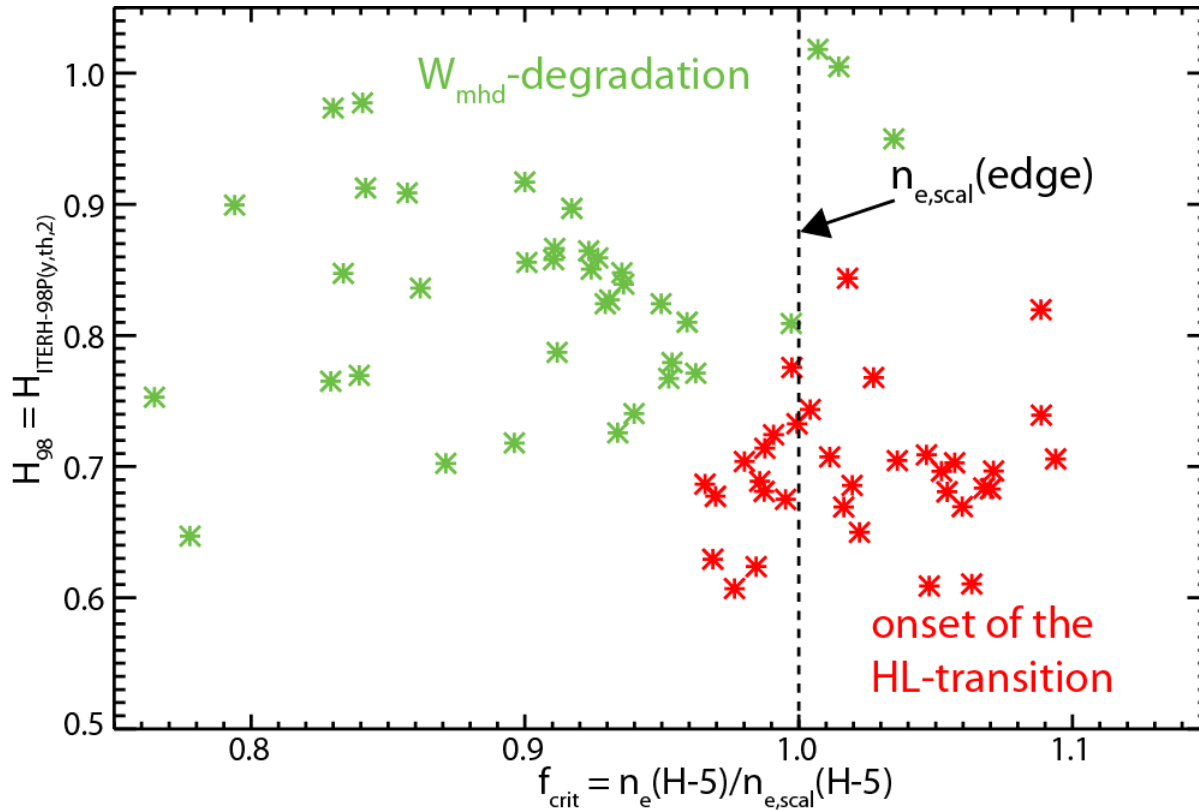
⇒ identifiable point,
 which should never
 be reached during
 safe operation

- generalized coordinates:

$$H_{98} = H_{\text{ITER-98P}}(y, \text{th}, 2) - f_{\text{crit}} = n_e(\text{edge}) / n_{e, \text{scal}}(\text{edge})$$



Deuterium H-mode density limit in $H_{98} - f_{\text{crit}}$ space



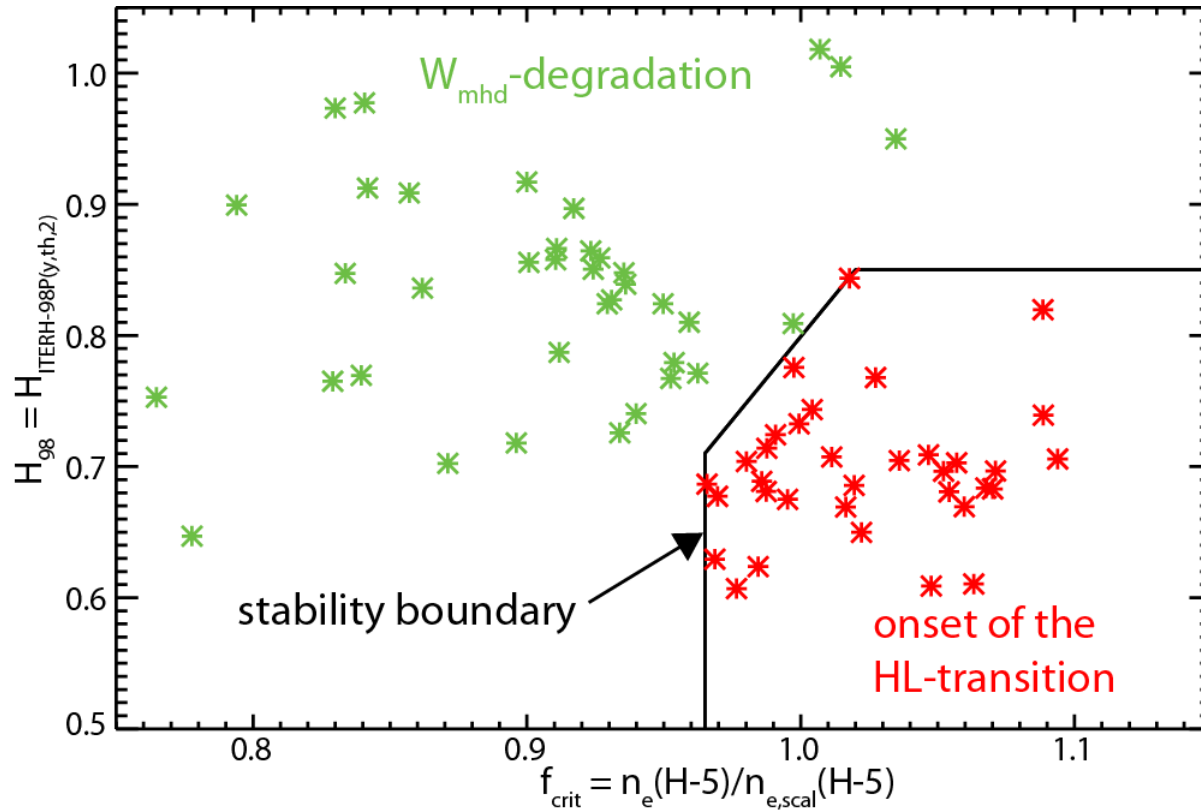
data range:

pure deuterium gas
 $6\text{MW} \leq P_{\text{NBI}} \leq 12.5\text{MW}$
 $0.6\text{MA} \leq I_p \leq 1.2\text{MA}$
 $3.5 \leq q_{95} \leq 7$

- **Begin of confinement degradation** and **start of HL-transition / MARFE entering confined region** dissociate in $H_{98} - f_{\text{crit}}$



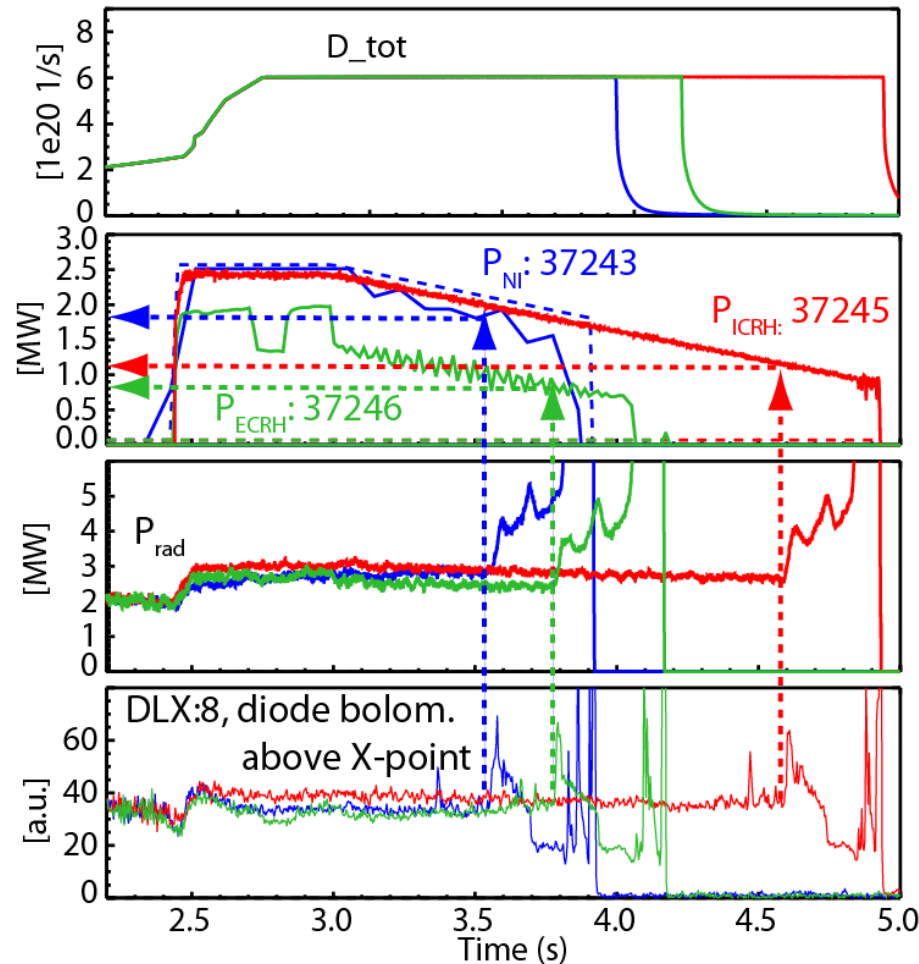
Danger boundary in $H_{98} - f_{crit}$ state space



- empirical **boundary for D** in $H_{ITER-98P(y,th,2)} - n_e/n_{e,scal}$ plasma-state
- possible actuators: gas flux reduction, particle confinement reduction, additional heating, ...



Feedforward actuator comparison: NBI, ICRH, ECRH



- 0.8 MA, -2.5 T, $q_{95}=5.5$, $P_{\text{NBI}} = 5.5$ MW,
- stabilize discharge with additional ff actuator power \rightarrow P-ramp to measure marginal actuator power, P_{marg} , for MARFE formation

- $P_{\text{marg,NBI}} = 2.0$ MW
- $P_{\text{marg,ICRH}} = 1.2$ MW
- $P_{\text{marg,ECRH}} = 0.84$ MW

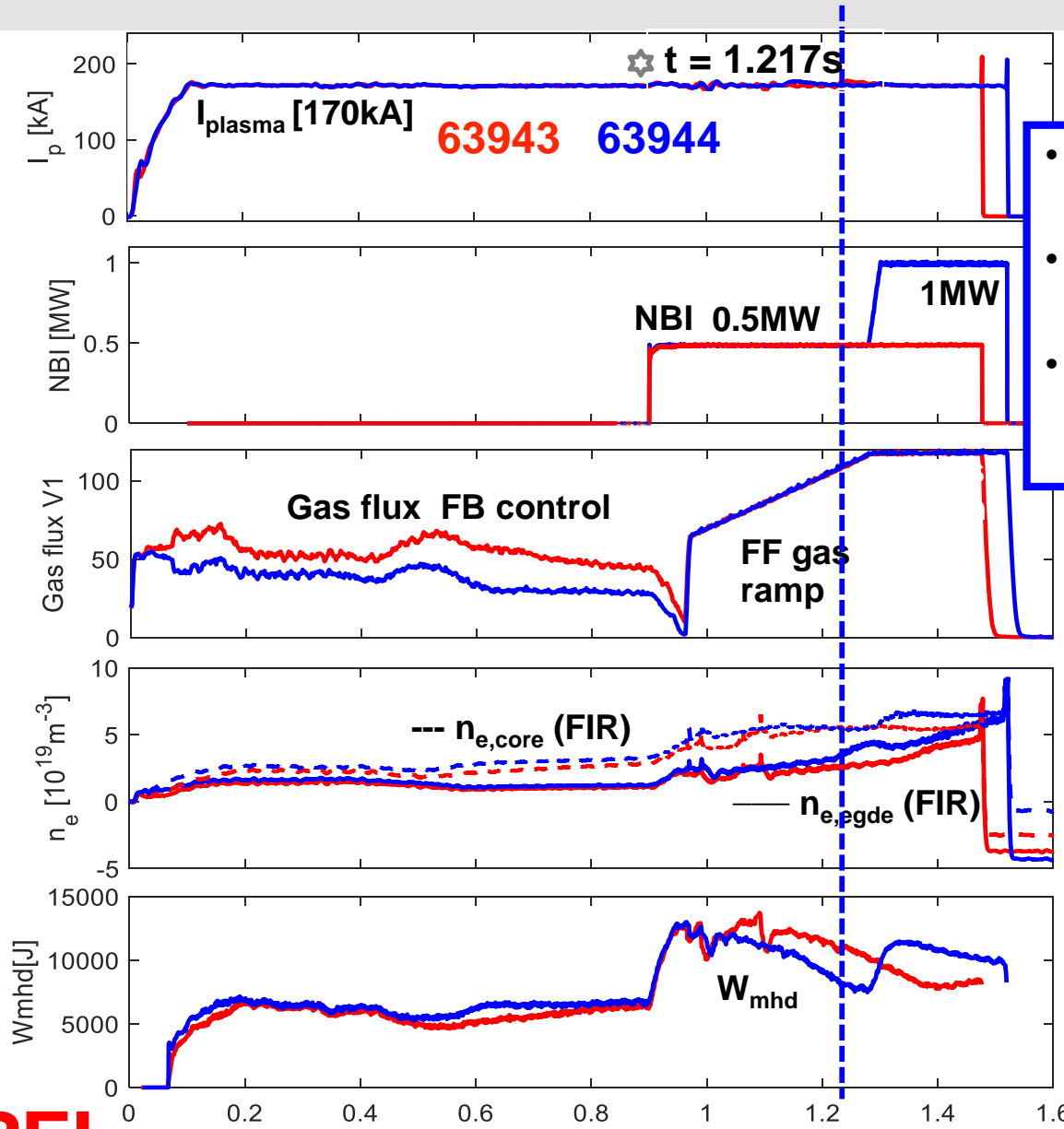
- comparison co-ECCD at $q=2 \leftrightarrow$
 \leftrightarrow central ECRH (not shown)

\Rightarrow **central heating** most effective in terms of required actuator power, P_{act}

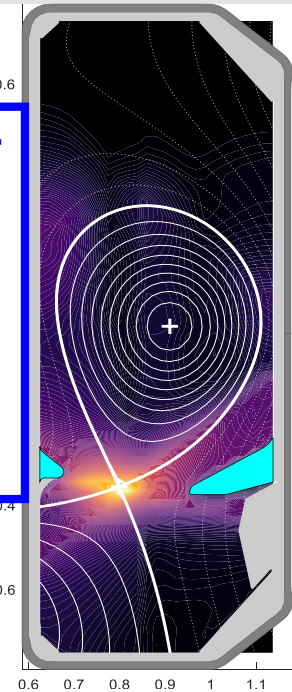
$T_e(0)$ assumed to play central role



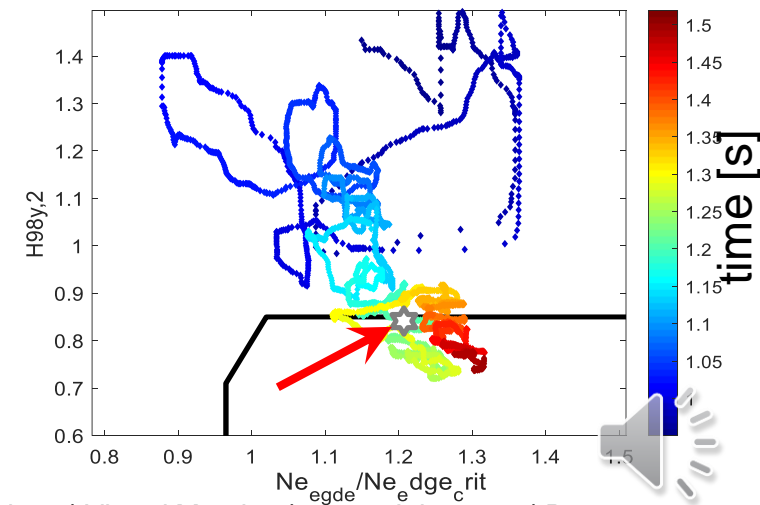
TCV: 0.17MA with initial MARFE at AUG! boundary



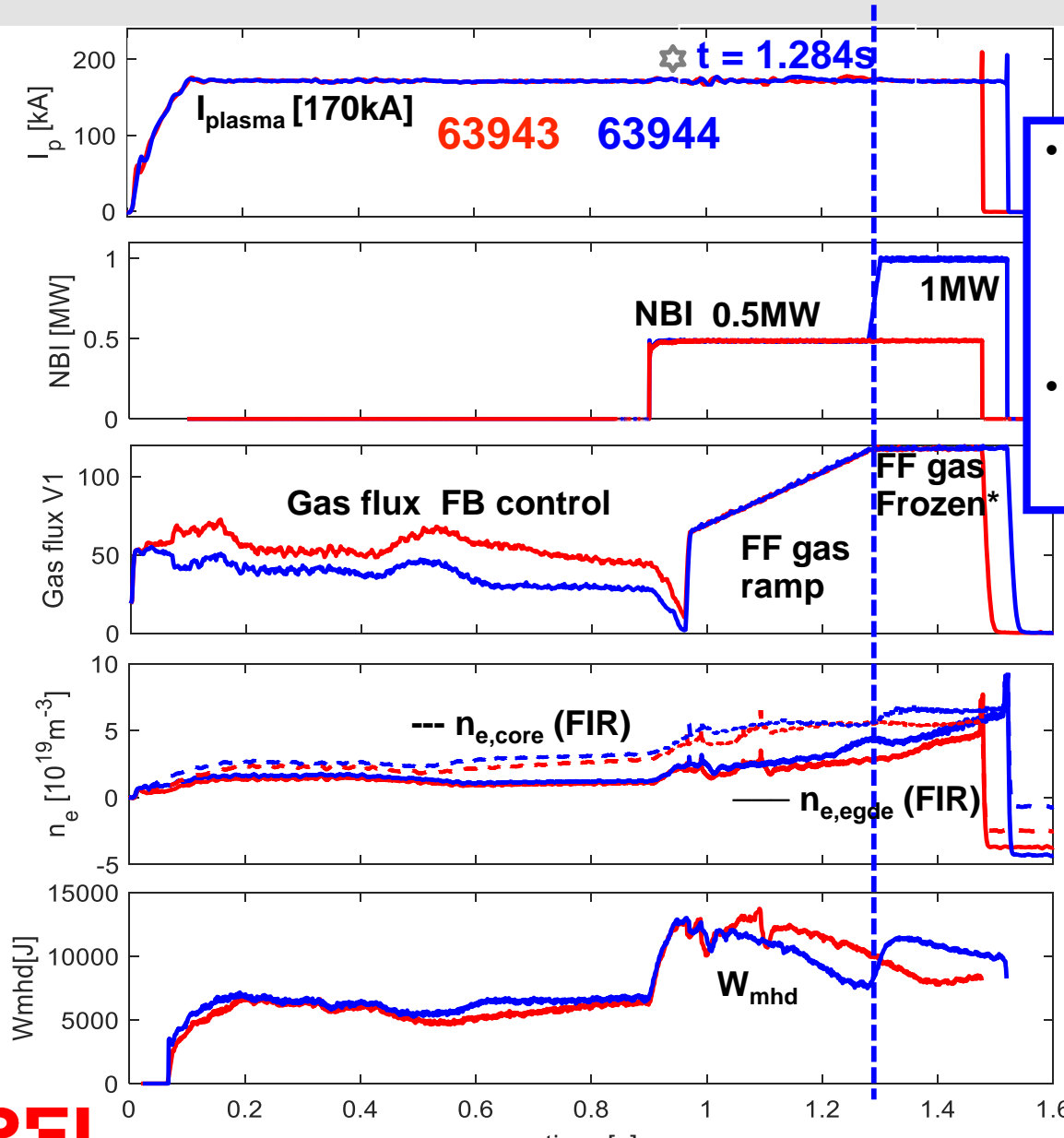
- Radiation moves to **X-point** and increases;
- Sharp increase of the **HFS n_e** ;
- Operating point in the state space reaches the **boundary**.



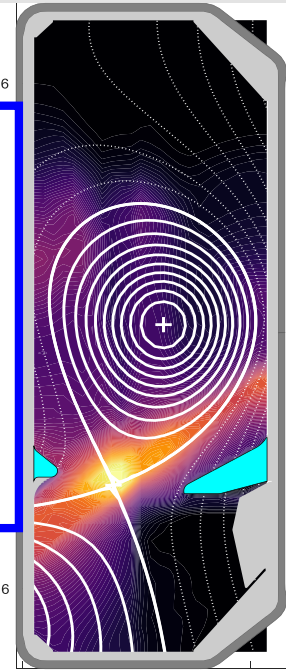
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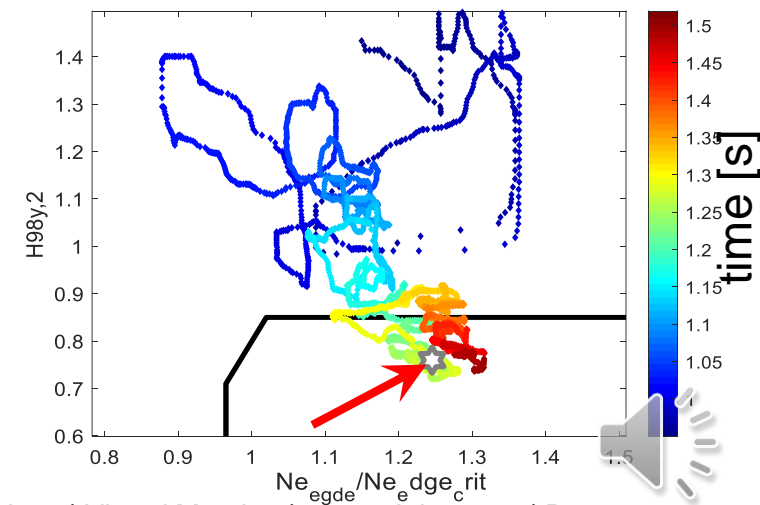
TCV: developed MARFE in danger zone



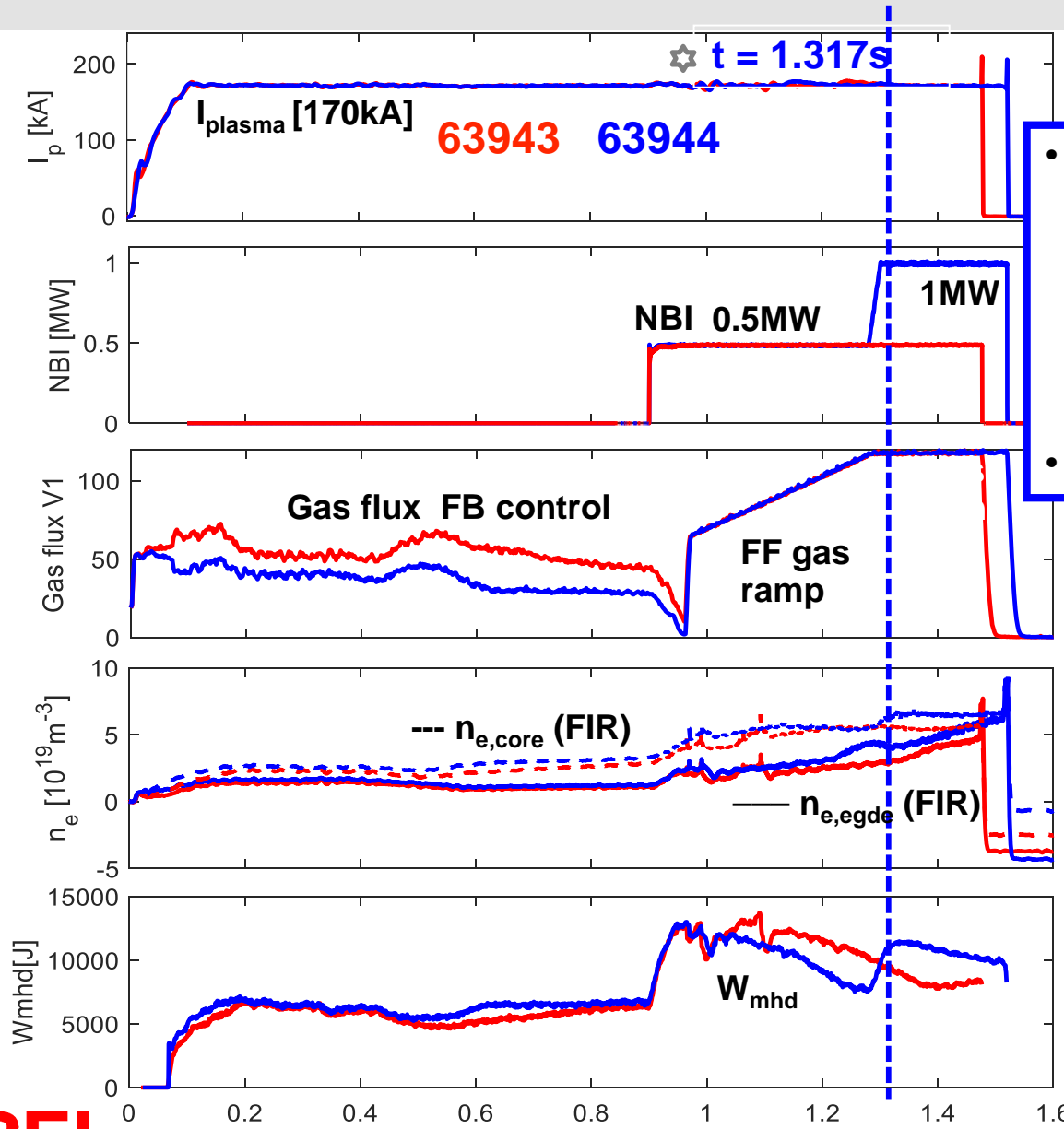
- H_{98} keeps degrading until additional NBI power is applied, whereas f_{crit} is increasing;
- **Radiation** begins to leave the X-point moving upwards.



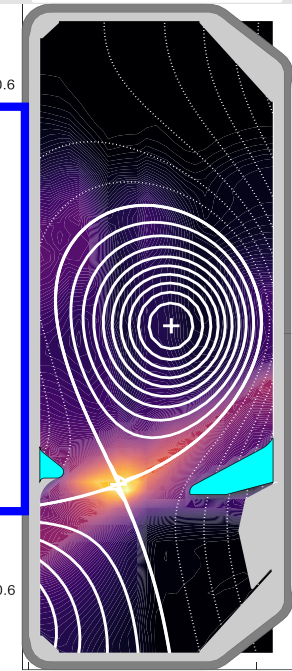
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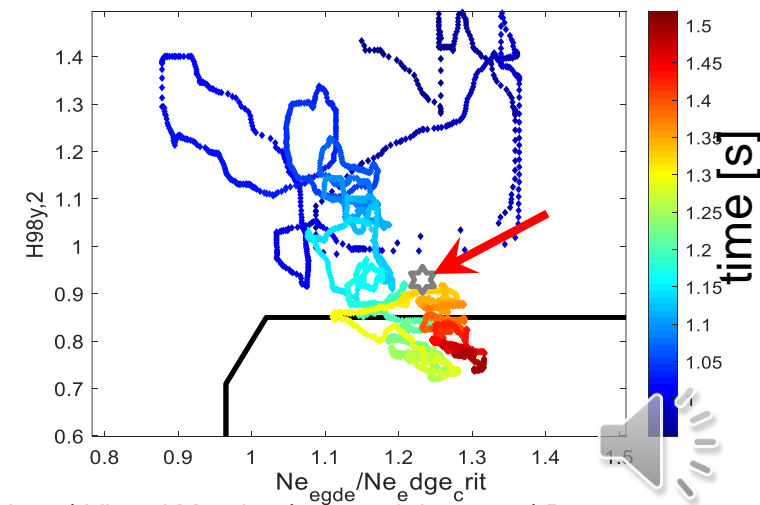
TCV: NBI suppressed MARFE, back in safe zone



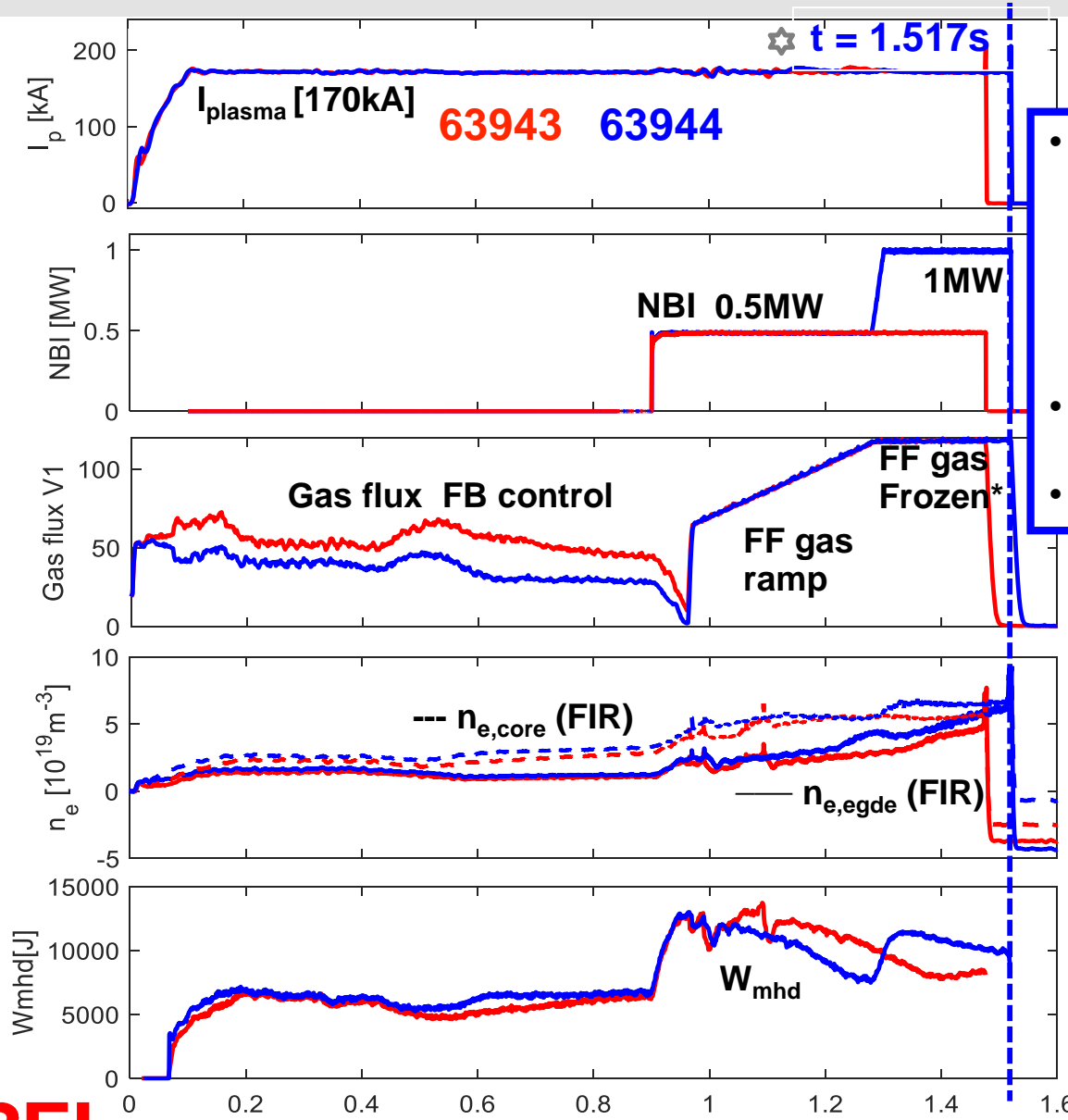
- Stepping up NBI power the MARFE is temporarily suppressed (radiation pushed back towards the X-point and H_{98} improves)
- NBI heating works



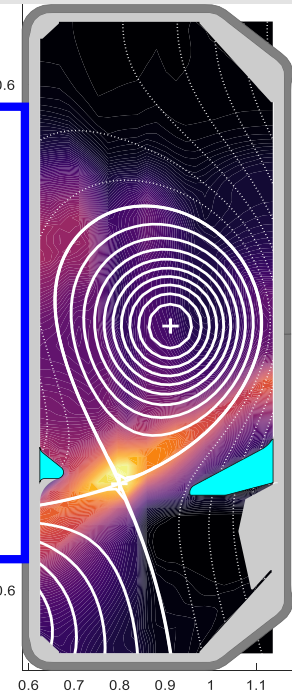
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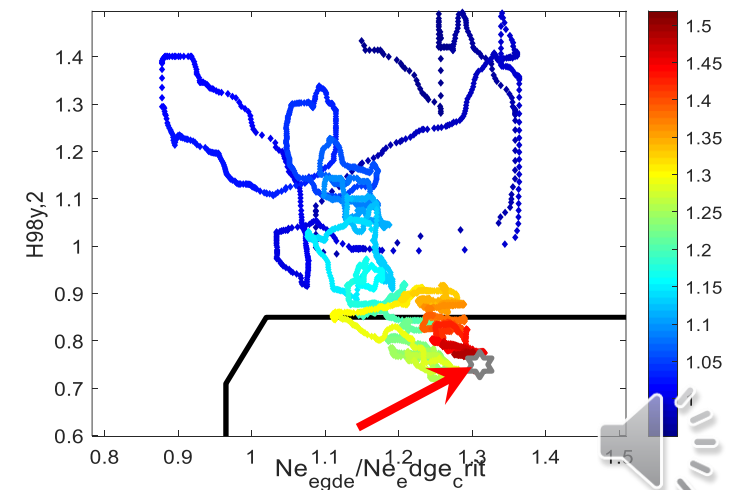
TCV: re-developed MARFE in danger zone, higher n_e



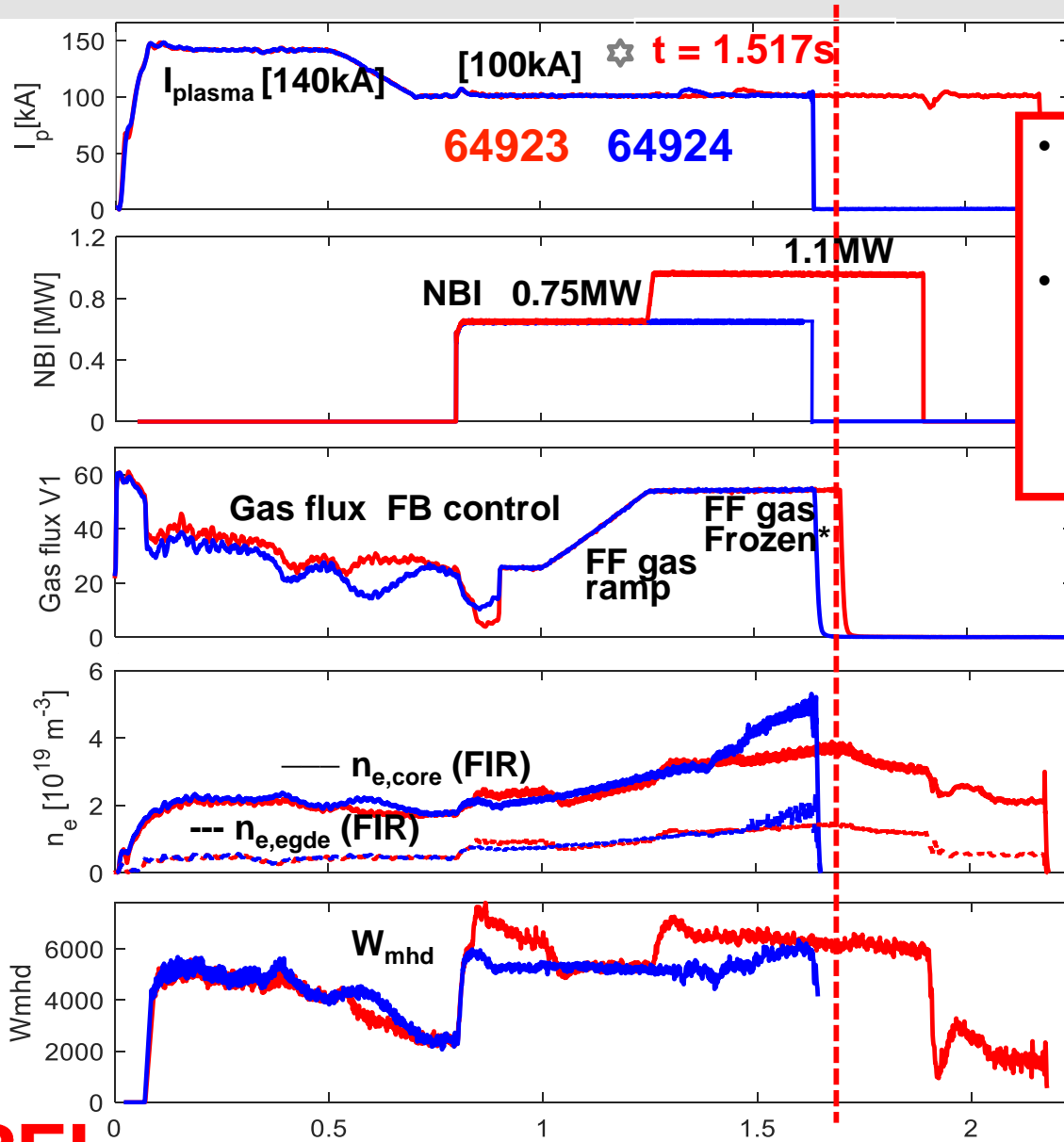
- At constant gas flux f_{crit} starts again to slowly increase with H_{98} degrading.. until plasma disrupts!
- **state space transferable !**
- **vertical: P_{act}**



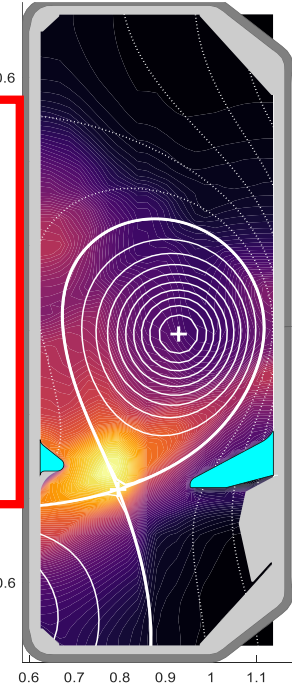
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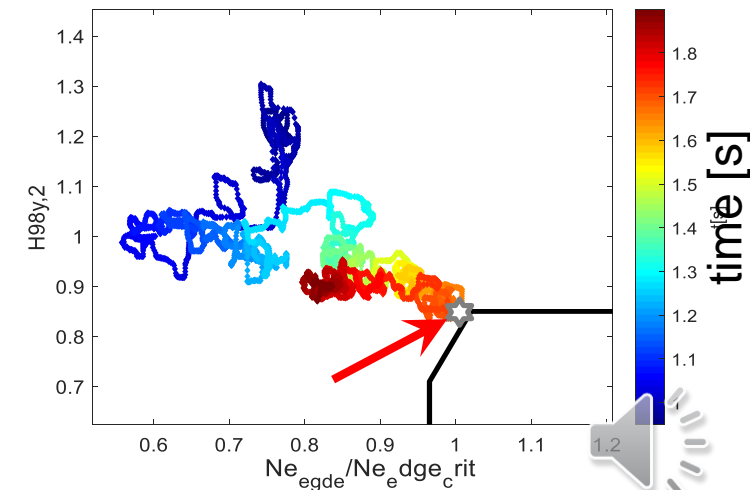
TCV: 0.1MA with developed MARFE at boundary



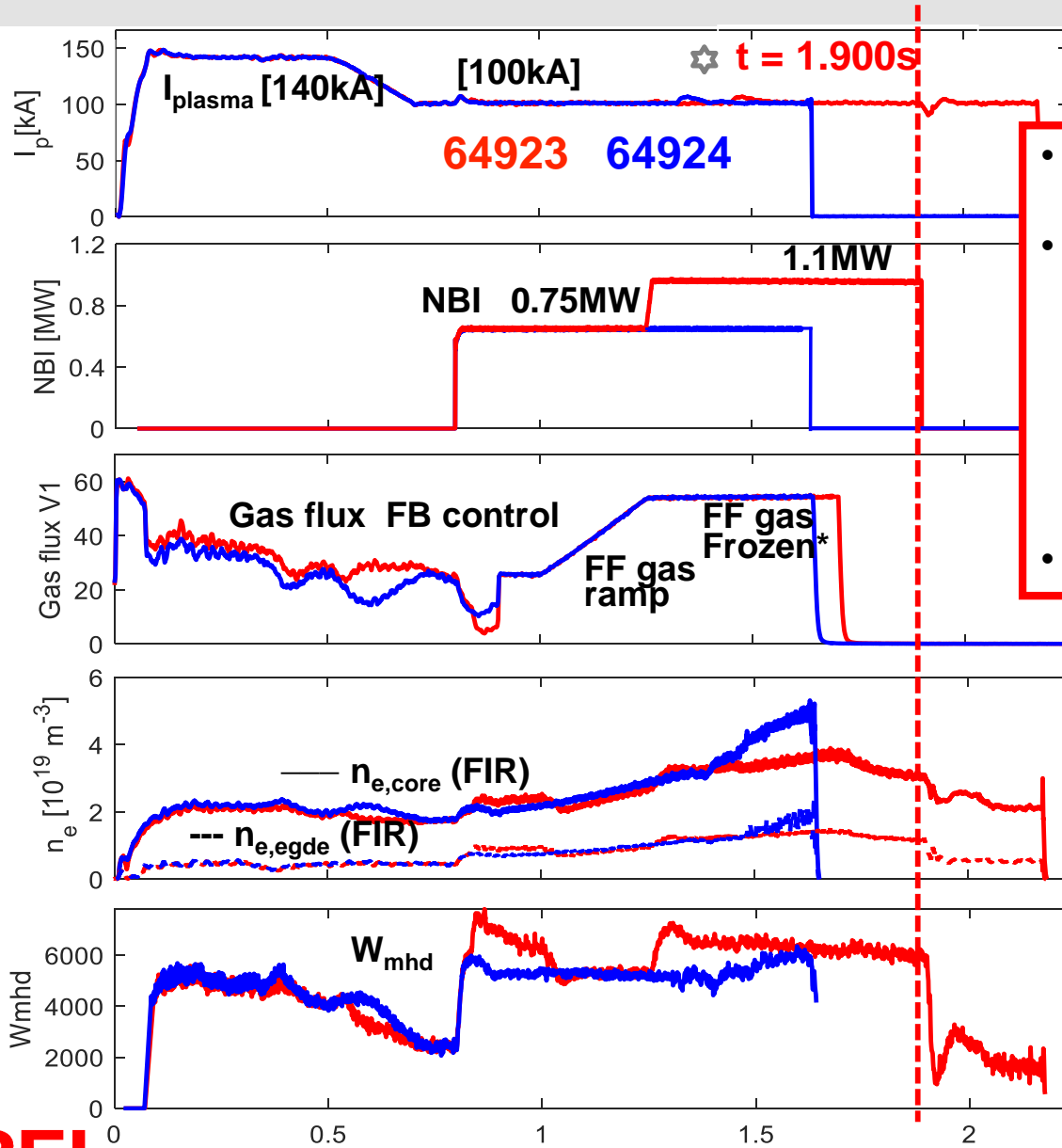
- At constant gas flux f_{crit} increases with H_{98} slowly degrading;
- **MARFE** starts developing with radiation leaving the X-point (operating close to the boundary!)



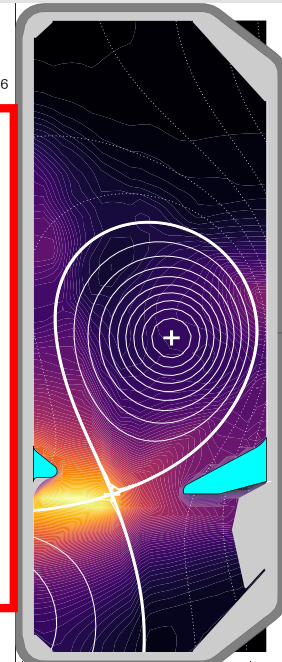
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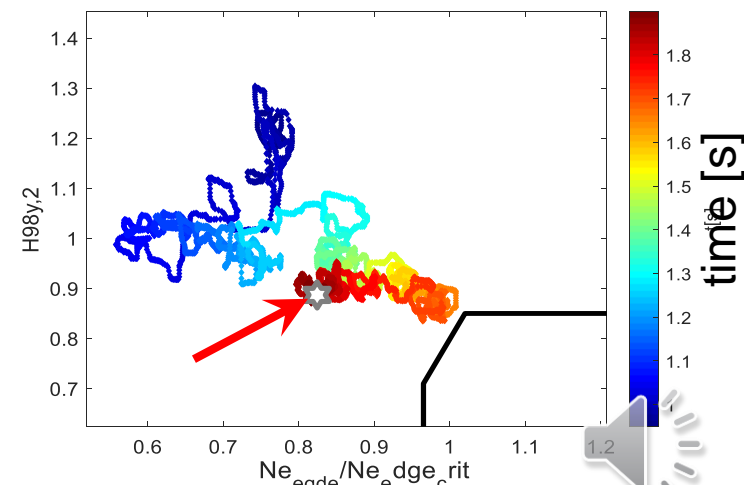
TCV: 0.1MA with remove MARFE by gas reduction



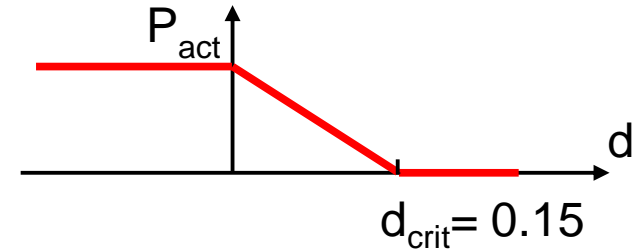
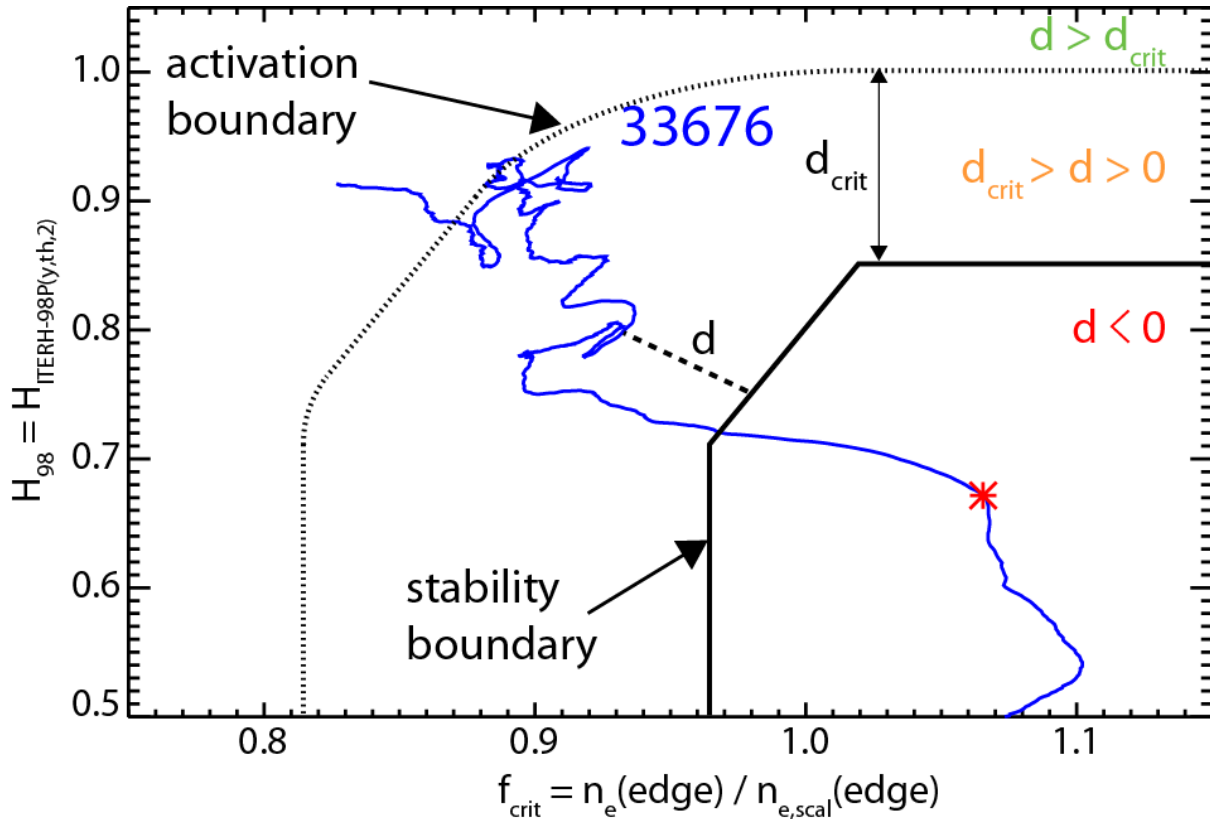
- Cutting the gas the disruption is avoided!
- f_{crit} is reduced with H_{98} slowly improving until we switch the **NBI off** (the discharge disrupts later because of the **OH limit**).
- horizontal: gas flux



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Controller scheme at ASDEX Upgrade



normalized 2D distance d :

$d > d_{crit}$, safe region

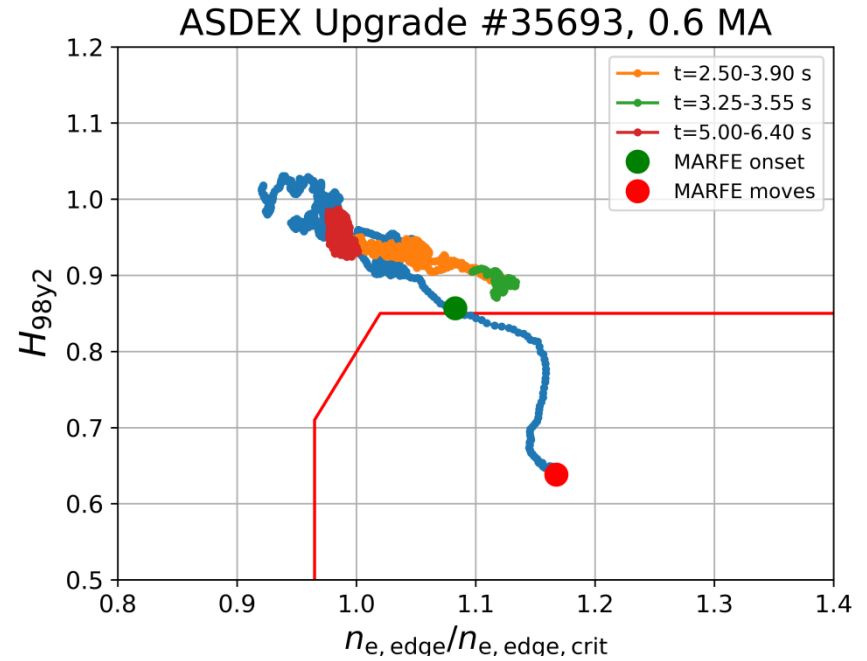
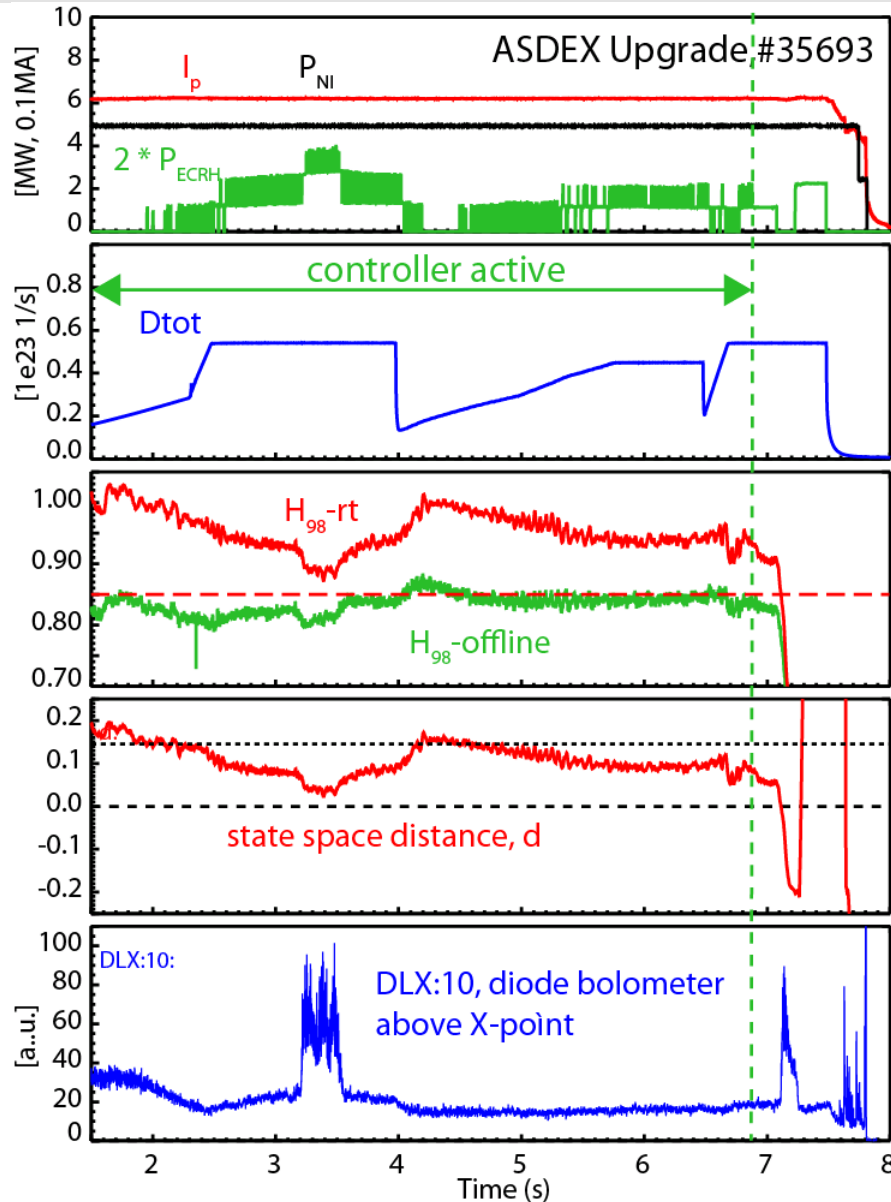
$d_{crit} > d > 0$, activation

$d \leq 0$, danger zone

- soft controller activation before reaching danger zone :
actuator reaction = $f(d)$
 - different weight of H_{98} and f_{crit} could be considered

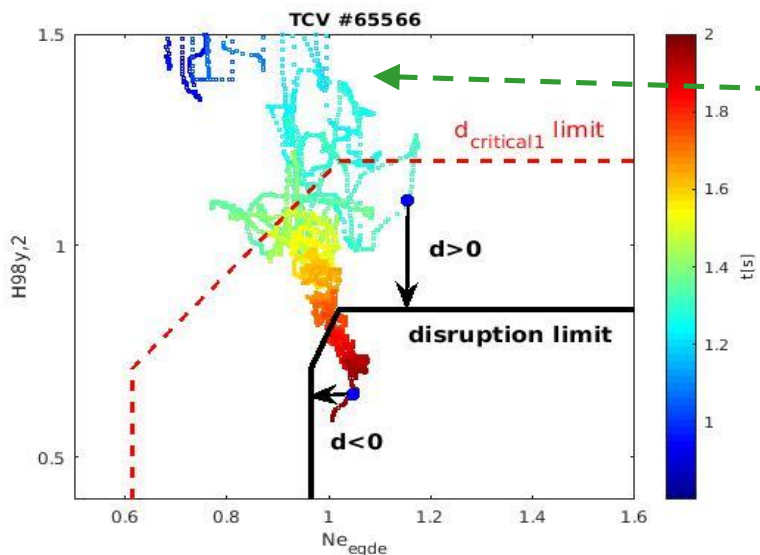


Feedback controlled ECRH at $\rho=0$ with rt-signals

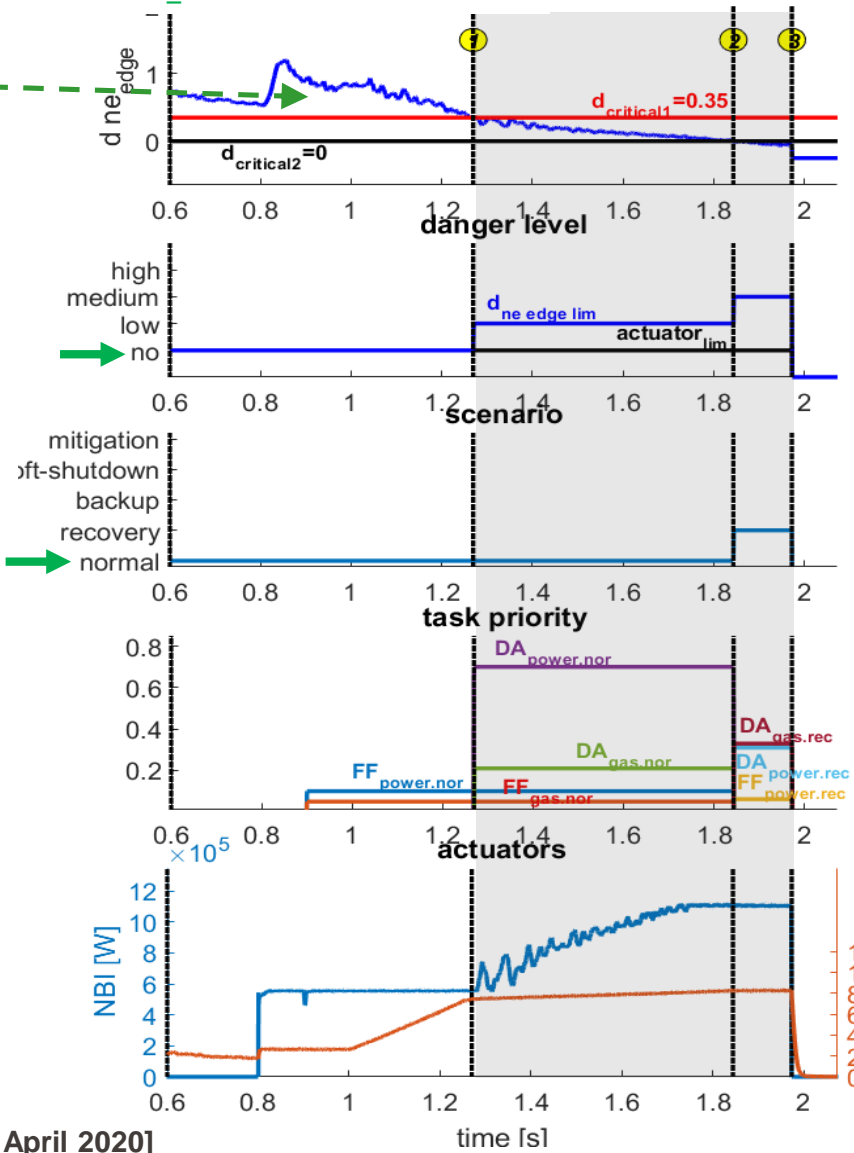


- ECRH starts already approaching the disruptive zone and keeps discharge safely away from it
- MARFE and disruption after ECRH is off
- distance d as sensor, note: with corrected rt- H_{98} , the actuator would start even earlier

Controller with 2 actuators, NBI and gas flux, and hierarchical reaction at TCV



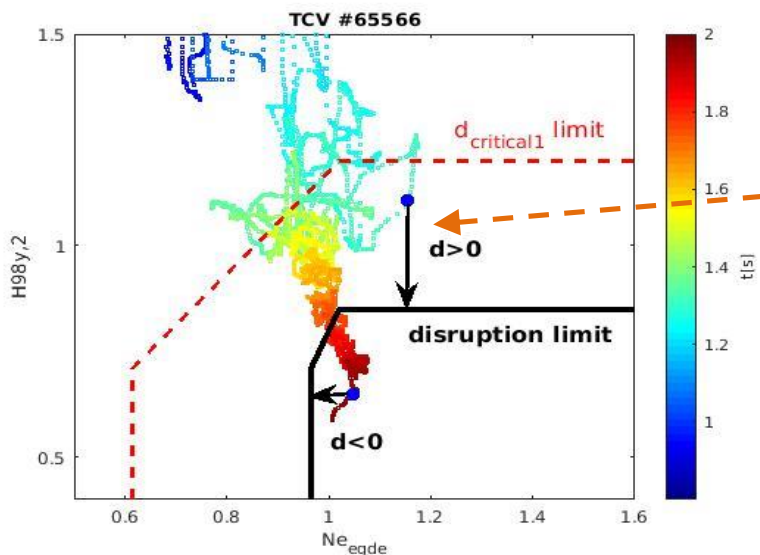
$$d_{ne_lim} > d_{critical1}$$



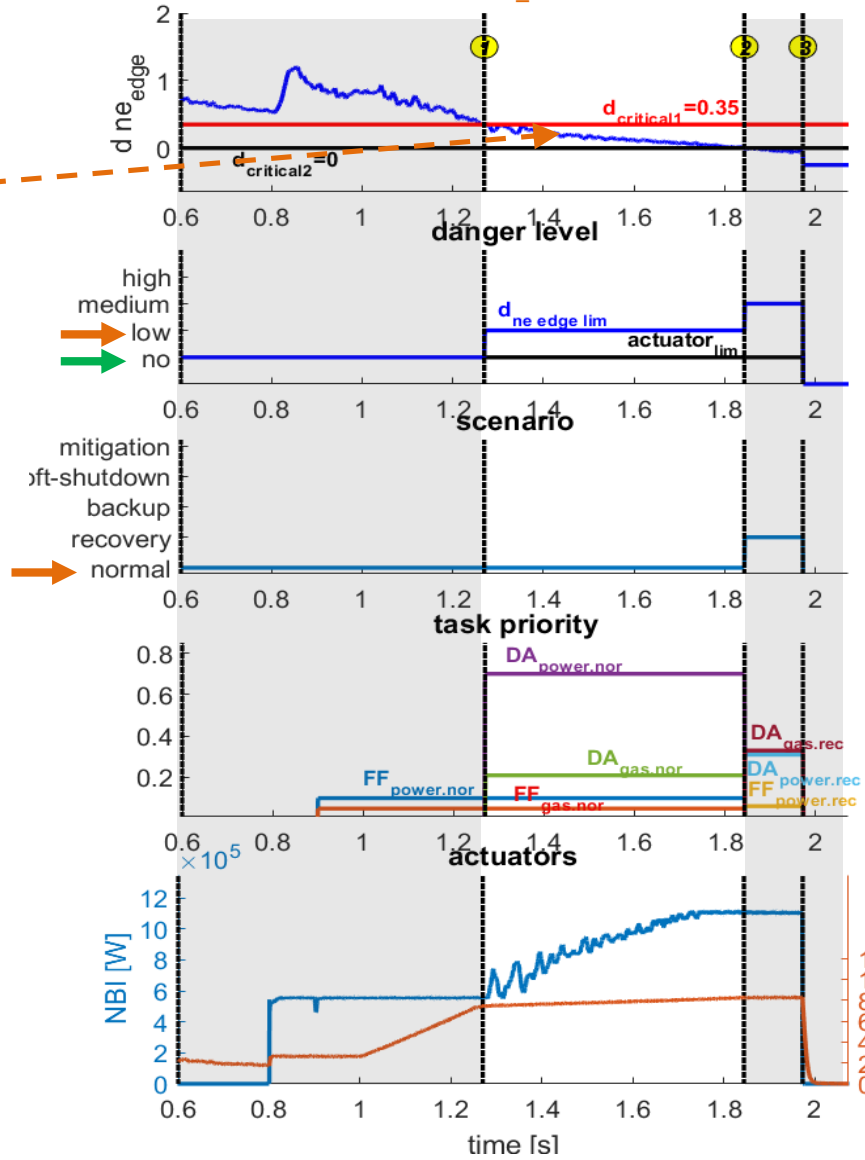
- *no danger* for $E_{d_ne_lim}$ and E_{act_lim}
- *normal scenario*:
 - NBI and gas valve are controlled by the feedforward tasks



Controller with 2 actuators, NBI and gas flux, and hierarchical reaction at TCV



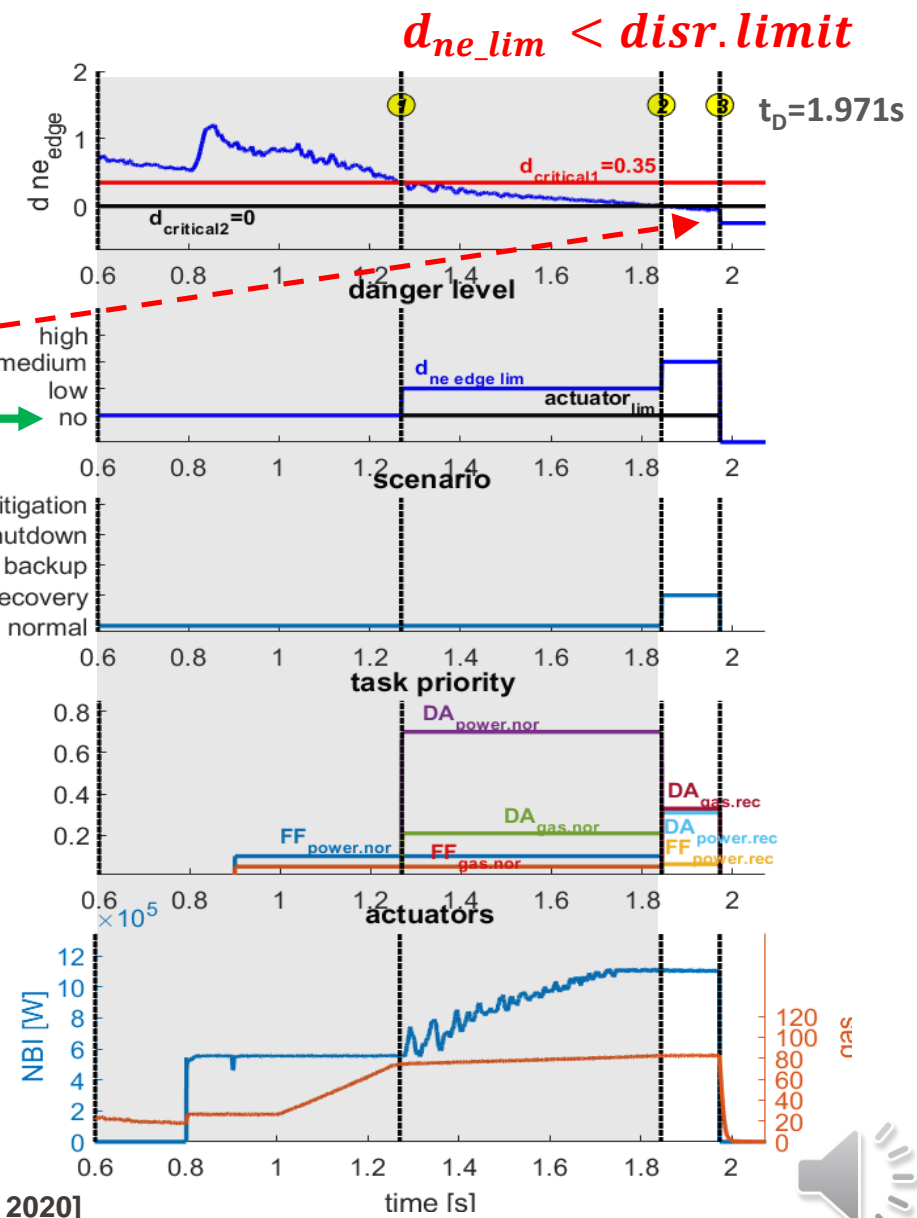
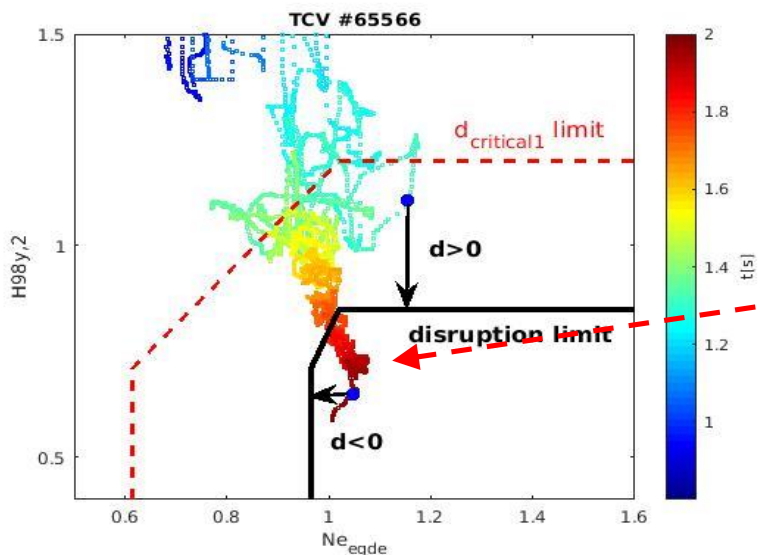
$$d_{critical1} < d_{ne_lim} < disr.\ limit$$



- **low danger** for $E_{d_ne_lim}$ and still **no danger** for $E_{act.lim}$
- **normal scenario:**
 - NBI and gas valve are controlled by the feedforward tasks
 - + $DA_{power.nor}$ asks for linearly increasing power
 - + $DA_{gas.nor}$ reduces the gas flux



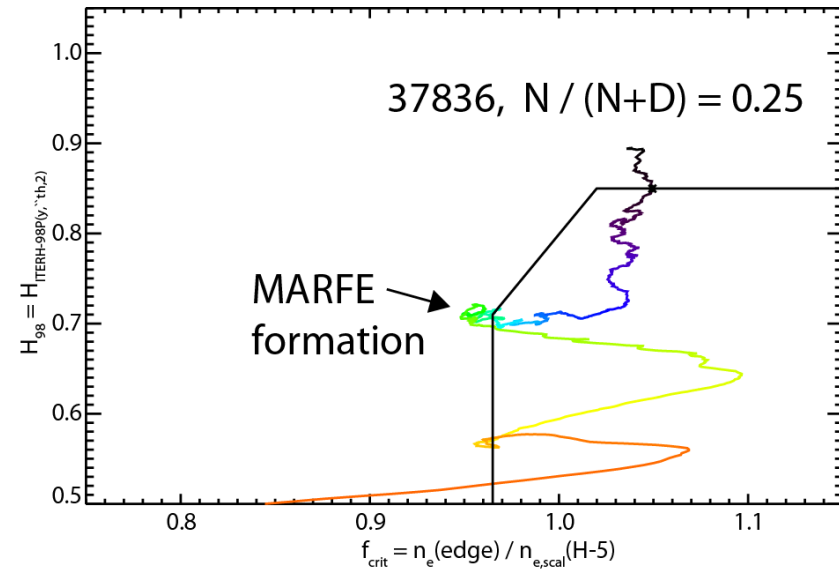
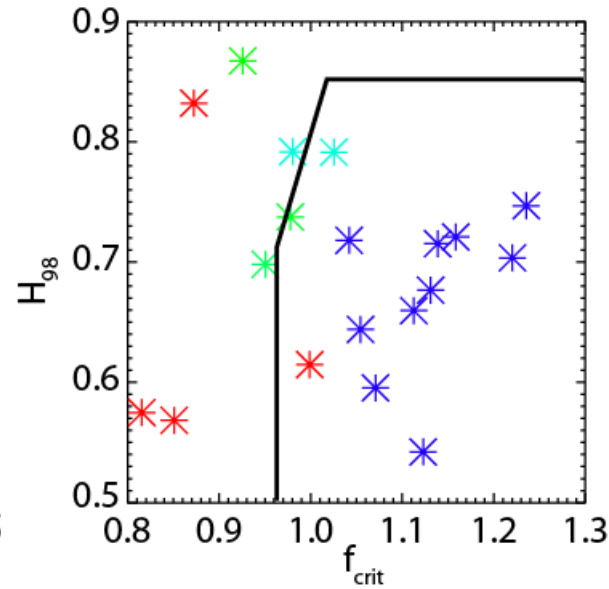
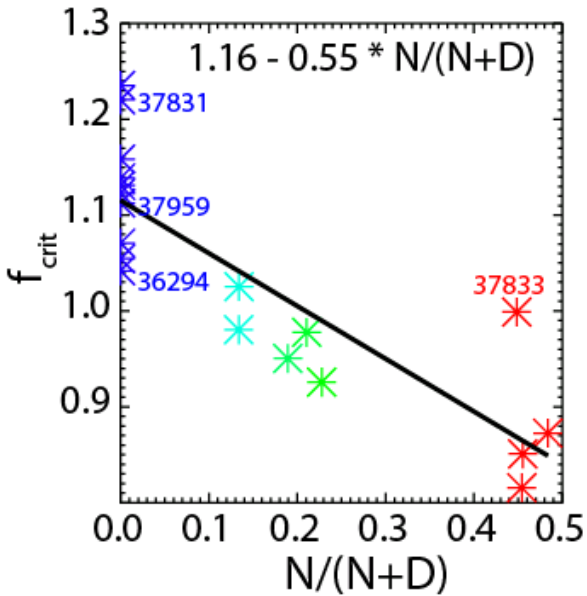
Controller with 2 actuators, NBI and gas flux, and hierarchical reaction at TCV



- **medium danger** for $E_{d_{ne_lim}}$ and still **no danger** for E_{act_lim}
- **recovery scenario:**
 - NBI is controlled by the feedforward
 - + $DA_{power.rec}$ asks for maximum power
 - + $DA_{gas.rec}$ freezes the gas flux



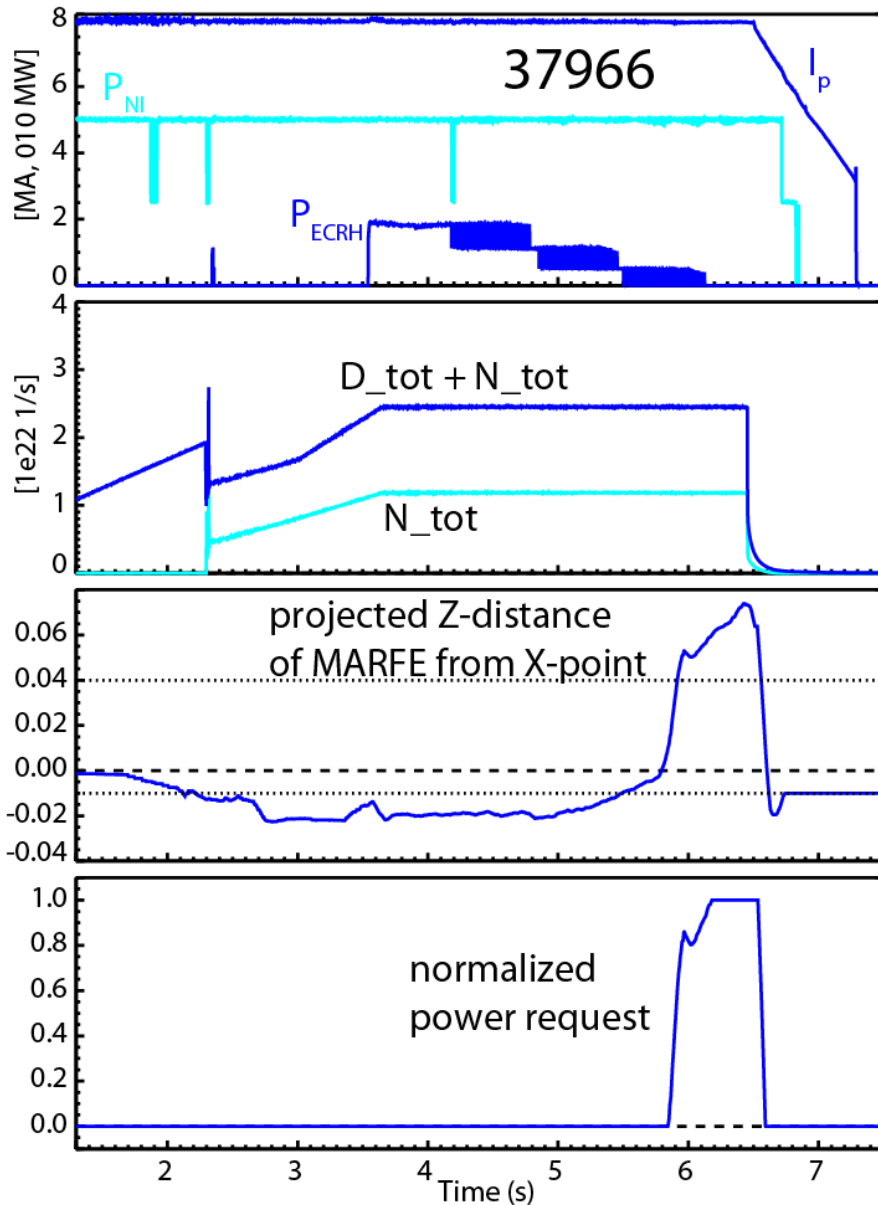
MARFE formation with additional impurities (N₂)



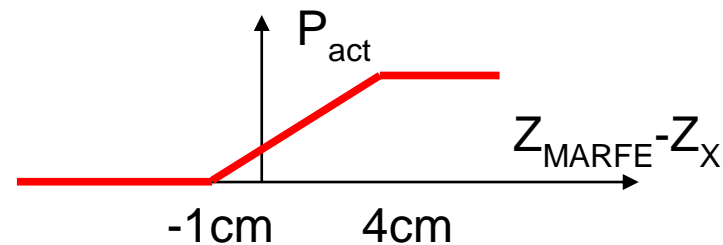
- f_{crit} and n_e typically lower with increasing nitrogen content, \Rightarrow modified scaling for f_{crit} including impurities could help
- H_{98} possibly higher, but large scatter
- trajectory behaves differently \Rightarrow boundary modification insufficient!
 \Rightarrow not applicable with impurities
- complementary sensor, such as a MARFE detector desirable



MARFE observer and alternative controller



- realtime observer of Z-position of X-point radiator above X-point as complementary direct detector for MARFE and as control quantity
- transfer function for actuator :



- state space based controller for the H-mode density limit established for deuterium at ASDEX Upgrade and ported to TCV

ASDEX Upgrade:

- different efficiencies of heating actuators (co-ECCD, central ECRH, central ICRH, NBI): further analysis and understanding needed
- include seeded impurities, such as N_2 (for divertor protection): at least f_{crit} adaption needed, but different behaviour in state space with N_2 needs further work

TCV:

- combined actuators controller extended by including gas control
- application to achieve stable high density ELMy H-mode (not shown)



Outlook and next steps



- data base analysis at JET could provide:
 - behaviour with impurities (different impurity for divertor protection)
 - behaviour at higher $T_e(\text{edge})$ (test for ITER and DEMO)
 - portability to larger devices
- modified state space (f_{crit}) and MARFE behaviour with impurities
- physics based derivation of scaling and boundary desirable
- manage competing requests from prevention schemes for other disruption paths, such as NTM's (presentation by A.Pau)

