

*12th IAEA Technical Meeting
on Control, Data Acquisition
and Remote Participation for
Fusion Research*

Automatic recognition of anomalous patterns in discharges by recurrent neural networks

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May 13-17 2019 / Daejeon, KOREA

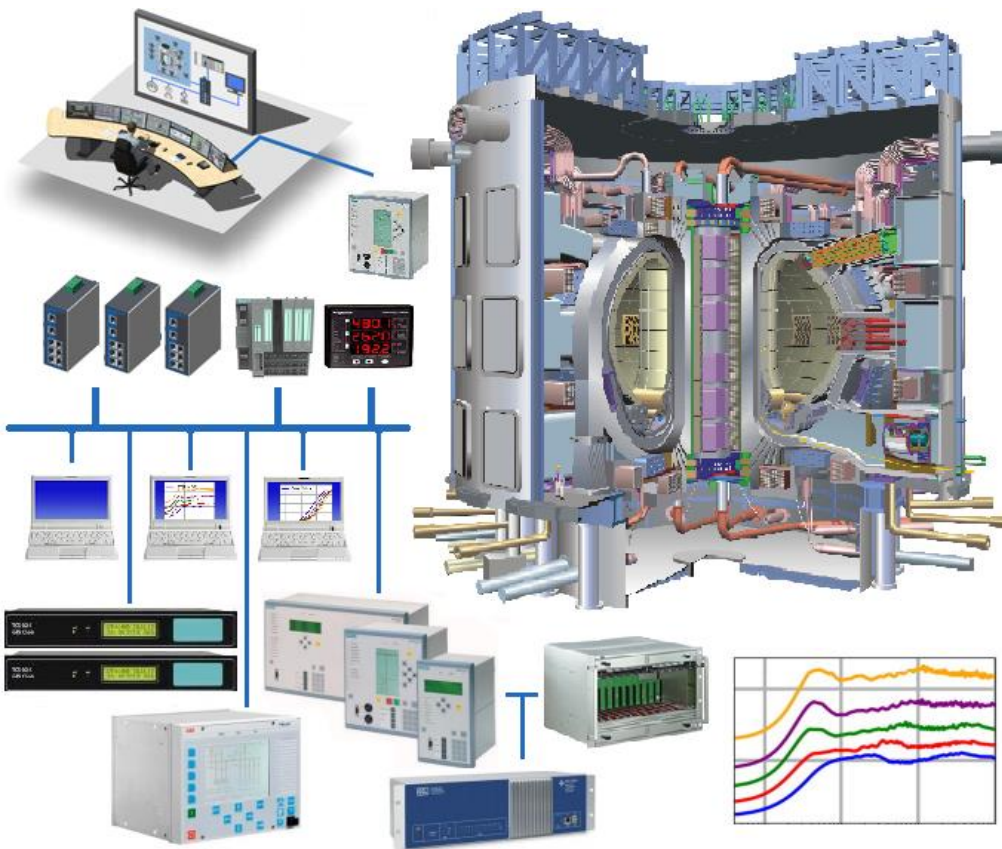


Outline

- Introduction
- Background
 - Anomaly Detection
- Proposed Solution
 - Recurrent Neural Networks (LSTM)
- Results
- Summary

Introduction

- The experiments generate huge quantities of data. It is estimated that only 10% of this data is analyzed.



A shot of few seconds can generate huge quantity of data:

- **TJ-II** device has +1000 channels of measurements.
- A shot in **JET** can take around 10 seconds (**10 GB/shot**. around 100 TB/year).
- **ITER** could generate **1 TB/shot**. around 1 PB/year.

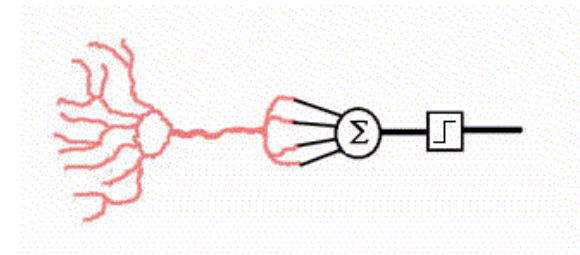
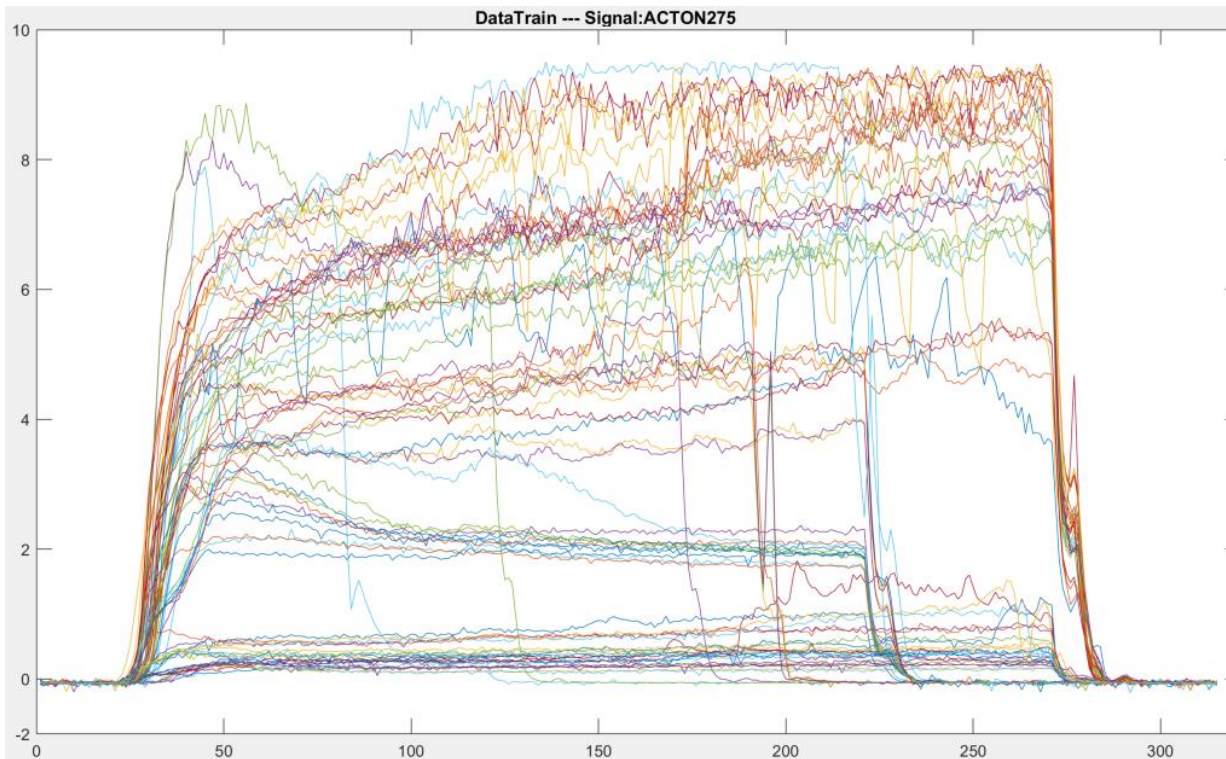


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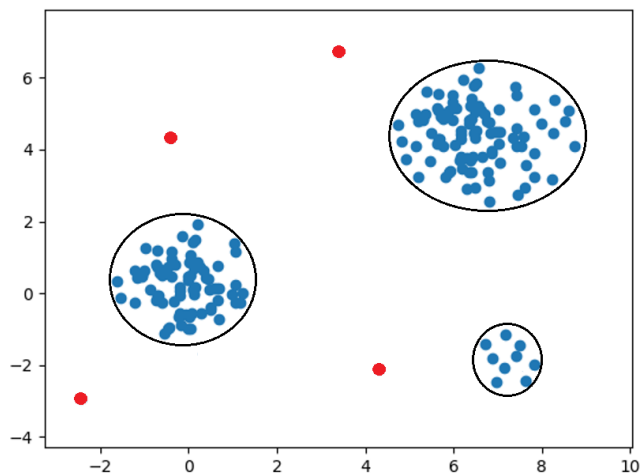
Background

- ❑ The idea is to use Artificial Intelligence to deal with fusion data.
- ❑ Create systems that allow specialists to analyze and interpret data more quickly and efficiently than manually.

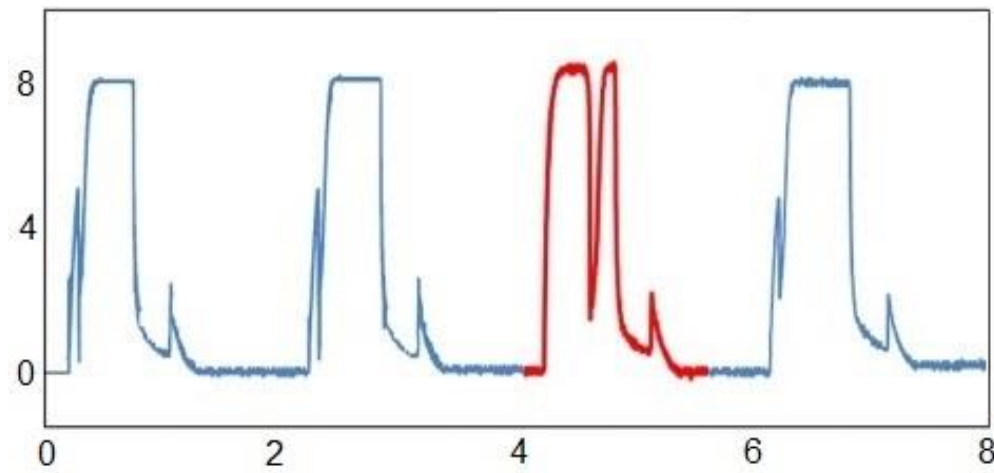


Background – Anomalies

- ❑ **Anomaly:** Something that deviates from what is standard, normal, or expected.
- ❑ One type of anomaly is known as '**outlier**', which is a value located outside of the normal class.
- ❑ Other type of anomaly is an anomalous behavior, which is a **periodic collapsing phenomenon in time series**.



Clustering



Pattern recognition

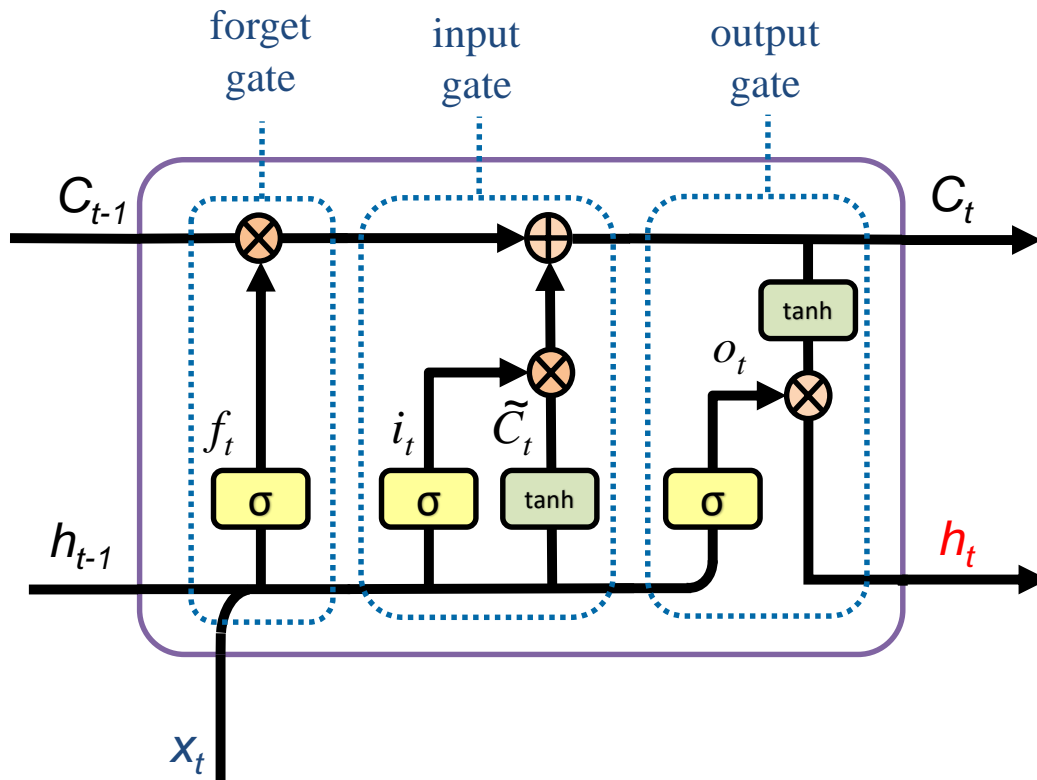
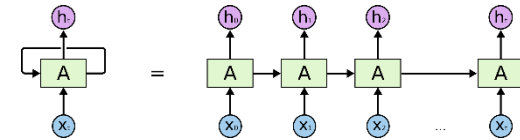


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Proposed Solution – LSTM

□ Recurrent Neural Network – Long Short Term Memory (LSTM)



*They have memory

Forget gate layer

$$f_t = \sigma (W_f [h_{t-1}, x_t] + b_f)$$

Input gate layer

$$i_t = \sigma (W_i [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh (W_c [h_{t-1}, x_t] + b_c)$$

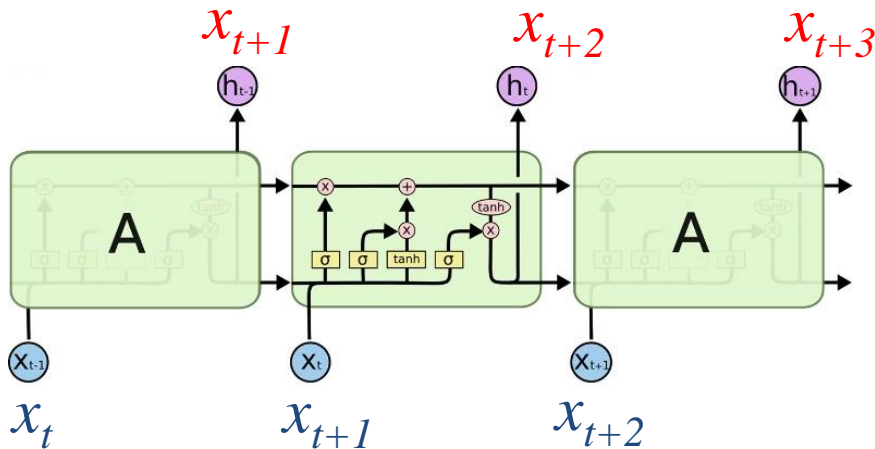
$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

Output gate layer

$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh (C_t)$$

LSTM – Forecasting (training stage)



Forget gate layer

$$f_t = \sigma(W_f[h_{t-1}, x_t] + b_f)$$

Input gate layer

$$i_t = \sigma(W_i[h_{t-1}, x_t] + b_i)$$

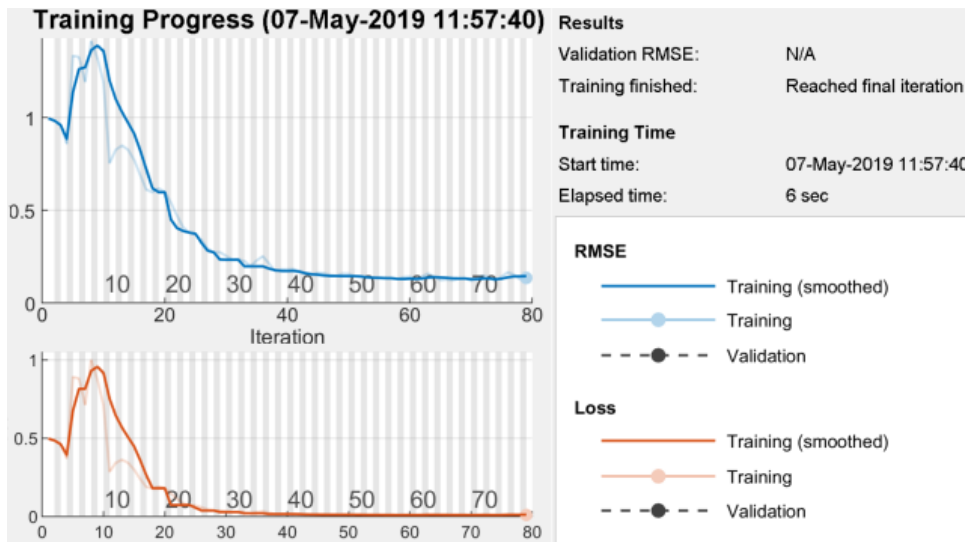
$$\tilde{C}_t = \tanh(W_c[h_{t-1}, x_t] + b_c)$$

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

Output gate layer

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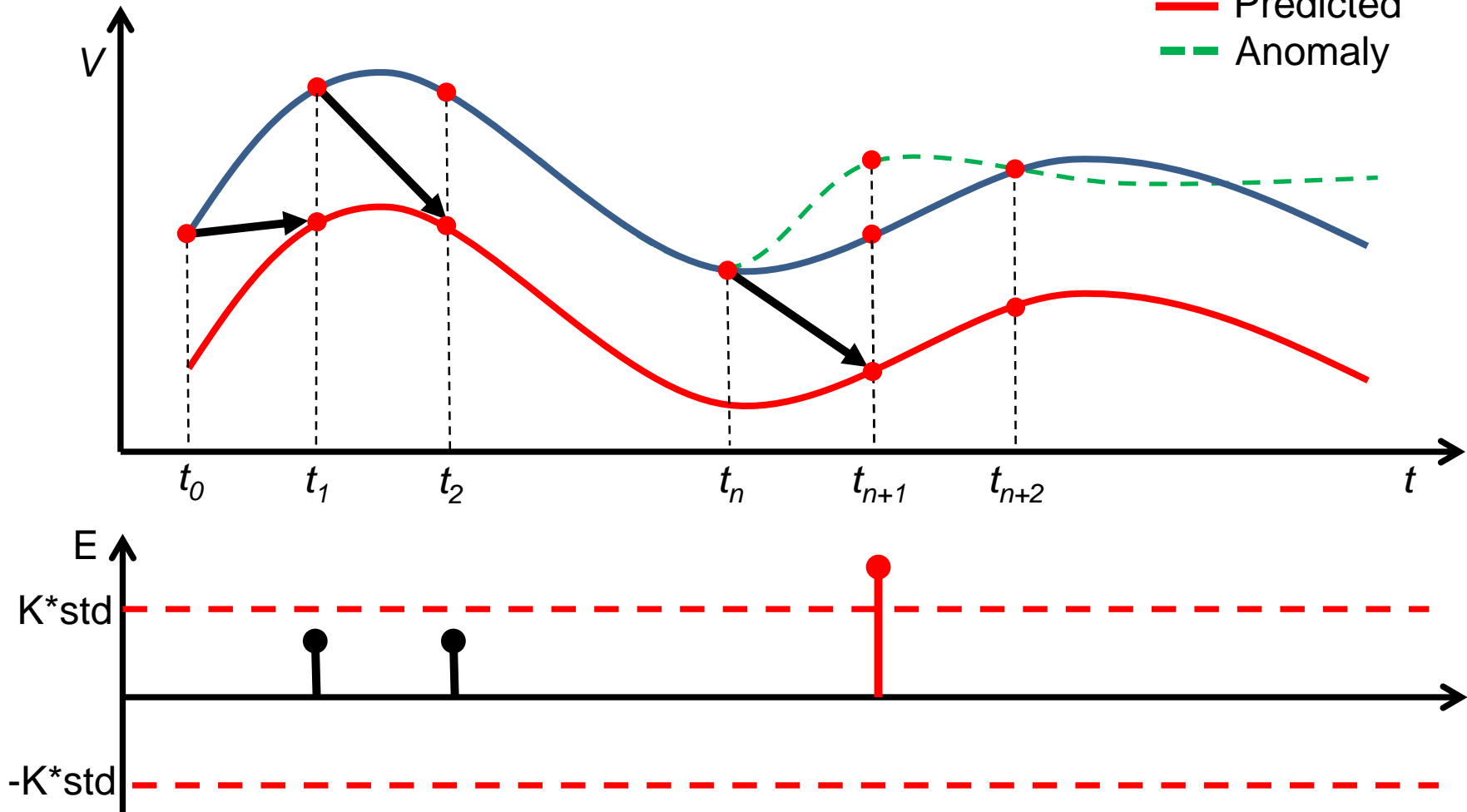


*It adjusts the bias and weights to learn the shape of the waveform

LSTM – Forecasting (test stage)

□ LSTM for forecasting (trained newtork)

— Observed
— Predicted
- - Anomaly



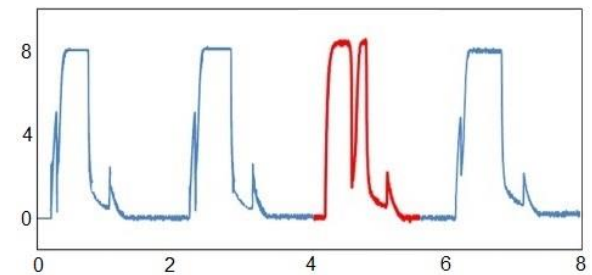
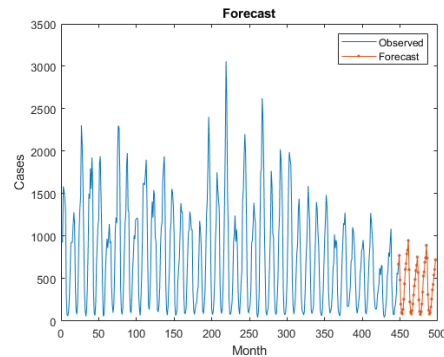
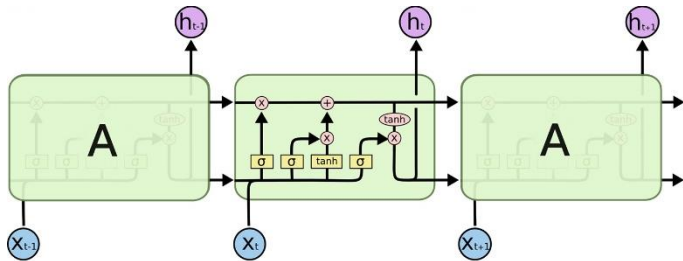
Goals

□ General Goal

- Anomaly detection using Recurrent Neural Network (LSTM - Long Short Term Memory).

□ Specific Goal

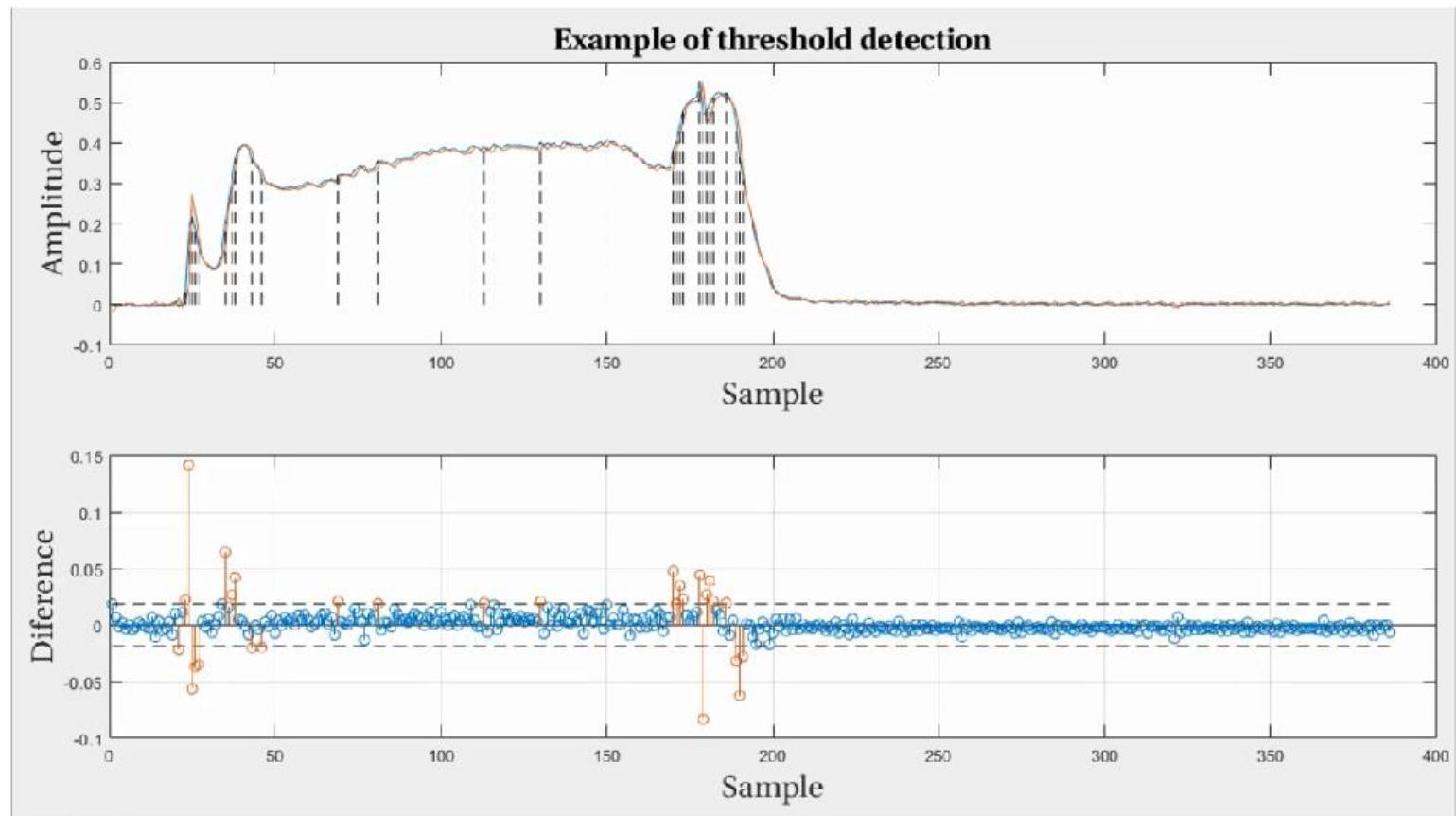
- The LSTM Neural Network learns the waveform to detect anomalies through forecasting.



Anomaly Detection – Threshold ($th=k*std$)

□ How the Anomaly is detected?

- We fix a **threshold** proportional to the **Standard Deviation** of the **Error**.





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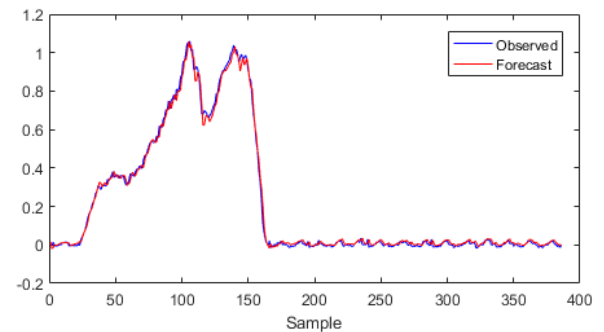
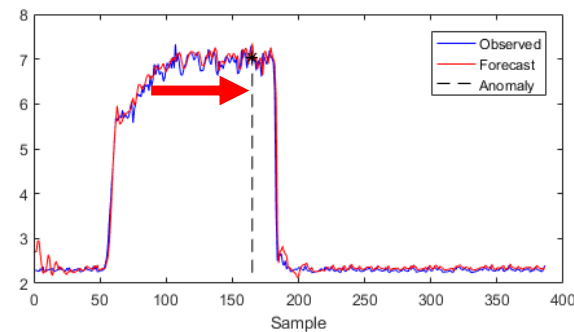
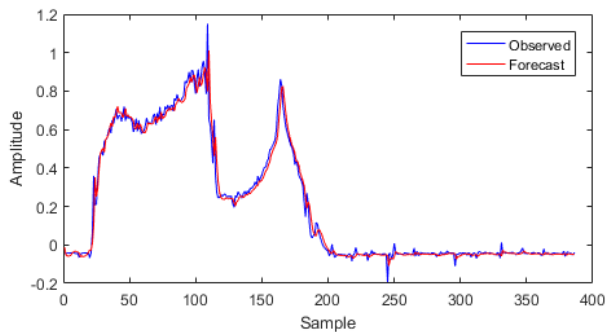
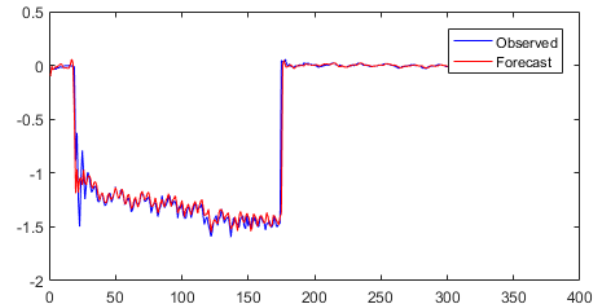
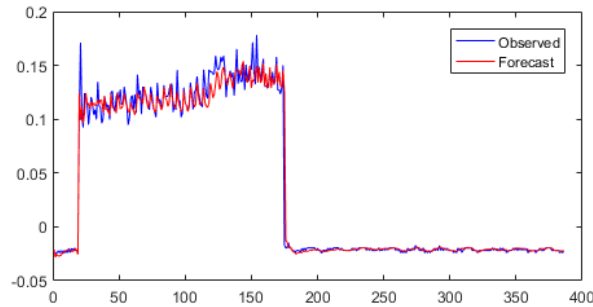
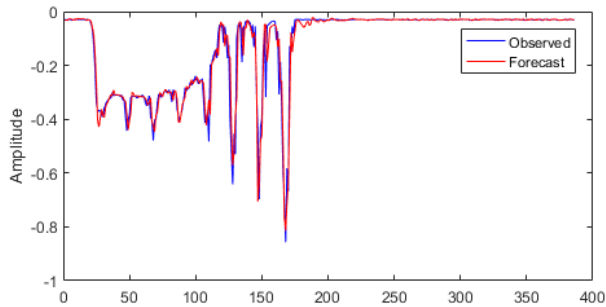
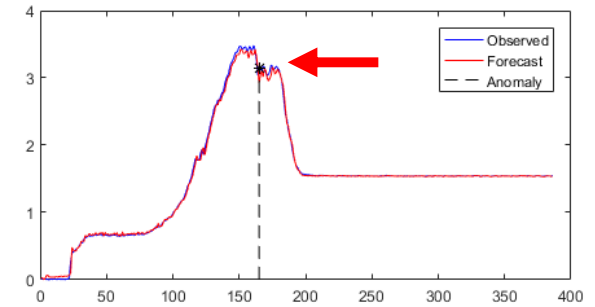
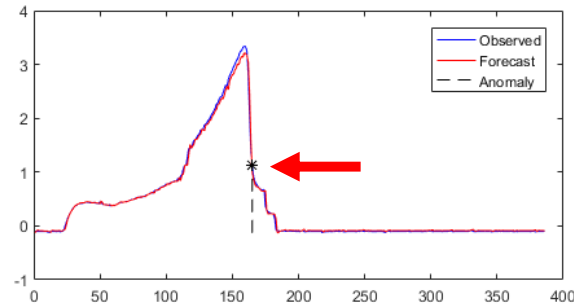
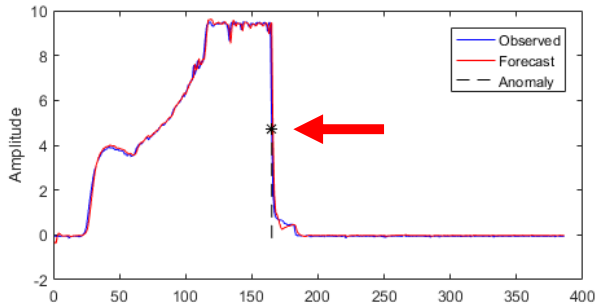
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Anomaly Detection – Simultaneous (t=165)





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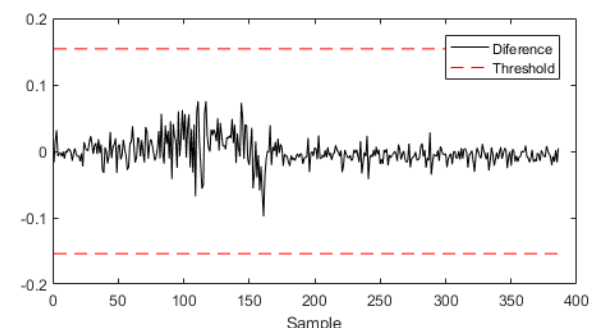
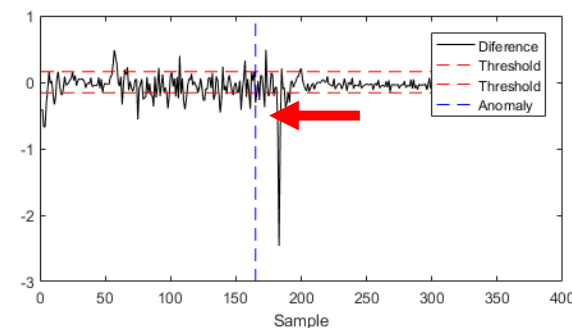
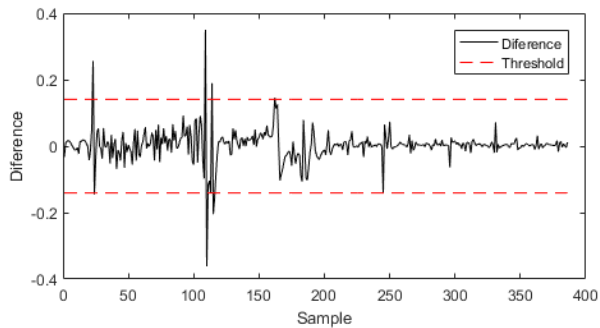
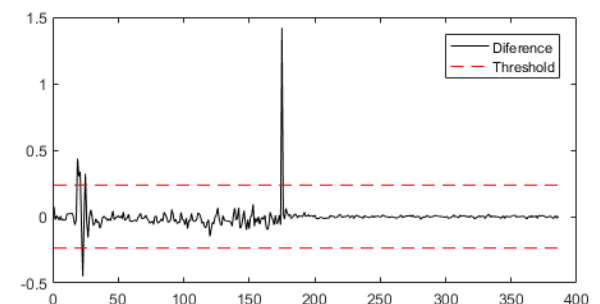
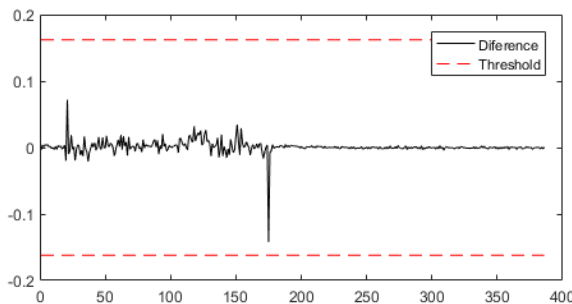
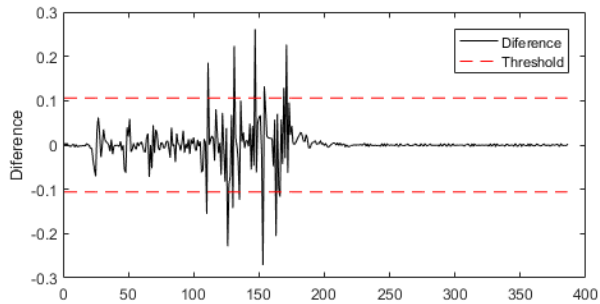
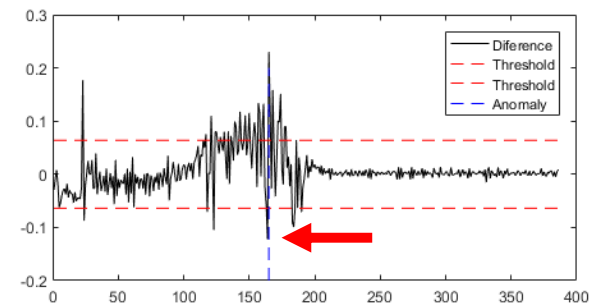
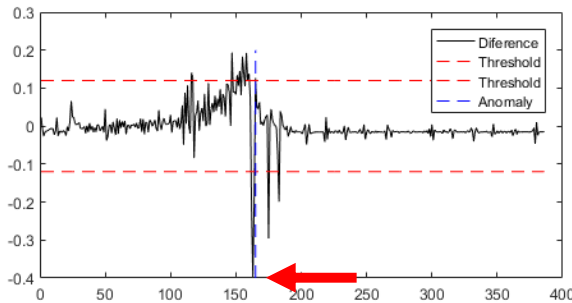
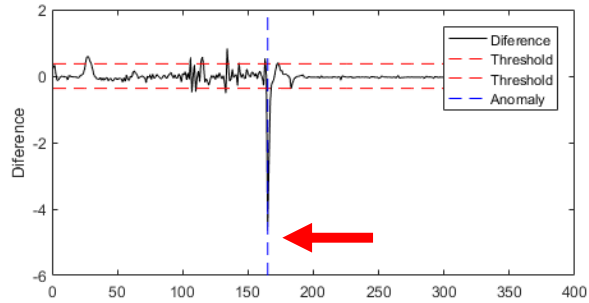
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Anomaly Detection – Simultaneous (t=165)





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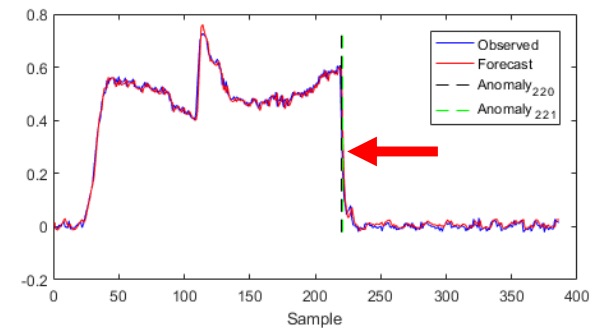
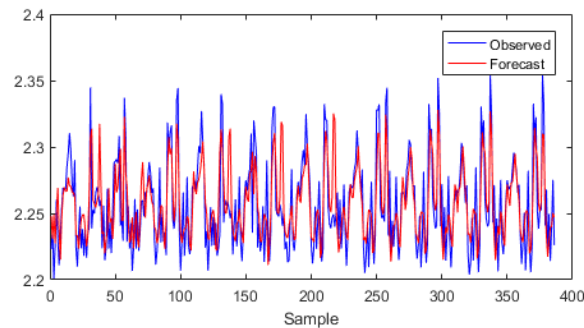
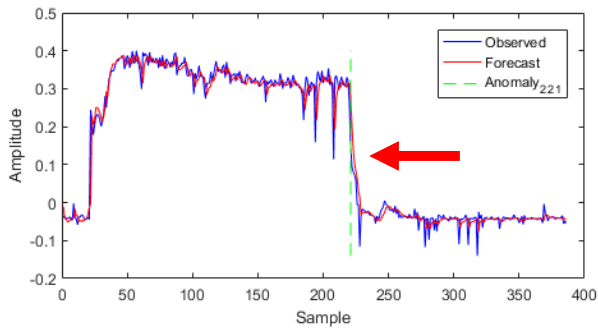
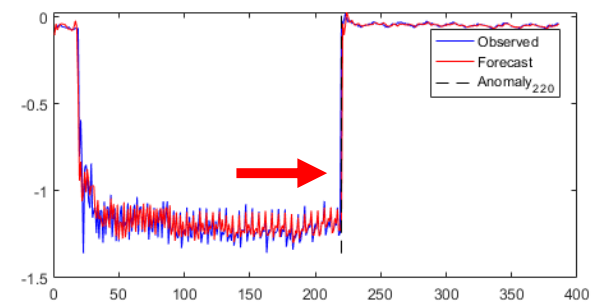
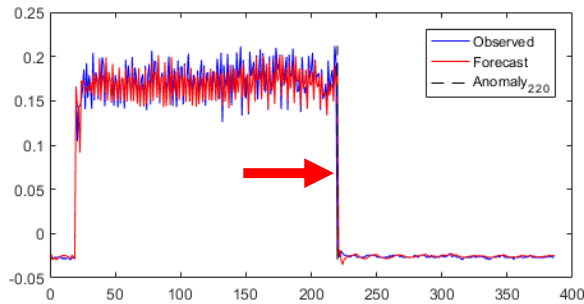
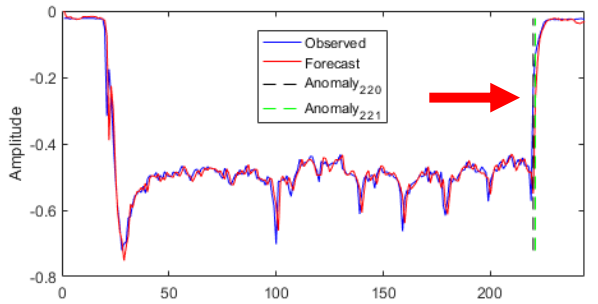
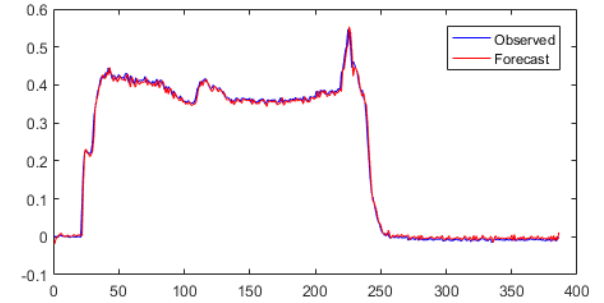
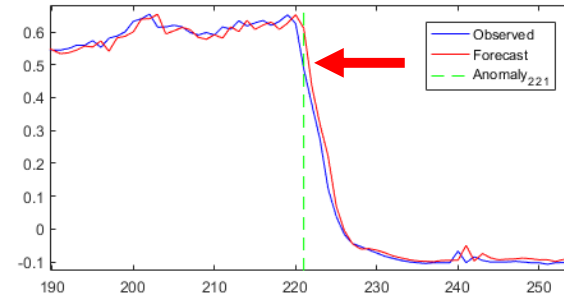
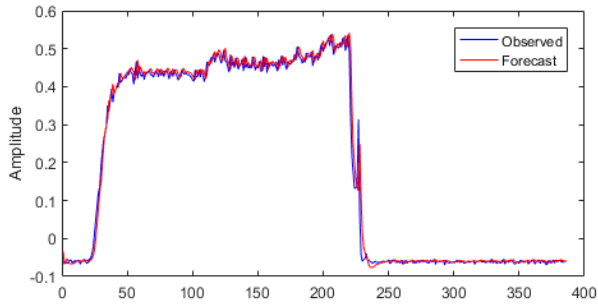
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Anomaly Detection – Simultaneous (Δt)





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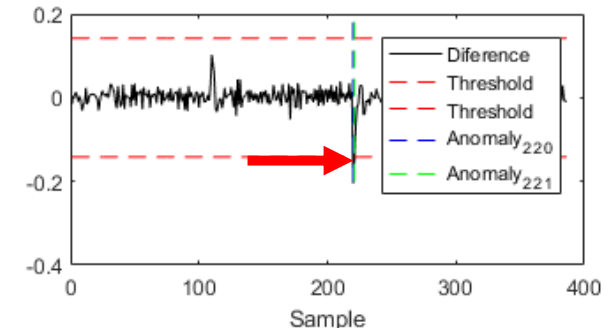
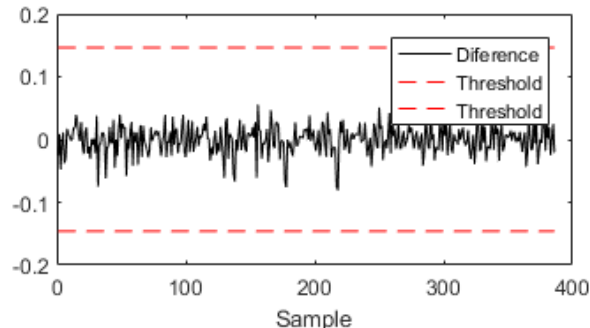
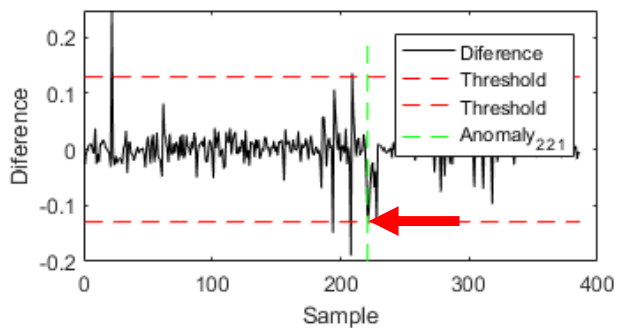
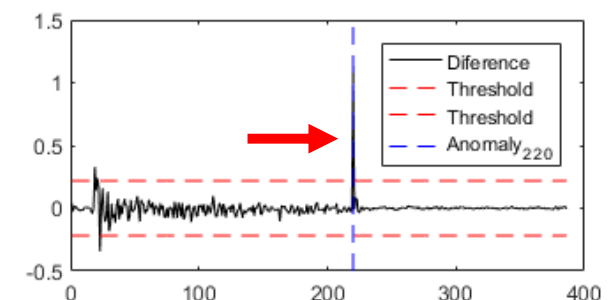
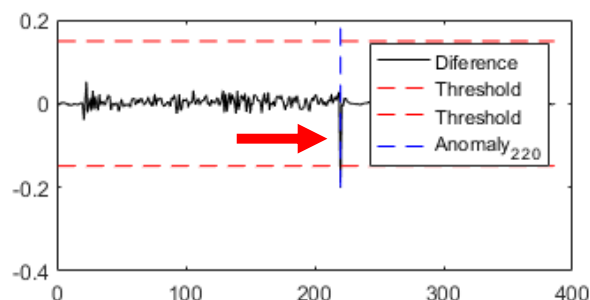
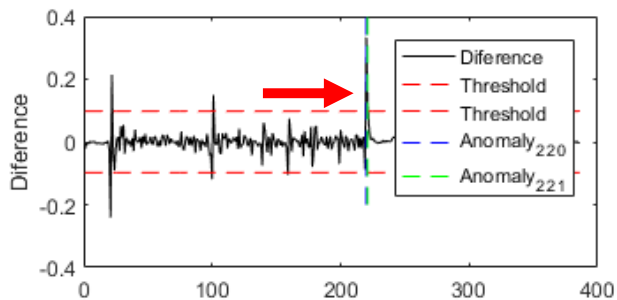
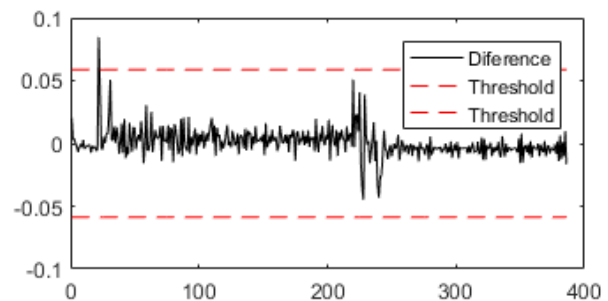
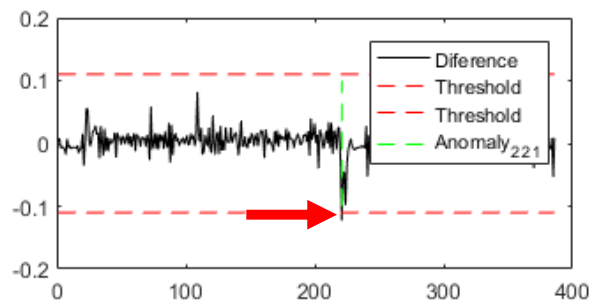
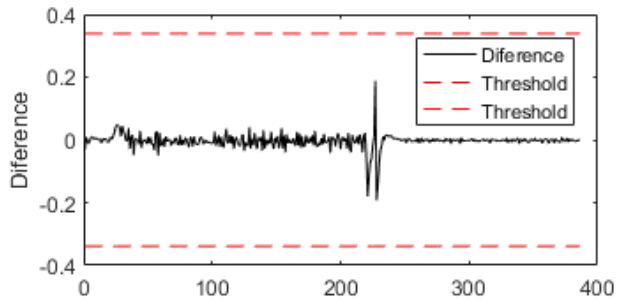
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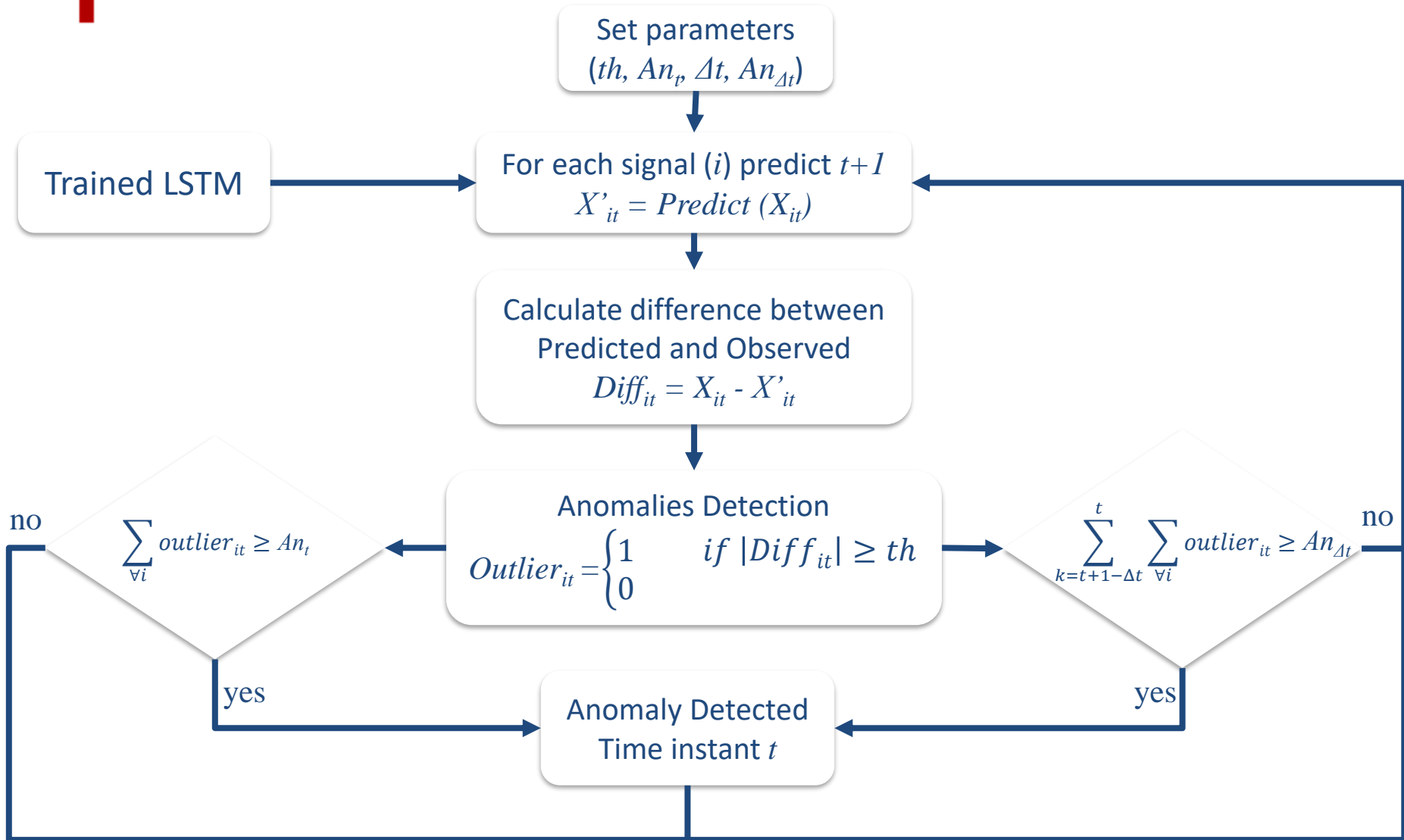


Anomaly Detection – Simultaneous (Δt)





Anomaly Detection – Algorithm





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Results

Simultaneous Anomalies Detection in a Shot (t)

The wider is the band the less anomalies are detected



The more simultaneity is required, the less anomalies are detected.



An _t	K (th = K*STD)							
	1	2	3	4	5	6	7	8
1	190	109	67	40	21	11	8	6
2	96	34	8	3	2	0	0	0
3	49	11	4	0	0	0	0	0
4	21	1	0	0	0	0	0	0
5	4	0	0	0	0	0	0	0
6	1	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0
8	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0

1 simultaneous anomaly in 4 signals for k=2 at given time (t)

*100 shots randomly selected



Results

Simultaneous Anomalies Detection in Time Windows ($\Delta t=5$)

The wider is the band the less anomalies are detected



$An_{\Delta t}$	K (th = K*STD)							
	1	2	3	4	5	6	7	8
1	266	204	153	110	62	33	30	25
2	212	98	50	35	21	5	3	0
3	146	54	25	3	2	0	0	0
4	92	35	8	0	0	0	0	0
5	64	5	0	0	0	0	0	0
6	30	3	0	0	0	0	0	0
7	15	0	0	0	0	0	0	0
8	4	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0

The more simultaneity is required, the less anomalies are detected.



4 simultaneous anomalies in 8 signals for k=1 with $\Delta t=5$

*100 shots randomly selected



Summary

- ❑ LSTM networks can learn the shape of a waveform (one model for signal).
- ❑ LSTM networks can be used for anomaly detection in signals.
- ❑ The specialists have to define the parameters to distinguish the noise from the real anomalies.
- ❑ It is possible to design supervised systems that allow the detection of previous detected/studied anomalies.
- ❑ In the paper ID. 484 you can find other anomaly detection methods.

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